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Velocity Measurements for Turbulent Nonseparated Flow Over Solid Waves

Laser-Doppler velocimetry measurements have been made of nonseparated velocity fields over solid sinusoidal wavy surfaces. Time-averaged velocity and turbulent intensity data are given.

The measurements were conducted over waves on the bottom wall of a rectangular channel with a cross section of twenty four by two inches, the two inch dimension being vertical. Two sets of velocity data were obtained at conditions corresponding to flows where linear and nonlinear shear stress responses are observed. The conditions were wave steepnesses $2a/\lambda$, and channel Reynolds numbers of 0.03125, 6400, and 0.05, 38,800 respectively. The wavelength of the waves was two inches.

The viscous wall region was of particular interest. Sufficient measurements were taken to give an accurate representation of both the streamwise and normal variations of the viscous wall region. The data was Fourier analyzed to determine the extent of nonlinearities, the wavelength averaged flowfields, and the amplitudes and phases of the velocity responses. The physical meaning of the data is interpreted in terms of pressure gradient effects along the wave surfaces. Comparisons of the data with predictions from simple eddy viscosity models are also given.

VELOCITY MEASUREMENTS FOR TURBULENT NONSEPARATED FLOW OVER SOLID WAVES

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DEPARTMENT OF CHEMICAL ENGINEERING
UNIVERSITY OF ILLINOIS
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JUNE, 1986

VELOCITY MEASUREMENTS FOR TURBULENT NONSEPARATED FLOW OVER SOLID WAVES

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for

The Office of Naval Research, Arlington, VA 22217 Contract NO0014-82-K-0324 Project NR 657-728

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Department of Chemical Engineering University of Illinois Urbana, Illinois 61801

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CHAPTER 1

INTRODUCTION

When a turbulent fluid interacts with a wave spatial variations occur in the surface stresses and the velocity field. These variations affect the transport of heat, mass, and momentum at the interfacial boundary. The prediction of the flowfield over a wave is important to the understanding of many natural and industrial processes.

The pressure distribution along a wave surface is of major interest in the problem of wave generation on large bodies of water and in determining when atomization occurs in two phase flows. Shear stress variations play an important role in sediment transport in rivers and in describing interfacial instabilities on thin liquid films. A knowledge of the surface stresses along a wave is also critical in predicting the motion of desert sand dunes and the dissolution patterns found in underwater caverns and melting ice.

Previous investigations in this laboratory by Cook [17], Morrisroe [33], Zilker [48], Thorsness [44], and Abrams [2] have concentrated on the measurement of the pressure and shear stress along a solid sinusoidal wave. Experiments were performed with waves having height to wavelength ratios of $2a_d/\lambda = 0.0125$, 0.03125, 0.05, 0.125, 0.200 and with a range of flowrates so that $0.0058 < \alpha_d \nu/u^* < 0.01$ where α_d is the wavenumber. It was found that for $2a_d/\lambda < 0.033$ and $a_d u^*/\nu < 27$ the shear stress is perturbed linearly with wave amplitude. That is, the responses can be described by single harmonics with characteristic amplitudes and phases. For $a_d u^*/\nu > 27$ shear stress responses are nonlinear since the profiles become distorted and

can no longer be described by single harmonics. Pressure responses were observed to be linear for all nonseparated flows. Separation can occur for waves with $2a_d/\lambda > 0.033$ and the size of the reversed flow region increases with increasing $2a_d/\lambda$ and with increasing $\alpha_d v/u^*$. The reversed flow region with $2a_d/\lambda = 0.05$ waves is very thin and was observed to disappear approximately at the value of $\alpha_d v/u^*$ predicted by the solution of the linear momentum equations.

The above observations are consistent with pressure and shear stress measurements conducted over waves in other laboratories.

Additional pressure measurements were performed by Stanton et.al [43], Motzfeld [34], Larras and Claria [27], Zagustin [47], Kendall [24], Sigal [41], Beebe [8], Cary et al. [12] and Lin et al. [30] and other shear stress data were obtained by Kendall [24], Sigal [41], and Beebe [8].

Considerable progress has been made in the modelling of the pressure and shear stress distributions along waves that have small enough amplitudes to produce a linear response. The analysis for this case is greatly simplified since the momentum equations can be linearized. The critical issue is the specification of the wave induced Reynolds stresses. The best model to date is the eddy viscosity Model D* developed by Thorsness [44] and Abrams [2]. This model uses the mixing length hypothesis of Lyod, Moffat, and Kays [31]. The effects of pressure gradient and relaxation are taken into account by an empirical method that uses one lag constant. Model D* provides a good prediction of the pressure and shear stress over a wide range of dimensionless wavenumbers, $\alpha_{\rm d} v/u^*$.

Measurements of the velocity field over a wave are not as numerous and detailed as those of surface stresses. Motzfeld [34], Kendall [24], Hsu and Kennedy [20], Sigal [41], and Zilker [48] investigated the flowfield above waves under nonseparated flow conditions. Separated flow over waves has been studied by Beebe [8], Zilker [48], Buckles [10], and Kuzan [25]. Only the separated flow studies of Buckles and Kuzan involved sufficient measurements to give an accurate representation of the spatial variation of the flowfield and measured close enough to the wave surface to detect wave-induced perturbations within the lower viscous wall region.

The primary purpose of this thesis is to extend the previous experimental studies by obtaining detailed measurements of the velocity field above waves with nonseparated flows. Of particular interest are measurements within the viscous wall region which can be used as a test of the turbulence models of Thorsness [44] and Abrams [2]. Previous tests of these models have been limited to comparisons with surface stress data. Two sets of velocity measurements were obtained at conditions corresponding to flows where linear and nonlinear shear stress responses are observed. The conditions are $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$, $a_d u^*/v = 12.3$ and $2a_d/\lambda = 0.05$, $\alpha_d v/u^* = 0.00165$, $a_d v/v = 95.2$ respectively.

The measurements were made in a water channel with a rectangular cross section of 2.0 in. × 24.0 in. The overall channel length was about thirty-five feet, with the last five feet at the downstream end being the test section. The bottom surface of this section was removable and had wave profiles of wavelength two inches machined

across it. Tests were conducted over the eighth wave in a series of ten waves. The velocity data consisted of time-averaged and turbulent intensity profiles in the streamwise direction.

Detailed measurements of the viscous wall region were made with the laser-Doppler velocimeter (LDV) techniques developed by Buckles [10]. The technique of obtaining velocities with LDV has several advantages over the classical hot film and hot wire methods which were used by Kendall [24], Sigal [41], Beebe [8], and Zilker [48]. A LDV requires no calibration, does not disturb the flow with a physical probe, can detect momentary flow reversals, and can operate in highly turbulent flows. The key feature of the LDV used in this study is an optics system containing two beam expanders. The beam expanders provided a small enough measurement volume to perform velocity measurements as close to the wave surface as y-plus, $y_{d}u^{*}/v$, equal to two and ten at the dimensionless wavenumbers, $\alpha_d v/u^*$, of 0.008 and 0.00165 respectively. Fifteen to twenty data points were taken vertically within the viscous wall region. Good spatial resolution in the horizontal direction was achieved by conducting velocity measurements every tenth of a wavelength.

The velocity measurements were obtained over finite amplitude waves where the application of linear theory is uncertain. Therefore a nonlinear computer code was developed to predict the flowfield above finite amplitude waves. The code solves the nonlinear Reynolds-averaged Navier-Stokes equations using spectral methods in the flow direction and finite differences in the normal

direction. The code is a modification of the boundary layer program of McLean [32] to the flow geometry of waves on the lower wall of a rectangular channel. Previous linear and nonlinear wavy surface codes developed in this laboratory [1, 2, 45] have been limited to the prediction of boundary layer flows.

A comparison of the velocity measurements with linear and non-linear calculations using the turbulence models of Thorsness [44] and Abrams [2] provides considerable physical insight into the nature of nonseparated flow over a wave surface.

CHAPTER 2

LITERATURE REVIEW

This chapter reviews the literature on velocity measurements over solid and rigid two-dimensional sinusoidal wavy surfaces. The discussion, which is facilitated by using the flow regime map of Abrams, Frederick and Hanratty [3], is presented in the chronological order in which the measurements were made.

The flow regime map is shown in Figure 2.1. The vertical axis, $2a_d/\lambda$, is the wave steepness and the horizontal axis is the wavenumber, $2\pi/\lambda$, made dimensionless with respect to wall parameters. The wall parameters are the friction velocity, $u^* = \sqrt{\tau_w/\rho}$, and the kinematic viscosity, ν , of the fluid. The observed behavior for flow over solid sinusoidal waves can be divided into three regions: a region where the flows are separated, a nonseparated region where the shear stress response is linear, and a nonseparated region where the shear stress response is nonlinear. Velocity measurements have been obtained in all three regions.

The first velocity measurements over a wavy surface were conducted by Motzfeld [34]. A pitot tube was used in a low-speed wind tunnel to obtain mean streamwise velocity profiles above two sinusoidal waveforms containing six waves with λ = 300 mm and values of $2a_d/\lambda$ equal to 0.05 and 0.100 respectively. Profiles were taken at several x_d/λ positions and strong deviations from the flat plate profile were observed. The major limitation of this study was that measurements close to the wave surface could not be obtained with the pitot tube technique. From Figure 2.1 it is seen that both sets of measurements were obtained for nonlinear nonseparated flows.

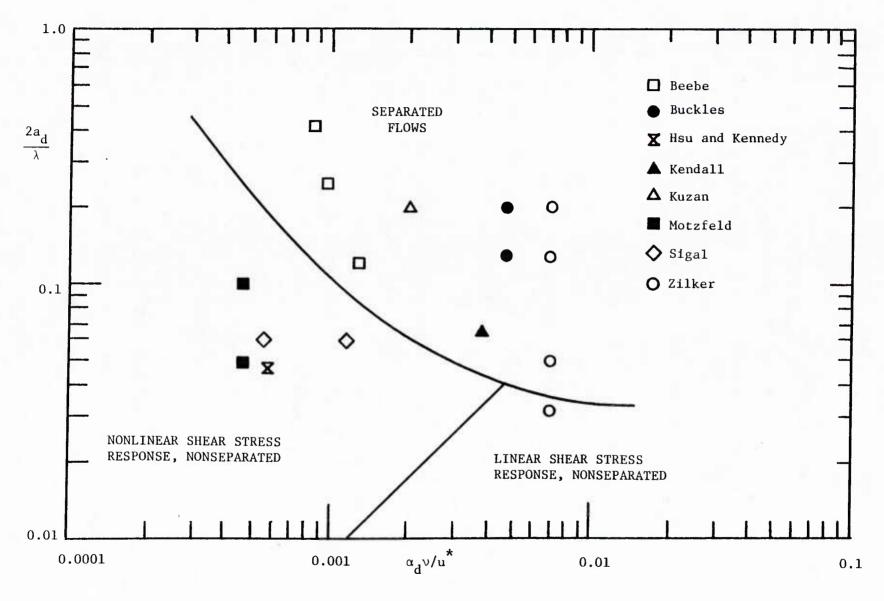


Figure 2.1 Flow Regime Map for Two-Dimensional Solid Sinusoidal Waves

Kendall [24] used hot wire probes to measure the velocity field above a smooth wavy neoprene rubber sheet that comprised a portion of the bottom floor of a low turbulence wind tunnel. The sheet was mechanically deformed into twelve sinusoidal waves which could progress upwind or downwind at a controlled speed. The wavelength of the waves was four inches and the steepness, $2a_{\mbox{\scriptsize d}}/\lambda,$ was equal to 0.0625. Only one set of average velocity measurements was reported at zero wave speed. Two streamwise velocity profiles were obtained at the limits of excursion of the cyclic velocity perturbation about the wavelength averaged flowfield. The maximum and minimum perturbations occurred at $x_d/\lambda = 0.96$ and $x_d/\lambda = 0.35$ respectively. Figure 2.1 shows that these data are located in the separated flow regime. However, no reversed flows were observed even at the closestmeasurement point of $y_d u^*/v = 12.4$. This is consistent with the flow visualization experiments of Zilker [48] which indicate that the separated region is extremely thin for the wave steepness and flowrate used by Kendall.

Hsu and Kennedy [20] studied turbulent air flow in wavy pipes. The wavy pipes had an average diameter of 0.408 ft. and were constructed by forming fiberglass onto wooden mandrels. Hot wire probes were used to investigate the flowfield over waves with steepnesses, $2a_{\rm d}/\lambda$, equal to 0.0222 and 0.0444 and wavelengths of 1.67 ft. and 0.83 ft. respectively. A constant Reynolds number of 1.13 \times 10 based on the average pipe diameter was maintained in the experiments.

Longitudinal components of the mean and turbulent velocities were measured with a single-wire probe. Tangential and radial

components, as well as Reynolds stresses,were obtained with a cross-wire probe. Profiles were taken at 1/8th wavelength increments in the flow direction. Each profile consisted of only about ten velocity measurements. The closest measurement to the wavy surface was at approximately y-plus, y_d^* , equal to 120. It was observed that the mean velocity profiles at positions symmetrical about the location of minimum (or maximum) diameter are nearly identical. Turbulent intensities remained constant along the pipe within a central core covering about sixty percent of the radius. The data of Hsu and Kennedy is located in the nonlinear shear stress response region of Figure 2.1.

Sigal [41] made velocity measurements over two geometrically similar wavy surfaces in a turbulent boundary layer of a low-speed wind tunnel. The waves were constructed of smooth aluminum sheeting deformed to a sinusoidal shape. The two wavy sheets each contained five waves of steepness, $2a_d/\lambda$, equal to 0.055 and had wavelengths of six and twelve inches respectively. Measurements of the average and fluctuating velocities parallel to the wave surface were obtained with a single sensor hot wire probe. In addition, average and fluctuating velocities in the streamwise and normal directions as well as Reynolds stresses were obtained with an x-array hot wire probe. The closest measurements to the wave surface were at about $y_d u^*/\nu$ equal to ten.

Profiles were taken at only four positions along each wave surface above the locations where

- 1) C' is a minimum,
- 2) $\textbf{C}^{\, \boldsymbol{\prime}}_{\, \boldsymbol{p}}$ equals zero and the pressure gradient is negative,
- C' is a maximum,

and 4) C_p' equals zero and the pressure gradient is positive, where C_p' is the local wall pressure coefficient. The four locations correspond to x_d/λ positions of approximately 0.0, 0.25, 0.50, and 0.75 respectively. Figure 2.1 shows the location of Sigal's data in the nonlinear shear stress response region of the flow regime map.

Velocity profiles at the crests and troughs showed strong positive and negative perturbations respectively about the flat plate profile. These disturbances extended to several thousand y-plus units, $y_d^*u^{\prime}/v$, above the wave surface. In contrast, the profiles corresponding to C_p^{\prime} equal to zero showed smaller perturbations that became negligible at about y-plus equal to 300. For both pairs of profiles the positive and negative deviations are approximately equal in magnitude. The wavelength average profiles are in close agreement with the flat plate profile. Strong streamwise variations in the turbulent intensities were also noted.

Beebe [8] investigated large amplitude wavy surfaces as a particular form of surface roughness. Waves with λ equal to 4.2 inches and $2a_d/\lambda$ equal to 0.119, 0.238, and 0.405 were constructed out of styrofoam and covered with felt. Average streamwise velocity profiles were taken over the crests with a pitot tube. Turbulent intensities and Reynolds stresses were also measured above the crests with a two-wire probe. All measurments were performed at conditions within the separated flow region of Figure 2.1 but no velocities within the

the separated bubble could be obtained with the pitot tube and hot wire techniques.

The first detailed set of velocity measurements in this laboratory were obtained by Zilker [48] over smooth Plexiglas waves with $2a_d/\lambda$ equal to 0.0125, 0.03125, 0.05, 0.125 and 0.200. Each wave test surface contained ten waves of wavelength two inches and was part of the bottom wall of a rectangular channel. A split film sensor was used to obtain average and fluctuating streamwise velocities. Normal velocities, normal fluctuations and Reynolds stresses were also measured but are subject to a degree of uncertainty since the normal velocities had unrealistic values at the center of the channel. Profiles were taken at one-tenth wavelength increments in the streamwise direction. All measurements were made at a Reynolds number of 8000 based on the half channel height.

Figure 2.1 shows that the above flowrate places the two waves of smallest amplitude within the linear shear stress response region. The wave with $2a_d/\lambda$ equal to 0.0125 did not perturb the flowfield enough to differentiate profiles at any x_d/λ position from flat channel results. Average velocity profile data obtained over the 0.03125 wave surface began to reflect the presence of the sinusoidal boundary.

Flow visualization experiments indicated that reversed flow regions existed for the waves with $2a_d/\lambda$ equal to 0.05, 0.125, and 0.200. The separated region for the 0.05 wave was very thin and thought to be below the lowest velocity measurement at approximately y_d^*/ν equal to ten. This is confirmed by recent LDV measurements at the same conditions by Kuzan [] which show that the time

averaged velocity field does not reverse as close to the wave surface as $y_d^*u^*/v$ equal to two. The reversed flow portions of the flowfields over the 0.125 and 0.200 waves were much larger and could not be studied since split film sensors do not distinguish between positive and negative velocities.

Buckles [10] conducted the first detailed study of separated flow over a wavy surface. The measurements of Zilker were extended to include the reversed flow regions above waves with $2a_{d}/\lambda$ = 0.125 and 0.200. A LDV was used to detect negative velocities. Average and fluctuating velocities were obtained at a Reynolds number of 12,000 based on the half channel height. Profiles were taken at streamwise increments no greater than one-tenth of a wavelength beginning as close to the wave surface as y-plus, $y_d u^*/v$, equal to 3.5. The size, shape, and extent of the time-averaged separation bubble was determined for both waves. The thickest point of the separated region over the 0.200 wave was found to be of the order of the wave amplitude. The separation bubble above the 0.125 wave is about one-third the thickness. It was noted that there is no position above the wave surfaces where the flow is separated at all times. Similarities between separated flow over waves and a classical shear layer were also observed.

Kuzan [25] extended Buckles work by studying the effect of flowrate on the separation bubble. LDV measurements were taken above a wave with $2a_{\rm d}/\lambda$ equal to 0.200 at a Reynolds number of 30,000. The separated region was observed to shrink uniformily as the Reynolds number increases. That is, the separation bubble was inclined in the trough at the same angle for the two flowrates tested.

CHAPTER 3

THEORY

This chapter is in three sections. Section I presents a nonlinear analysis for turbulent flow over finite amplitude waves in a rectangular channel. In Section III the turbulent stress models used in the above theory are described. Section III gives a check of the nonlinear analysis by comparing surface stress results for very small amplitude waves with the linear theory of Thorsness [44] and Abrams [2] and with literature data. A comparison of the nonlinear analysis with the LDV measurements over finite amplitude waves is given in Chapter 6.

I. Nonlinear Channel Analysis

The linear theory of Thorsness [44] and Abrams [2] is strictly valid only for boundary layer flows with waves of infinitesimal amplitude. This section discusses a nonlinear analysis and a computational method for extending the calculations of Thorsness and Abrams to the case of finite amplitude waves on the bottom wall of a rectangular channel. The method is a modification of the boundary layer analysis of McLean [32].

A. Governing Equations

Prediction of the turbulent flowfield over waves of finite amplitude was achieved by solving the nonlinear Reynolds-averaged Navier-Stokes equations. These momentum equations are shown below for two-dimensional steady-state incompressible flow in Cartesian coordinates:

$$\mathbf{u}_{\mathbf{d}} \frac{\partial \mathbf{u}_{\mathbf{d}}}{\partial \mathbf{x}_{\mathbf{d}}} + \mathbf{v}_{\mathbf{d}} \frac{\partial \mathbf{u}_{\mathbf{d}}}{\partial \mathbf{y}_{\mathbf{d}}} = -\frac{1}{\rho} \frac{\partial \mathbf{p}_{\mathbf{d}}}{\partial \mathbf{x}_{\mathbf{d}}} + \nu \left[\frac{\partial^{2} \mathbf{u}_{\mathbf{d}}}{\partial \mathbf{x}_{\mathbf{d}}^{2}} + \frac{\partial^{2} \mathbf{u}_{\mathbf{d}}}{\partial \mathbf{y}_{\mathbf{d}}^{2}} \right]$$

$$+\frac{\partial}{\partial \mathbf{x_d}}\left(-\overline{\mathbf{u_d^{'}u_d^{'}}}\right) + \frac{\partial}{\partial \mathbf{y_d}}\left(-\overline{\mathbf{u_d^{'}v_d^{'}}}\right) \tag{3.1}$$

$$\mathbf{u}_{\mathbf{d}} \frac{\partial \mathbf{v}_{\mathbf{d}}}{\partial \mathbf{x}_{\mathbf{d}}} + \mathbf{v}_{\mathbf{d}} \frac{\partial \mathbf{v}_{\mathbf{d}}}{\partial \mathbf{y}_{\mathbf{d}}} = -\frac{1}{\rho} \frac{\partial \mathbf{p}_{\mathbf{d}}}{\partial \mathbf{y}_{\mathbf{d}}} + \nu \left[\frac{\partial^{2} \mathbf{v}_{\mathbf{d}}}{\partial \mathbf{x}_{\mathbf{d}}^{2}} + \frac{\partial^{2} \mathbf{v}_{\mathbf{d}}}{\partial \mathbf{y}_{\mathbf{d}}^{2}} \right]$$

$$+ \frac{\partial}{\partial \mathbf{x_d}} \left(- \overline{\mathbf{u_d' v_d'}} \right) + \frac{\partial}{\partial \mathbf{y_d}} \left(- \overline{\mathbf{v_d' v_d'}} \right)$$
 (3.2)

where $\mathbf{u_d}$, $\mathbf{u_d}'$ and $\mathbf{v_d}$, $\mathbf{v_d}'$ are time-averaged and fluctuating velocities in the $\mathbf{x_d}$ and $\mathbf{y_d}$ directions respectively. The subscript "d" refers to dimensional variables.

The wave surface is the sinusoid

$$y_{d} = a_{d} \cos (\alpha_{d} x_{d}) , \qquad (3.3)$$

where a_d is the wave amplitude, $\alpha_d=2\pi/\lambda$ is the wavenumber and λ is the wavelength.

The boundary conditions at the wave surface and the top wall of the channel are no slip and may be written as

$$u_{d}(x_{d}, a_{d} \cos \alpha_{d} x_{d}) = v_{d}(x_{d}, a_{d} \cos \alpha_{d} x_{d}) = 0$$
 (3.4)

and

$$u_d(x_d, y_T) = v_d(x_d, y_T) = 0.$$
 (3.5)

where \mathbf{y}_{T} is the coordinate of the top wall of the channel. In the horizontal direction the boundary conditions are periodic and given by

$$u_d(0, y_d) = u_d(\lambda, y_d),$$
 (3.6)

and

$$v_d(0, y_d) = v_d(\lambda, y_d).$$
 (3.7)

B. Numerical Solution

It is desirable to perform computations on a rectangular region. This was accomplished by a conformal mapping of the physical domain $0 \leq \mathbf{x}_d \leq \lambda; \ \mathbf{a}_d \cos{(\alpha_d \mathbf{x}_d)} \leq \mathbf{y}_d \leq \mathbf{y}_T \ \text{to the rectangular region}$ $0 \leq \epsilon \leq 2\pi; \ 0 \leq \mathbf{n} \leq \mathbf{n}_T, \ \text{where } \mathbf{n}_T \ \text{is the transformed coordinate of}$ the top wall of the channel. The map is given by the following orthogonal transformation developed by Caponi et al. [11]:

$$\alpha_{\mathbf{d}}^{\mathbf{x}}_{\mathbf{d}} = \varepsilon + \sum_{i=1}^{\infty} \frac{b_{i}}{i} \sin i\varepsilon \left(\frac{\cosh i (\eta_{T} - \eta)}{\sinh i \eta_{T}} \right), \qquad (3.8)$$

$$\alpha_{d} y_{d} = \eta + b_{o} - \sum_{i=1}^{\infty} \frac{b_{i}}{i} \cos i \varepsilon \left(\frac{\sinh i (\eta_{T} - \eta)}{\sinh i \eta_{T}} \right).$$
 (3.9)

The coefficients b_i can be chosen to approximate any given periodic and symmetrical surface. Eleven terms were found to be sufficient to fit the wave surface $y_d = a_d \cos \alpha_d x_d$ for $2a_d/\lambda \le 0.05$. Figure 3.1 shows the physical and transformed regions. Equations (3.8) and (3.9) can easily be modified to accommodate asymmetric surfaces [32].

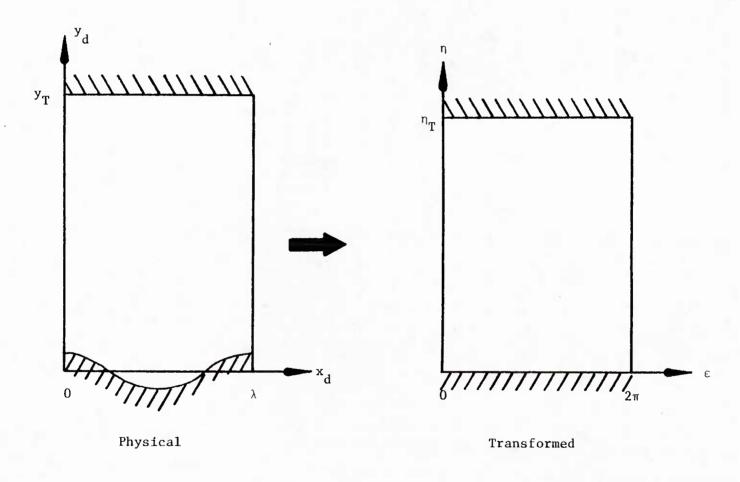


Figure 3.1 Physical and Transformed Regions

The momentum equations (3.1) and (3.2) were solved in streamfunction-vorticity form. The streamfunction, $\psi_{\rm d}$, and the vorticity, $\omega_{\rm d}$, are defined by,

$$\omega_{d} = \frac{\partial v_{d}}{\partial x_{d}} - \frac{\partial u_{d}}{\partial y_{d}}, \qquad (3.10)$$

$$\mathbf{u}_{\mathbf{d}} = \frac{\partial \psi_{\mathbf{d}}}{\partial \mathbf{y}_{\mathbf{d}}} , \qquad (3.11)$$

and

$$v_{d} = -\frac{\partial \psi_{d}}{\partial x_{d}}. \qquad (3.12)$$

McLean [32] has shown that in the transformed coordinates, (ϵ,η) , the equations of motion become

$$\omega_{d} = -J \left[\frac{\partial^{2} \psi_{d}}{\partial \varepsilon^{2}} + \frac{\partial^{2} \psi_{d}}{\partial \eta^{2}} \right] , \qquad (3.13)$$

and

$$\frac{\partial \omega_{\mathbf{d}}}{\partial \varepsilon} \frac{\partial \psi_{\mathbf{d}}}{\partial \eta} - \frac{\partial \omega_{\mathbf{d}}}{\partial \eta} \frac{\partial \psi_{\mathbf{d}}}{\partial \varepsilon} = \left(\frac{\partial^2}{\partial \varepsilon^2} + \frac{\partial^2}{\partial \eta^2} \right) \left[(v + v_{\mathbf{t}}) \omega_{\mathbf{d}} \right]$$

$$+\frac{2}{J}\left[\frac{\partial^{2}\psi_{d}}{\partial x_{d}^{2}}\frac{\partial^{2}v_{t}}{\partial y_{d}^{2}}-2\frac{\partial^{2}\psi_{d}}{\partial x_{d}\partial y_{d}}\frac{\partial^{2}v_{t}}{\partial x_{d}\partial y_{d}}+\frac{\partial^{2}\psi_{d}}{\partial y_{d}^{2}}\frac{\partial^{2}v_{t}}{\partial x_{d}^{2}}\right],$$
(3.14)

where the Jacobian, J, is defined by

$$J = \left(\frac{\partial^2 x_d}{\partial \varepsilon^2} + \frac{\partial^2 x_d}{\partial \eta^2}\right)^{-1} . \tag{3.15}$$

In the derivation of equation (3.14) the turbulent stress terms in equations (3.1) and (3.2) have been modeled with an isotropic eddy viscosity according to the following constitutive equations:

$$-\overline{\mathbf{u}_{\mathbf{d}}^{\dagger}\mathbf{u}_{\mathbf{d}}^{\dagger}} = \frac{1}{\rho} \quad \mathbf{R}_{\mathbf{x}_{\mathbf{d}}^{\mathbf{X}}\mathbf{d}} = \mathbf{v}_{\mathbf{t}} \quad 2\mathbf{S}_{\mathbf{x}_{\mathbf{d}}^{\mathbf{X}}\mathbf{d}} = \mathbf{v}_{\mathbf{t}} \quad 2\frac{\partial \mathbf{u}_{\mathbf{d}}}{\partial \mathbf{x}_{\mathbf{d}}}, \tag{3.16}$$

$$-\overline{\mathbf{v}_{\mathbf{d}}^{\dagger}\mathbf{v}_{\mathbf{d}}^{\dagger}} = \frac{1}{\rho} \quad \mathbf{R}_{\mathbf{y}_{\mathbf{d}}}\mathbf{y}_{\mathbf{d}} = \mathbf{v}_{\mathbf{t}} \quad 2\mathbf{S}_{\mathbf{y}_{\mathbf{d}}}\mathbf{y}_{\mathbf{d}} = \mathbf{v}_{\mathbf{t}} \quad 2\frac{\partial \mathbf{v}_{\mathbf{d}}}{\partial \mathbf{y}_{\mathbf{d}}}, \qquad (3.17)$$

and

$$-\frac{\overrightarrow{u_d'} \overrightarrow{v_d'}}{\overrightarrow{v_d'}} = R_{\overrightarrow{x_d}} \overrightarrow{y_d} = v_t \quad 2 \quad S_{\overrightarrow{x_d}} \overrightarrow{y_d} = v_t \quad \left(\frac{\partial u_d}{\partial y_d} + \frac{\partial v_d}{\partial x_d}\right). \tag{3.18}$$

Models for the eddy viscosity are described in Section II.

The no slip boundary conditions in the transformed region are

$$\frac{\partial \psi_{\mathbf{d}}}{\partial n} (\varepsilon, 0) = \frac{\partial \psi_{\mathbf{d}}}{\partial \varepsilon} (\varepsilon, 0) = 0 \tag{3.19}$$

and

$$\frac{\partial \psi_{\mathbf{d}}}{\partial \eta} (\varepsilon, \eta_{\mathbf{T}}) = \frac{\partial \psi_{\mathbf{d}}}{\partial \varepsilon} (\varepsilon, \eta_{\mathbf{T}}) = 0$$
 (3.20)

at the top and bottom walls respectively. In the horizontal direction the periodic boundary conditions become

$$\psi_{d}(0, \eta) = \psi_{d}(2\pi, \eta)$$
 (3.21)

and

$$\omega_{d}(0, \eta) = \omega_{d}(2\pi, \eta)$$
 (3.22)

In order to resolve the steep velocity gradients near the two surfaces, the vertical coordinates were stretched according to the following equation:

$$\eta = \eta_{T} \left[\frac{\tan^{-1}[-b(1-2z)] - \tan^{-1}[-b]}{2 \tan^{-1}[+b]} \right]$$
 (3.23)

where z is the unstretched coordinate and b is a stretching parameter. Figure 3.2 shows an example of the stretched coordinate system in the physical domain for $2a_d/\lambda = 0.05$ and b = 5 with a 9 × 81 mesh. Details of the coordinate system in the near wall region, which is not visible in this figure due to the fine spacing, is discussed below.

Table 3.1 shows the stretching parameters and the number of vertical points used for the computational studies of the two wave steepnesses investigated. These parameters provide the necessary grid spacing to resolve accurately the flowfield in the vertical direction. Resolution was verified by reducing the number of grid points from 151 to 81 for the case of $2a_{\rm d}/\lambda = 0.05$ and ${\rm Re}_{\rm b} = 38,800$. Predictions of surface stresses and velocities differed by only about one percent.

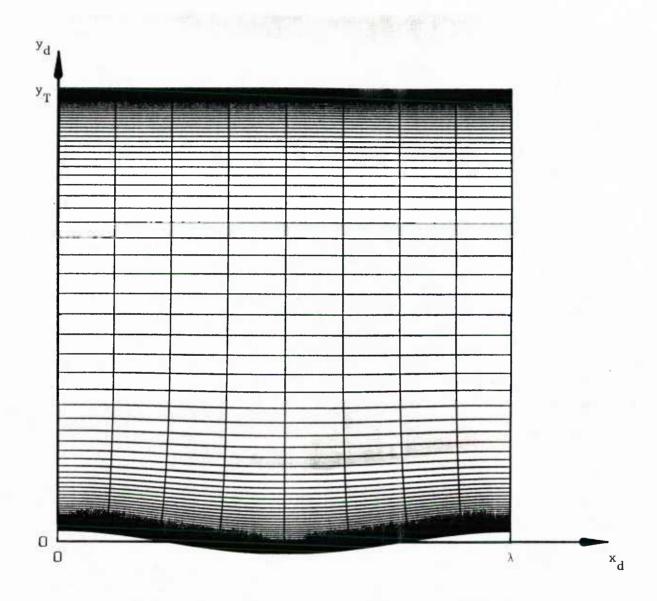


Figure 3.2 Stretched Coordinate System in Physical Domain, $2a_d/\lambda$ = 0.05, b = 5, 9 × 81 Mesh

# Points in # Points in Viscous Viscous Sublayer Wall Region	3 17	4 24
# Vertical Points	81	151
Stretching Parameter	S	15
Flow	$2a_d/\lambda = 0.03125$ $Re_b = 6400$	$2a_d/\lambda = 0.05$ Re. = 38,800

Table 3.1 Numerical Parameters and Vertical Resolution

The resolution is illustrated in Figures 3.3 and 3.4 which show the discrete velocity profiles obtained using the parameters in Table 3.1 in a flat channel with Re = 6400 and 38,800 respectively. These flat channel profiles represent the average vertical resolution found over one wavelength. The resolution is slightly higher at the crests and slightly lower over the troughs due to the transformed coordinates and the change in cross sectional area. Note that there are 3,4 grid points in the viscous sublayer $(y_d u^*/v < 5)$ and 17,24 grid points in the viscous wall region $(y_d u^*/v < 40)$ for Re = 6400 and 38,800 respectively. These numbers are also included in Table 3.1.

Numerically, the vertical derivatives are evaluated by finite differences. The first, second and third derivatives are approximated as

$$\frac{\partial \phi}{\partial \eta} \approx \frac{\phi_{n,m+1} - \phi_{n,m-1}}{2\Delta z} \left(\frac{\partial z}{\partial \eta} \right)$$
 (3.24)

$$\frac{\partial^{2} \phi}{\partial \eta^{2}} \approx \frac{\phi_{n,m+1} - 2\phi_{n,m} - \phi_{n,m-1}}{(\Delta z)^{2}} \left(\frac{\partial z}{\partial \eta}\right)^{2}$$

$$+\frac{\phi_{n,m+1}-\phi_{n,m-1}}{2\Delta z}\left(\frac{\partial^2 z}{\partial \eta^2}\right)$$
 (3.25)

and

$$\frac{\partial^{3} \phi}{\partial \eta^{3}} \approx \frac{\phi_{n,m+2} - 2\phi_{n,m+1} + 2\phi_{n,m-1} - \phi_{n,m-2}}{(\Delta z)^{3}} \frac{1}{2} \left(\frac{\partial z}{\partial \eta}\right)^{3}$$

$$+\frac{\phi_{n,m+1}-2\phi_{n,m}+\phi_{n,m-1}}{(\Delta z)^{2}}3\left(\frac{\partial z}{\partial n}\right)\left(\frac{\partial^{2} z}{\partial n^{2}}\right)+\frac{\phi_{n,m+1}-\phi_{n,m-1}}{2\Delta z}\left(\frac{\partial^{3} z}{\partial n^{3}}\right)$$
(3.26)

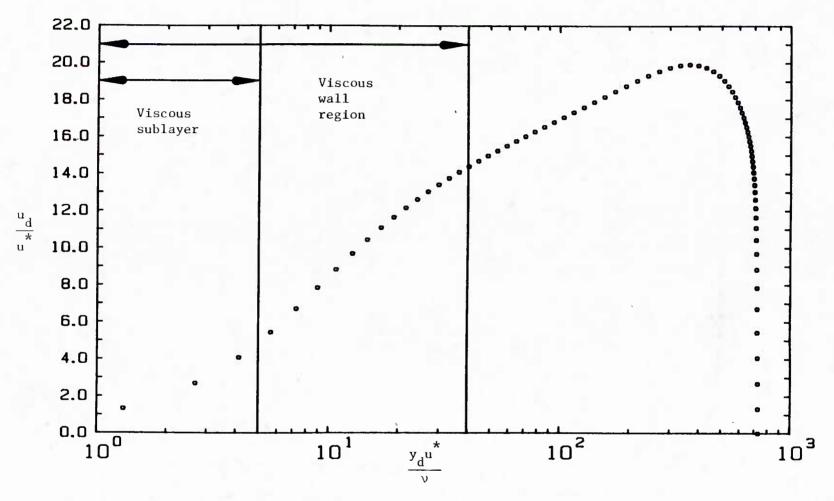


Figure 3.3 Discrete Flat Channel Profile, Re_b = 6400, b = 5, 81 Vertical Points

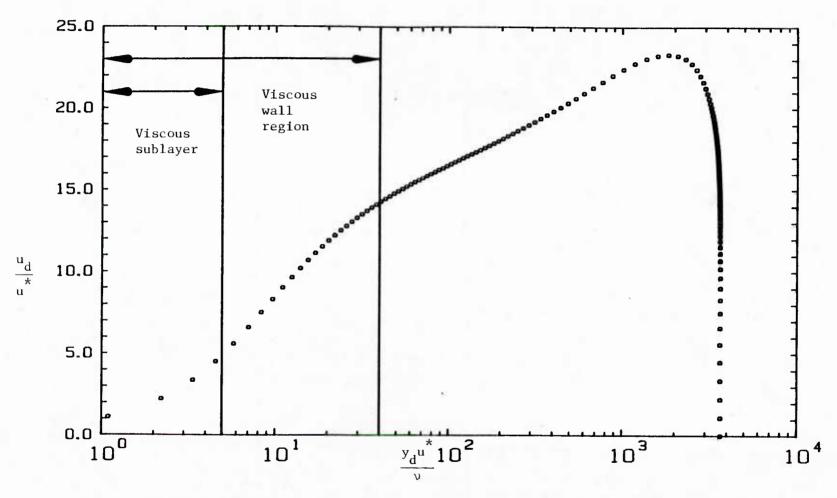


Figure 3.4 Discrete Flat Channel Profile, $Re_b = 38,800$, b = 15, 151 Vertical Points

where $\phi_{n,m}$ refers to either the streamfunction ψ_d or the vorticity ω_d . The derivatives of z arise because of the coordinate stretching.

The horizontal derivatives are evaluated by spectral methods. Since the flowfield is assumed to be periodic, the streamfunction and vorticity may be represented by the following discrete Fourier series at constant η :

$$\phi(\varepsilon_{j}) \Big|_{\eta} = \sum_{k=-N/2}^{N/2-1} \gamma_{k} e^{ik\varepsilon_{j}}$$
(3.27)

where N+1 is the number of points in the horizontal direction (crest to crest), $\epsilon_j = 2\pi j/N$, and $0 \le j \le N$. The Fourier coefficients, γ_k , are calculated by a fast Fourier transform routine. The horizontal derivatives are given by.

$$\frac{\partial \phi(\varepsilon_{j})}{\partial \varepsilon} \Big|_{p} = \sum_{k=-N/2}^{N/2-1} ik \gamma_{k} e^{ik\varepsilon_{j}}$$
(3.28)

and

$$\frac{\partial^{2} \phi(\varepsilon_{j})}{\partial \varepsilon^{2}} \Big|_{\eta} \sum_{k=-N/2}^{N/2-1} (-k^{2}) \gamma_{k} e^{ik\varepsilon_{j}}$$
(3.39)

Good spatial resolution in the horizontal direction was obtained with nine points (crest to crest) and four Fourier harmonics. The nine spectral points are equivalent to approximately 18 finite difference points. A rough rule of thumb given by Orszag [35] is that a finite difference method requires a factor of 2 more resolution in each spatial direction than a spectral method to achieve 5-10

percent accuracy. Tests with 17 points and 8 harmonics gave the same results for waves with $2a_d/\lambda=0.05$.

The discretised equations were solved by Newton's method.

Since the Jacobian matrix has substantial zero structure, a sparse matrix solver developed by Stadtherr [42] was used to lower storage requirements. A summary of the approximate storage requirements and run times on a VAX 11/780 is given in Table 3.2. The numbers in parentheses refer to values obtained by treating the Jacobian matrix as full. It should be noted that although the sparse matrix solver substantially lowered the storage requirements, no reduction in run times was observed. All runs were performed in double precision.

Cartesian streamwise velocities were calculated from results in transformed coordinates by use of the following chain rule equation:

$$u_{d}(x_{d}, y_{d}) = \frac{\partial \psi_{d}}{\partial y_{d}} = \frac{\partial \psi_{d}}{\partial \eta} \frac{\partial \eta}{\partial y_{d}} + \frac{\partial \psi_{d}}{\partial \varepsilon} \frac{\partial \varepsilon}{\partial y_{d}}$$
 (3.30)

A complete listing of the nonlinear channel computer code is given in Appendix A.

Flow Conditions	Mesh	Storage Requirement (M bytes)	Run Time (CPU hours)
$2a_{d}/\lambda = 0.03125$ $Re_{b} = 6400$	9 x 81	1.2 (4.0)	5 (5)
$2a_{d}/\lambda = 0.05$ $Re_{b} = 38,800$	9 x 151	2.4	20

Table 3.2 Storage Requirements and Run Times

II. Models for Turbulent Stresses

A channel flow consists of a wall region and a core region where the eddy viscosities behave differently. The following equation by Reynolds and Tiederman [38] was used to describe the eddy viscosity:

$$\frac{v_{t}}{v} = \frac{1}{2} \left[1 + \frac{4}{9} \kappa^{2} \left(\frac{y_{d}^{\dagger} u^{*}}{v} \right)^{2} \left(1 - \frac{y_{d}^{\dagger}}{2h_{d}} \right)^{2} \left(3 - 4 \frac{y_{d}^{\dagger}}{h_{d}} + 2 \left(\frac{y_{d}^{\dagger}}{h_{d}} \right)^{2} \right)^{2} \right]$$

$$\left[1 - \exp\left(\frac{-y_{d}^{1}\tau_{d}^{1/2}}{\rho^{1/2}v_{A}}\right)\right]^{2}$$
 \[1/2 \] \quad \tag{3.31}

where h_d is the average half channel height, κ is the von Karman constant, and τ_d is the local shear stress in the fluid. The van Driest parameter, A, is a measure of the thickness of the viscous wall region. Equation (3.31) is an adaptation for a channel of an expression first suggested by Cess [13] for pipe flow. The expression is a combination of van Driest's [46] wall region law and Reichardt's [36] middle law. The Cess profile provides a smooth transition between the inner and core regions because it is continuous and analytic.

In equation (3.31) the variable y_d' refers to a physical distance from either the wave surface or the top wall of the channel. In this analysis y_d' is measured from the wave surface for grid points at or below the center line of constant η . Above this line y_d' is measured from the top wall. Three methods of evaluating y_d' were investigated:

- l) along a line of constant ϵ ,
- 2) along a line normal to the surface,

and 3) along a vertical line to the surface.

Figure 3.5 illustrates the three types of distances. The three distances are identical for waves of infinitesimal amplitude.

It should be noted that for a channel it is not appropriate to model the eddy viscosity with a mixing length as did Thorsness and Abrams for a boundary layer flow. Mixing length theories predict zero eddy viscosity at the channel center. Measurements show that the eddy viscosity is large and nearly constant in the core region. Figure 3.6 shows the Cess eddy viscosity profile for a flat channel with $Re_b = 6400$, $\kappa = 0.48$ and A = 33.

The nonlinear channel calculations were performed with turbulence Models C * and D * developed by Thorsness [44] and Abrams [2].

A. Model C*

Model C* is simply the Cess eddy viscosity profile, equation (3.31), with the flat channel value of the van Driest parameter, A. Although the value of A is constant, the eddy viscosity varies slightly in the flow direction since it is a function of the local shear stress. Turbulent stresses change along the wave due to variations in both the eddy viscosity and the local rate of strain. See equations (3.16)-(3.18).

B. Model D*

Model D^* is an extension of Model C^* in which pressure gradient effects on the turbulence are taken into account. In this model the

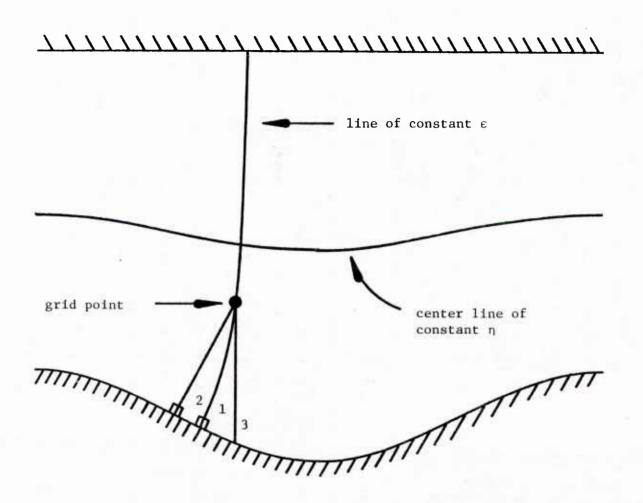


Figure 3.5 Methods of Evaluating y_d^{\prime} in Cess Profile, equation (3.31) (Wave Amplitude Exaggerated)

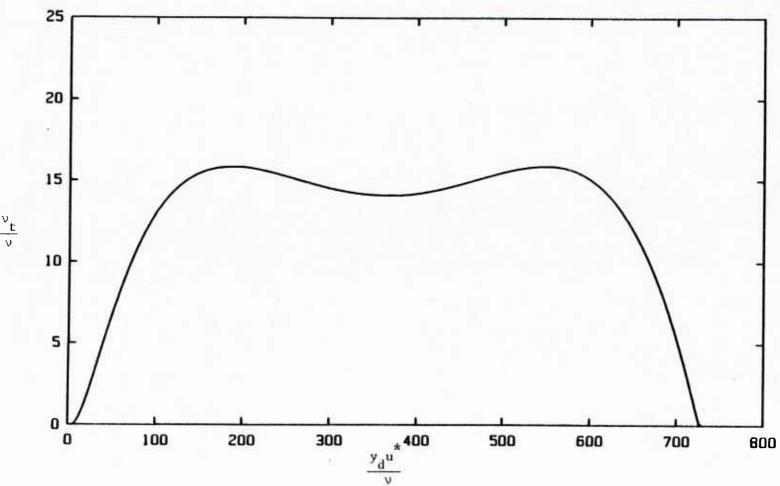


Figure 3.6 Cess Eddy Viscosity Profile (Flat Channel), Re $_{\rm b}$ = 6400, κ = 0.48, A = 33

van Driest parameter, A, is used as a scale factor that governs the thickness of the viscous wall region. The viscous wall region thickens with increasing negative pressure gradient and thins with increasing positive pressure gradient. For equilibrium boundary layers Loyd, Moffat and Kays [31] suggest the following functional dependence on A on the dimensionless pressure gradient, $p^+ = (dp_d/dx_d)(v/\rho u^{*3})$,

$$A = \overline{A} \left[1 + p^{+}k_{1} + p^{+2}k_{2} + \dots \right]$$
 (3.32)

where \bar{A} is the flat channel value of A and k_1 and k_2 are empirical constants. Loyd et al. have argued that for a nonequilibrium condition, such as exists in flow over waves, an effective pressure gradient, p_{eff}^+ , should be used in equation (3.21) where

$$\frac{d p_{eff}^{+}}{d \left(\frac{x_{d} u^{*}}{v}\right)} = \frac{p^{+} - p_{eff}^{+}}{k_{L}}$$
(3.33)

and \mathbf{k}_{L} is an empirical lag constant. This, in effect, introduces a lag between the imposition of a nonzero pressure gradient and a change of scale in the viscous wall region.

III. Test of Channel Analysis

The nonlinear channel analysis was tested by comparing surface stress results for the limiting case of very small amplitude waves with the linear boundary layer analysis of Thorsness [44] and Abrams [2] and with literature data. The channel calculations were performed

with $2h_d/\lambda=1.0$, $2a_d/\lambda=0.001$, $\kappa=0.48$, and A=33. The channel height to wavelength ratio, $2h_d/\lambda$, was chosen to correspond to that of the channel in this laboratory. The dimensionless wave amplitudes ranged from a_d $u^*/\nu=0.0314$ at α_d $\nu/u^*=0.1$ to a_d $u^*/\nu=6.28$ at α_d $\nu/u^*=0.0005$. Since a_d u^*/ν was always much less than 27 a linear response was ensured. Selection of the Cess profile constants, κ and A, is discussed in Chapter 5, Section I. All of the calculations presented in this section used turbulence Model D^* with $k_1=-35$, $k_2=0$, and $k_L=1800$ as suggested by Abrams [2].

Predictions of the amplitude of the shear stress responses are given in Figure 3.7 compared with the data of Abrams [2]. Abrams obtained linear shear stress responses in a channel with $2h_d/\lambda=1.0$ and $2a_d/\lambda=0.014$. This figure shows that with turbulence constants $k_1=-35$ and $k_L=1800$ the channel analysis provides the best fit to the data. The boundary layer calculations underpredict the data and were found by Thorsness [44] to be low for the range of contants $-60 < k_1 < -15$ and $1500 < k_L < 6000$.

Phase angles of the shear stress are given in Figure 3.8. Again, for k_1 = -35 and k_L = 1800, the best fit to the data is seen with the channel analysis. Better agreement might be obtained with a slight reduction of k_L . However, the lengthy nature of the channel calculations prohibited fine tuning of the turbulence constants.

Amplitudes and phases of pressure responses are shown in Figures 3.9 and 3.10 compared with literature data. The amplitudes predicted by the boundary layer and channel analyses are in close agreement. However, significant differences in the phase angles are observed

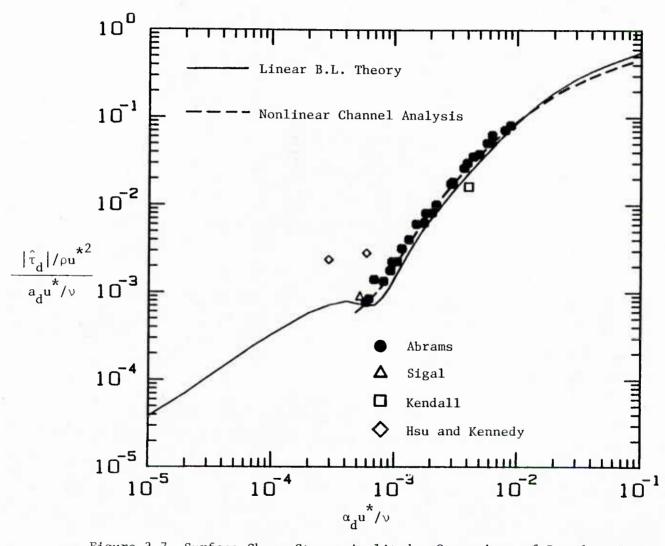


Figure 3.7 Surface Shear Stress Amplitude, Comparison of Boundary Layer and Channel Analyses for Small Amplitude Waves, Model D* $\binom{k_1}{k_1} = -35$, $k_L = 1800$

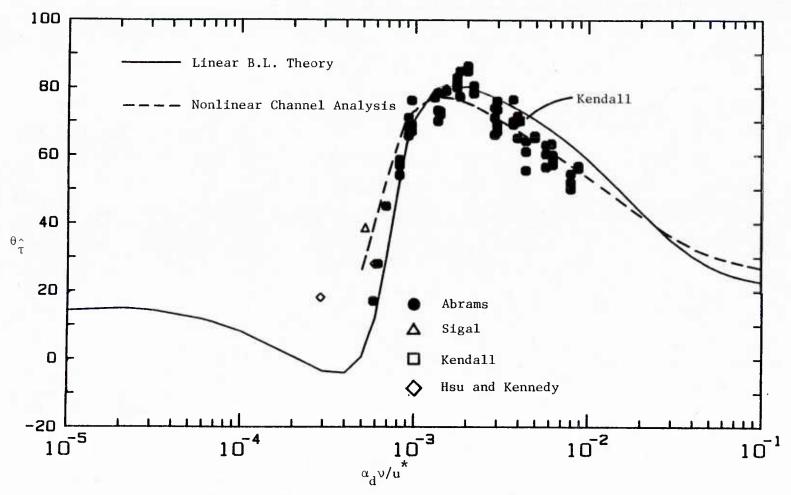


Figure 3.8 Phase Angle of Surface Shear Stress, Comparison of Boundary Layer and Channel Analyses for Small Amplitude Waves, Model D^* ($k_1 = -35$, $k_L = 1800$)

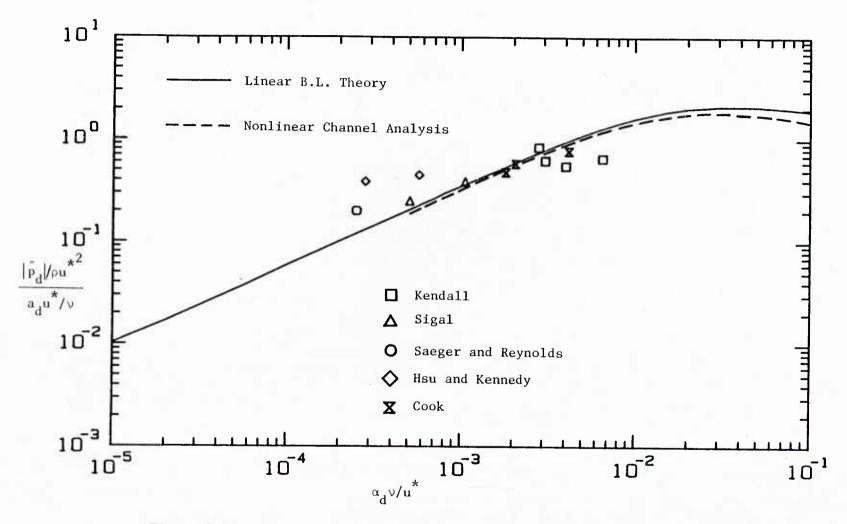


Figure 3.9 Surface Pressure Amplitude, Comparison of Boundary Layer and Channel Analyses for Small Amplitude Waves, Model D^* ($k_1 = -35$, $k_1 = 1800$)

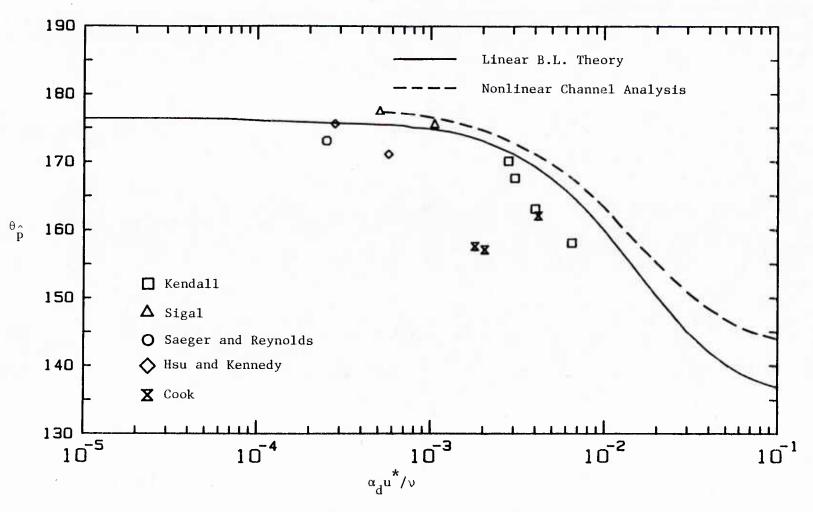


Figure 3.10 Phase Angle of Surface Pressure, Comparison of Boundary Layer and Channel Analyses for Small Amplitude Waves, Model D* $(k_1 = -35, k_L = 1800)$

between the two methods of calculation. At very small $\alpha_d v/u^*$, where the flow is in equilibrium with the wave, zero phase shift in the pressure field is expected ($\theta_{\hat{p}}$ = 180°). Here the channel analysis appears to be qualitatively more correct than the boundary layer analysis as it predicts a closer approach to 180°. At large $\alpha_d v/u^*$ the two theories differ greatly. This is not surprising because the boundary layer analysis of Thorsness and Abrams assumes a deep logarithmic layer while the logarithmic layer in a channel is very thin under these conditions. A quantitative check of the accuracy of the pressure calculations is not possible. This is because few pressure measurements have been made over wavy surfaces and those available show large scatter. Comparisons with theory are further complicated since the literature data were obtained in many different flow geometries including boundary layers, channels, and pipes.

CHAPTER 4

EXPERIMENTAL EQUIPMENT AND PROCEDURES

The purpose of the experimental work was to obtain velocity profiles in the viscous wall region $(y_d u^*/v < 40)$ for turbulent flow over a solid sinusoidal wavy surface with small enough amplitude that the flow does not separate. The major disturbances in the flowfield are expected to be within this thin region. The profiles will give a better physical understanding of how the presence of a wavy surface perturbs a turbulent flowfield and can be used as a test of the turbulence models of Thorsness [45] and Abrams [2].

Fluid velocities were measured using laser-Doppler velocimetry.

This method was chosen because it is a non-obtrusive measurement technique with a small enough "probe" size to resolve the viscous wall region.

Section I of this chapter describes the flow loop and test section.

Section II discusses the optical traverse and section III describes the

LDV system and data acquisition.

I. Flow Loop and Test Section

The experiments were carried out in a horizontal rectangular water channel originally built by Cook [17] and later modified by Zilker [48] and Buckles [10]. A detailed description of this flow loop may be found in a thesis by Buckles [9]. Consequently the description here is limited to the essential features.

A schematic of the flow loop is shown in Figure 4.1. The rectangular channel has a cross section 2 in. high and 2 ft. wide and a length of 27.5 ft.

Figure 4.1 Schematic of Low Loop

- 1. Test section window
- 2. Removable wave surface
- 3. Removable blanking plate
- 4. Honeycomb
- 5. Round to rectangular diffusors
- 6. Annubar flow meter
- 7. Butterfly throttling valve
- 8. Bypass diaphragm valve
- 9. Small pump
- 10. Large pump

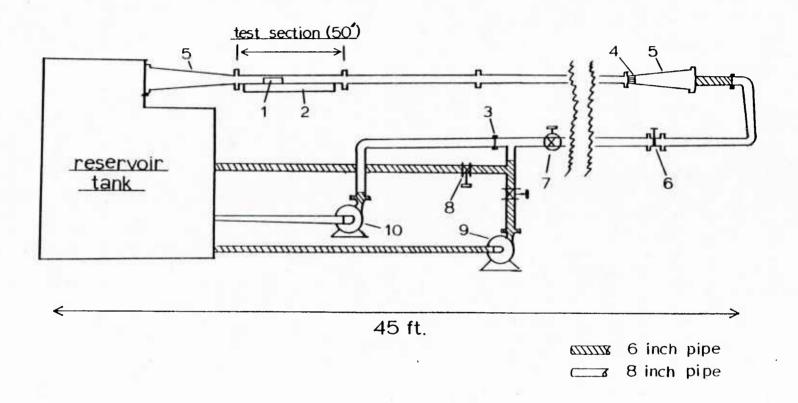


Figure 4.1 Schematic of Flow Loop

The first 23.5 ft. of the channel is made of stainless steel and provides approximately 70 hydraulic diameters for flow development before the test section. The existence of fully developed turbulent flow at the entrance to the test section has been verified by Zilker [48] and Thorsness [44]. The channel is also wide enough that the mean flow is essentially two-dimensional.

The pump is a Worthington 6CNG84 centrifugal pump with a 5 h.p. motor that can deliver flow rates of up to 800 g.p.m. This flow rate corresponds to a channel Reynolds number of 42,000 based on the half channel height and the bulk velocity.

The downstream end of the channel is a 58 in. long Plexiglas test section in which the velocity measurements were performed. The top wall of this section is flat and a portion of the bottom wall consists of a 24 in. by 27 in. removable sinusoidal wavy surface. The waves were machined with the mean wave level at the level of the lower wall. This was to ensure that there was no change in the mean cross-sectional area. Each side of the test section contains a 5 in. \times 1-1/2 in. glass window to allow the laser beams of the LDV system to pass through one side of the channel and be viewed by the receiving optics on the other side.

Velocity measurements were obtained over waves of amplitude 0.03125 in. and 0.05 in. at Reynolds numbers of 6400 and 38,800 repsectively. Each wave surface contained ten waves of wavelength two inches and the tests were conducted over the eighth wave at one-tenth wavelength increments. Details of the construction of the wave surfaces may be found in theses by Zilker [48] and Cook [17].

II. Modifications to Optical Traverse

Buckles [10] constructed a traversing mechanism for movement of the LDV system in the normal and streamwise directions. The traverse was modified to increase its accuracy of movement and to decrease its susceptability to vibration. Accurate vibration free movement was necessary to conduct measurements close enough to a wave surface to resolve the viscous wall region.

The mechanism's vertical motion is on twin stainless steel precision ground shafts. They are mounted vertically and parallel to each other on opposite sides of the unistrut structure that supports the flow loop. On each shaft are two linear ball bearing pillow blocks. The bearing blocks are mounted to a vertically movable rigid cage constructed of aluminum I-beams. Connected to the top of this cage are a pair of eleven foot I-beams that run perpendicular to the channel test section. This pair of beams in the optical bed for the LDV system. Buckles suspended the entire structure by 1/4 inch steel cables in a sling-type design that raised and lowered the traverse with a scissors jack. It was found that this suspension design did not provide an even enough lifting force on both sides of the cage to prevent binding in the shaft bearings. As a result the optical bed underwent a small amplitude seesaw type motion when moved vertically. The play in the shaft bearings also made the traverse susceptable to vibration.

The seesaw motion was corrected by supporting the I-beam cage and optical bed on two lead screws. A drawing of the design is shown in Figure 4.2.

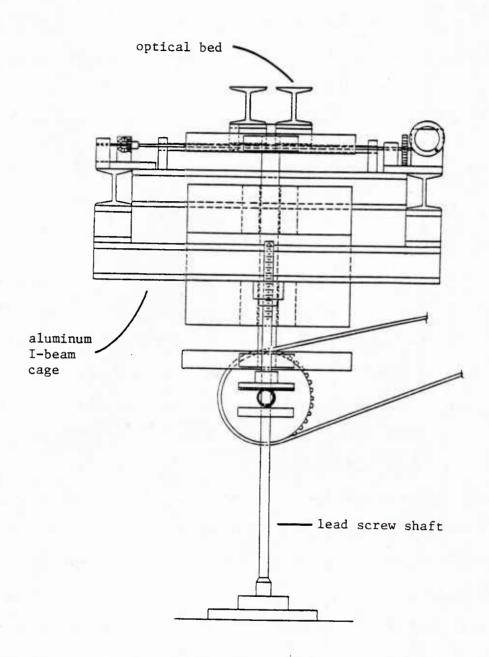


Figure 4.2 Optical Traversing Mechanism

Each lead screw is 8-1/2 inches long, one inch in diameter and turns through a 2-1/2 inch diameter brass nut that is attached to the cage. The lead screws are pinned to one inch diameter stainless steel shafts which are mounted vertically and parallel to each other with a separation distance of 5 feet.

The shafts are supported by a stainless steel collar and rotate freely in flat race thrust bearings (Figure 4.3). A radial bearing is mounted under the thrust bearings to keep the shafts aligned vertically. The entire lower shaft assembly sits on a 3-1/4 in. \times 5-1/4 in. \times 1-1/2 in. aluminum block which is attached to a second 6 in. \times 12 in. \times 1 in. aluminum block that is bolted to the floor.

To ensure that the lead screw shafts turn in unison and raise the optical bed evenly, they are connected mechanically by a system of four bevel gears and a horizontal 5/8 in. steel rod. A 9 in. sprocket is mounted on the rod. This sprocket is turned by a 2 in. sprocket on the end of a 4 ft. roller chain. See Figures 4.4 and 4.5. A hand crank is attached to the smaller sprocket.

The bevel gears on the lead screw shafts and rod have a 4:1 gear ratio. The gear ratio between the two sprockets in also 4:1. Thus a single turn on the hand crank will rotate the lead screw shaft 1/16th of a revolution. This rotation will raise or lower the I-beam cage and optical bed 0.0125 in. since then are 5 turns per inch on the lead screws. It was found that the smallest distance that the bed could accurately be moved was 0.0005 in.

The rigidness of the lead screw design eliminated most of the vertical vibrations inherent in the suspension design.

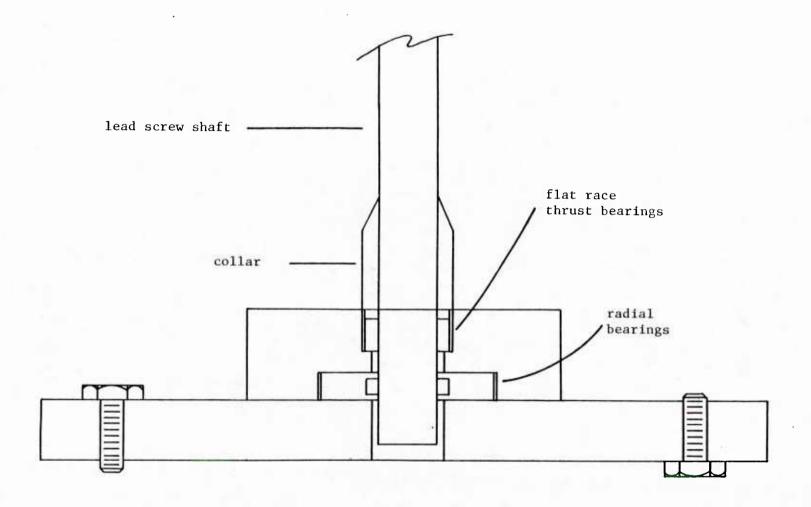


Figure 4.3 Detail of Lower Lead Screw Shaft Assembly

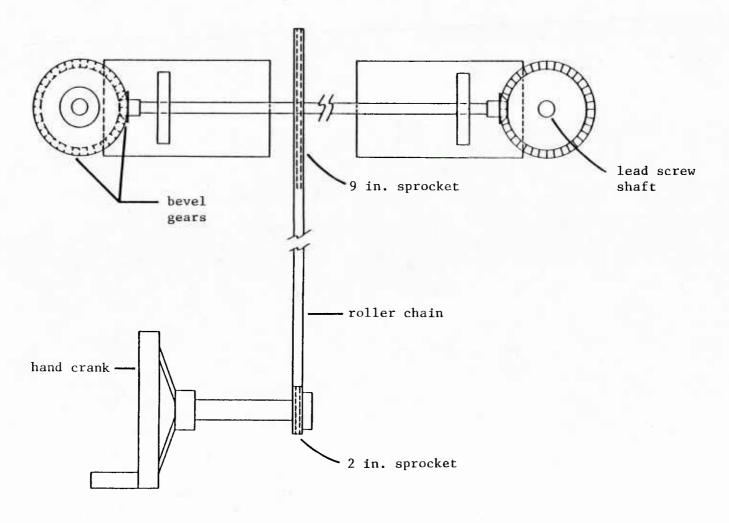


Figure 4.4 Top View of Mechanical Connection Between Lead Screw Shafts

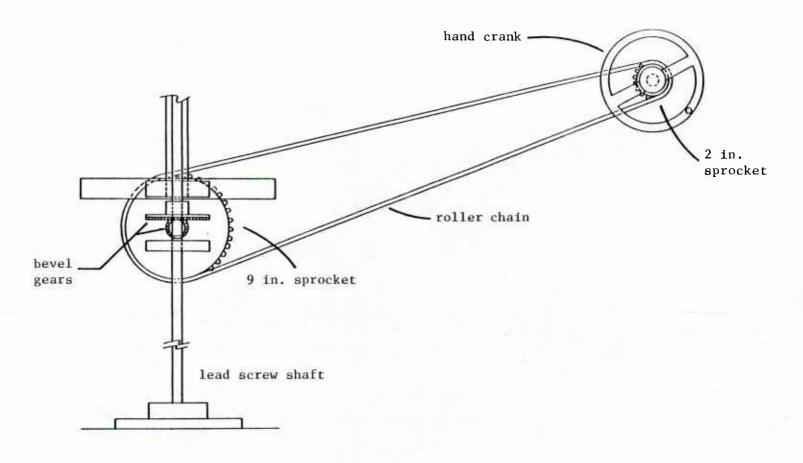


Figure 4.5 Side View of Lead Screw Shaft Crank Assembly

It was also necessary to modify the manner in which the traverse was moved in the horizontal direction. In the design of Buckles [9] the optical bed was moved horizontally on linear bearings with a pulley system using thin steel cables. This pulley system did not hold the bed stationary. The bed was free to move a little in the horizontal direction because the cables would stretch slightly when the heavy bed vibrated.

The horizontal vibration was substantially reduced by eliminating the pulley system and moving the optical bed on a second pair of lead screws. The new horizontal traverse design is shown in Figure 4.6. The pair of lead screws are pinned on each side to 1/2 in. stainless steel rods that are mounted horizontally and parallel to each other on the I-beam cage. As in the case of the vertical lead screws, these rods turn in unison because they are connected mechanically by a system of 4 bevel gears and a 3/8 in. steel rod. The lead screws turn through 1 in. \times 1-1/4 in. \times 2 in. brass nuts attached to the bed and the rods are rotated by turning a hand crank on a reduction gearbox. The entire horizontal traverse system is geared so that a single turn on the hand crank moves the optical bed 0.025 in.

III. LDV System and Data Acquisition

The velocity measurements were obtained using a single-channel dual-beam laser-Doppler velocimeter operated in the forward-scatter mode. The LDV system used was identical to that of Buckles [9] except for the receiving optics. Therefore only a brief description of the system and its operation will be given here. Also, for a

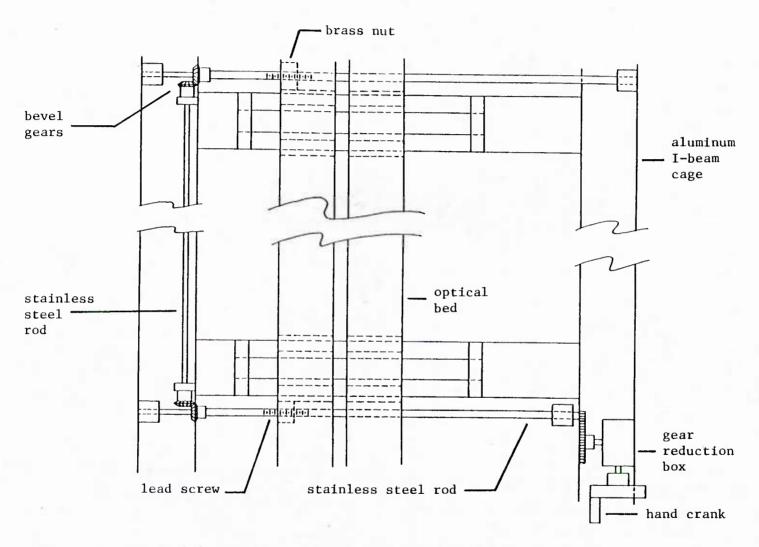


Figure 4.6 Top View of Horizontal Traversing Mechanism

complete description of LDV theory, the reader is referred to a report by Adrian [5].

The LDV system is shown in Figure 4.7. They system views the flowfield from the side of the channel. It consists of a 15 mW Spectra Physics He-Ne laser and TSI Inc. optics and a photomultiplier tube. A single laser beam is split by prisms into two beams in the horizontal plane. The beams are focused by a 250 mm focal-length transmitting lens and intersect to form the measurement volume where fluid velocity is determined. Two 2.27:1 beam expansion units were placed in series before the transmitting lens to reduce the measurement volume dimensions. The measurement volume, defined by the e^{-2} intensity distribution of the illuminating beams, is an ellipsoid with axes 3.5×10^{-3} cm, 3.5×10^{-3} cm, and 3.8×10^{-2} cm in the streamwise, normal and traverse directions.

The receiving optics is a TSI Model 9142-2 polarization separator. A schematic of this unit is shown in Figure 4.8. The unit can be used to collect and separate scattered light into two polarities that are perpendicular to each other. Light is collected with a 350 mm focal-length lens and focused by a 200 mm lens onto a mirror where it is reflected into a polarization splitter. The splitter sends horizontally polarized light to one photomultiplier tube and vertically polarized light to a second tube. The entire receiving optics unit is part of a LDV system manufactured by TSI to measure two velocity components that are distinguished by their polarities. However, for the experiments in this thesis a single component transmitting system was used where all of the scattered

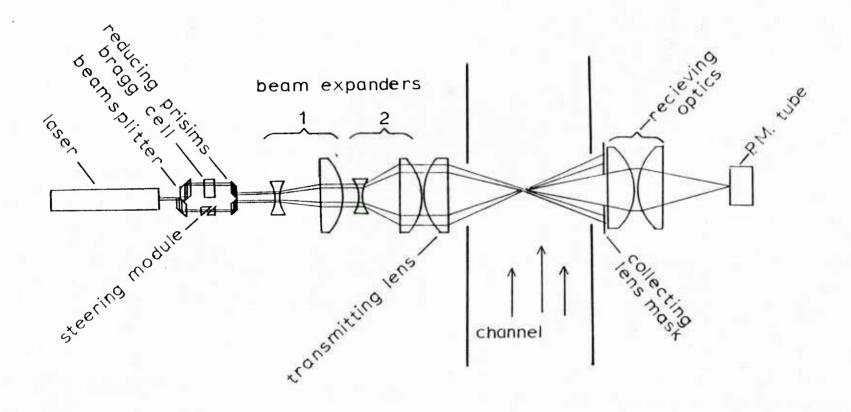


Figure 4.7 Laser-Doppler Velocimeter System

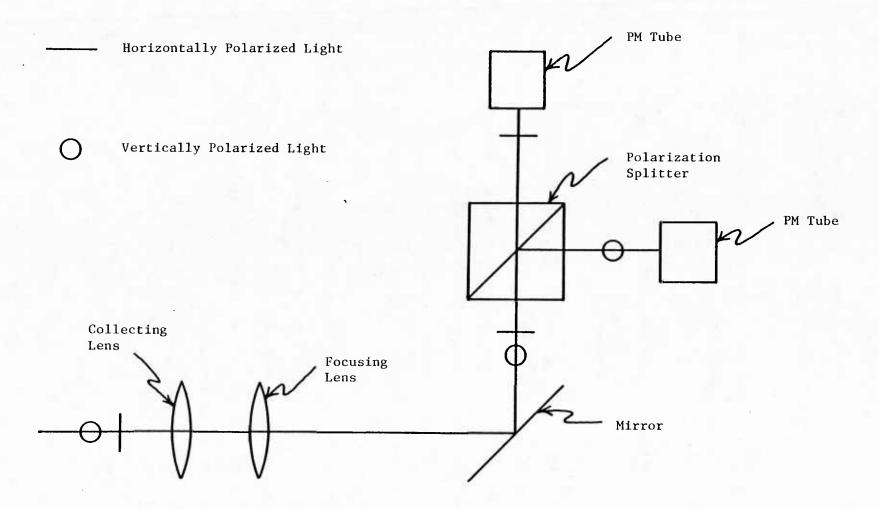


Figure 4.8 Schematic of Receiving Optics

light was vertically polarized. Consequently only one photomultiplier tube was used. The polarization separator was set up in anticipation of future two-component LDV measurements.

The Doppler signals were frequency shifted by 200-500 KHz to increase the count rate, lower fringe biasing and to detect negative velocities if present. Pedestal components were removed prior to processing with a 100 KHz high-pass filter. The signal processor was a TSI Model 1090 frequency tracker operated on its 500 KHz and 5MHz ranges.

The water was prepared by filtering out all particles larger than 3 µm in diameter and adding 0.5 µm white latex paint spheres manufactured by Dow Chemical Co. The concentration of these seed particles was such that on the average only one particle was in the measurement volume at any given time. Under these conditions data rates of 2000-4000 and 4000-8000 samples per second were achieved at Reynolds numbers of 6400 and 38,800 respectively. The resulting signals from the tracker had "high data density" (Adrain [5]); i.e. there were many velocity samples per Taylor microscale of the flow. In this region of operation the signals could be assumed to be continuous. They were filtered at 1 KHz to remove noise and sampled at 80 Hz by an 8-bit A/D converter. Mean velocities and mean root mean square fluctuations were calculated by averaging batches of 4000 samples.

CHAPTER 5

EXPERIMENTAL RESULTS

I. Flat Channel Data

A. Friction Factors

The velocity measurements presented in this thesis are made nondimensional with respect to wall parameters. Velocities are made dimensionless with flat channel friction velocities, $\mathbf{u}^* = \sqrt{\frac{\tau_{\mathbf{w}}}{\rho}}$, obtained from the flat channel electrochemical shear stress data of Thorsness [44]. Distances above the wave surface are made dimensionless with respect to v/\mathbf{u}^* , where v is the kinematic viscosity. Figure 5.1 shows Thorsness' Fanning friction factor data versus a Reynolds number, $Re_{\mathbf{b}}$, based on the half channel height, $h_{\mathbf{d}}$, and the bulk velocity, $U_{\mathbf{b}}$. The data are well fitted by the Blasius type equation

$$f = 0.0612 \text{ Re}_{b}^{-1/4}$$
 (5.1)

Equation 5.1 is identical to that obtained by Cohen [15] for air flow in a one inch rectangular channel. The friction velocity is defined as a function of the friction factor according to the following equation

$$u^* = U_b \sqrt{f/2}$$
 (5.2)

The channel calculations are also normalized with wall parameters. However, in order to keep the calculations self consistent and independent of the data, the friction velocities used were obtained

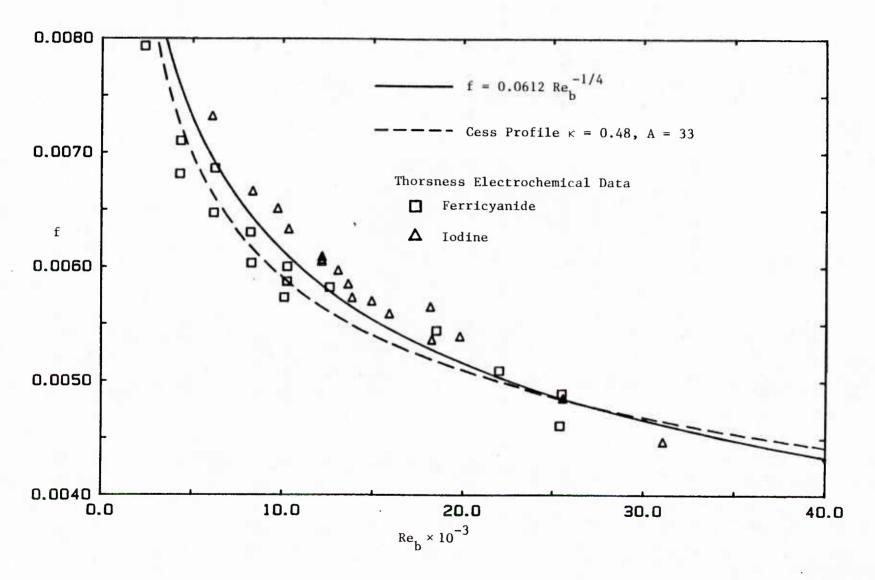


Figure 5.1 Fanning Friction Factor for Flat Channel

by applying the Cess profile to a flat channel. The flat channel friction factor-Reynolds number relationship predicted by the Cess profile with $\kappa=0.48$ and A=33 is also shown in Figure 5.1. Good agreement with the friction factor data is observed.

The values of the von Karman constant and the van Driest parameter were selected to give the best fit to equation (5.1). These values differ from the generally accepted values of κ = 0.41 and A \approx 25. It is believed that these constants can be adjusted freely for the Cess profile because they lose some physical meaning due to the matching process in the derivation of this equation.

Values of κ = 0.48 and A = 33 were used for all wavy surface channel calculations.

B. Mean Velocities

Thorsness [44] obtained flat channel velocity profiles at several bulk Reynolds numbers, Re $_{\rm b}$, ranging from 5190 to 29,600. Figure 5.2 shows a comparison of Thorsness' data at the extremes of this range with Cess profiles using κ = 0.48 and A = 33. Good agreement is observed. A good prediction of flat channel velocity profiles with the Cess equation is a prequisite for applying this eddy viscosity model to the more complicated flow over wavy surfaces.

C. Turbulent Intensities

In order to test the ability of the LDV system to measure accurately turbulent intensities, measurements of the streamwise intensity, $\sqrt{u_d^{'2}}/u^*$, were obtained in a flat channel. Figure 5.3 shows intensity data at Re $_b$ = 11,000. A maximum intensity of 2.7 in wall units is observed at $y_d u^*/v = 14$. This agrees closely with the

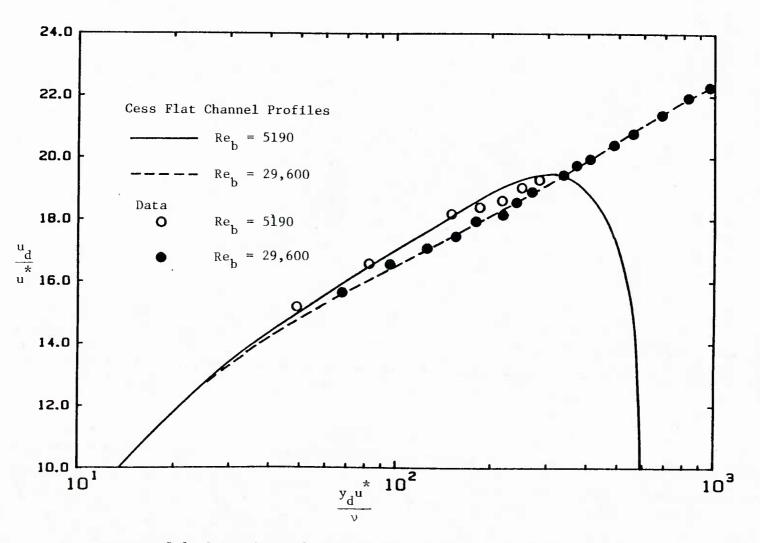


Figure 5.2 Comparison of Flat Channel Velocity Data of Thorsness with Cess Profile

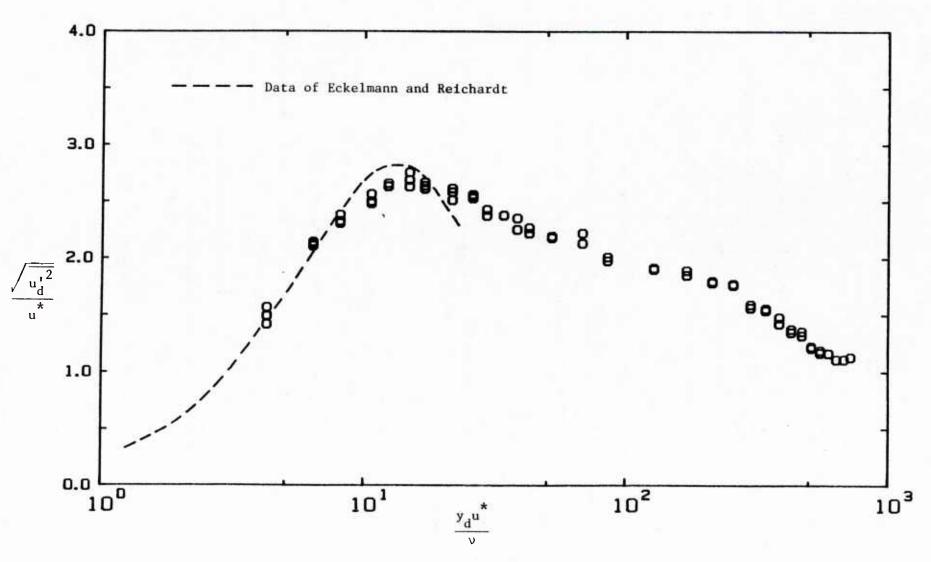


Figure 5.3 Flat Channel Streamwise Intensity Profile, $Re_{b} = 11,000$

measurements of Eckelmann and Reichardt [18], which are also shown in Figure 5.3. In other channel investigations Compte-Bellot [16], Clark [14], Hussain and Reynolds [21], and Reischman and Tiederman [37] found maximum intensities ranging from 2.5 - 3.3 at $y_d u^*/v$ locations of 12-15. The centerline intensity of 1.1 is slightly higher than values from the above literature which range from 0.75-1.0. A possible source of the increased intensity is vibrations of the optical traverse and test section.

It should be noted that the literature intensity measurements were obtained over a wide range of Reynolds numbers. However, comparisons with the data in Figure 5.3 are valid since both the maximum and centerline intensities are relatively insensitive to flowrate when normalized with wall parameters.

A tabulation of the flat channel intensity data may be found in Appendix B.

II. Flow Regime Map

Two sets of velocity measurements over waves were taken, one each in the linear and nonlinear shear stress response regions discussed in Chapter 2. The set of data in the linear region was obtained over a wave of steepness $2a_d/\lambda=0.03125$ with a dimensionless wavenumber of $\alpha_d v/u^*=0.008$ (Re $_b=6400$). For the nonlinear set $2a_d/\lambda$ was equal to 0.05 and $\alpha_d v/u^*$ was equal to 0.00165 (Re $_b=38,800$). Figure 5.4 shows the location of the two sets of data on the flow regime map.

The data consist of time averaged velocity profiles and profiles of the root mean square value of the fluctuating streamwise intensity.

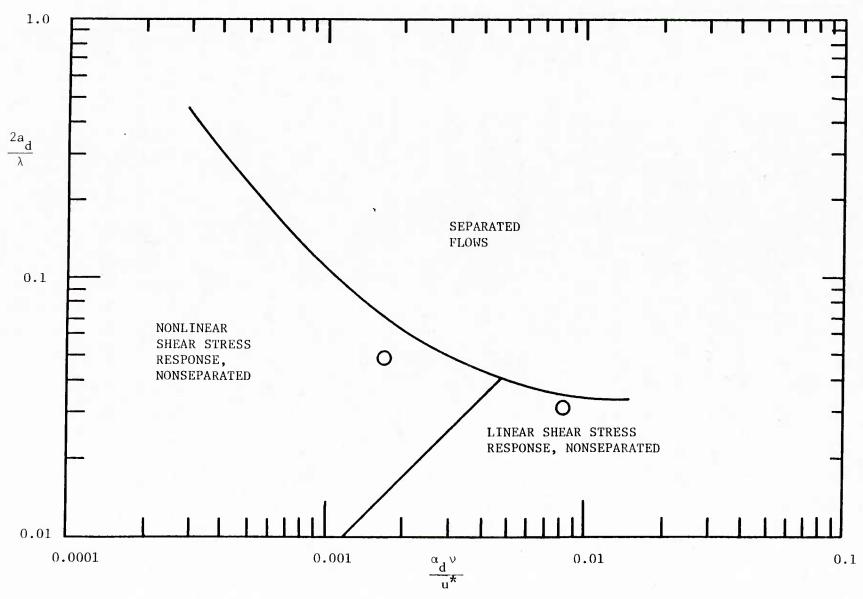


Figure 5.4 Location of LDV Data on Flow Regime Map

An analysis and discussion of the data and a comparison with the turbulence models described in Chapter 3 is given in Chapter 6.

III. Results for Wave of Steepness $2a_d/\lambda = 0.03125$

The wave steepness $2a_d/\lambda=0.03125$ and the wavenumber $\alpha_d v/u^*=0.008$ were chosen for the first set of data because a linear velocity field response was expected under these conditions. A wave of lower steepness would have produced a closer approximation to a linear flowfield. However, the wave of $2a_d/\lambda=0.03125$ was used because split film measurements of Zilker [48] indicated that a wave with $2a_d/\lambda=0.0125$ did not cause large enough changes in the velocity profiles to be distinguished from a flat plate profile. A larger amplitude wave was not used since separation may have resulted (Zilker [48]). The wavenumber $\alpha_d v/u^*=0.008$ corresponds to the lowest steady flowrate that can be obtained with the flow loop. Higher flowrates produce a more nonlinear flowfield by increasing the dimensionless wave amplitude, $a_d u^*/\nu$. The dimensionless wave amplitude is equal to 12.3. Zilker [48] observed linear shear stress responses for $a_d u^*/\nu < 27$.

Measurements of the mean velocity profiles at the ten x_d/λ positions are shown in Figures 5.5-5.14. Each profile was obtained by traversing the LDV vertically from near the wave surface to the channel centerline. The closest data to the wave are at $y_d^*/\nu = 2$. Closer measurements were not possible due to vibrations of the wave, extraneous laser light reflections off the wave surface, and the measurement volume diameter of 0.5 wall units. The channel centerline

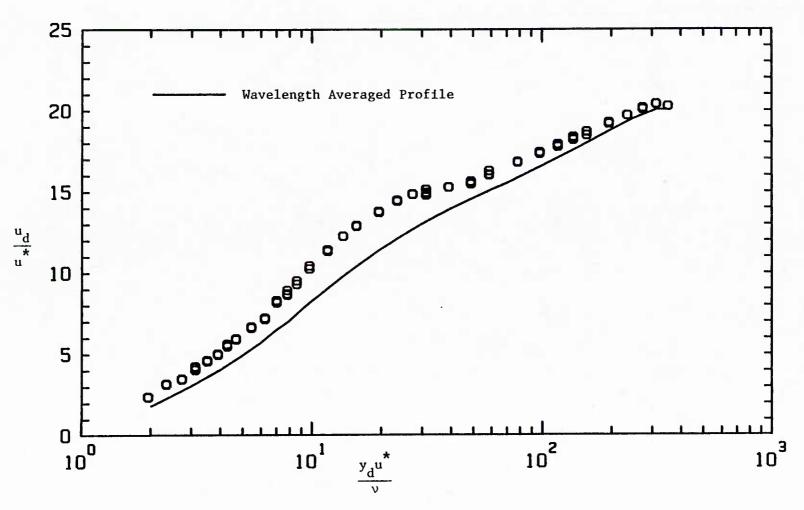


Figure 5.5 Mean Velocity Measurements, $x_d/\lambda = 0.1$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

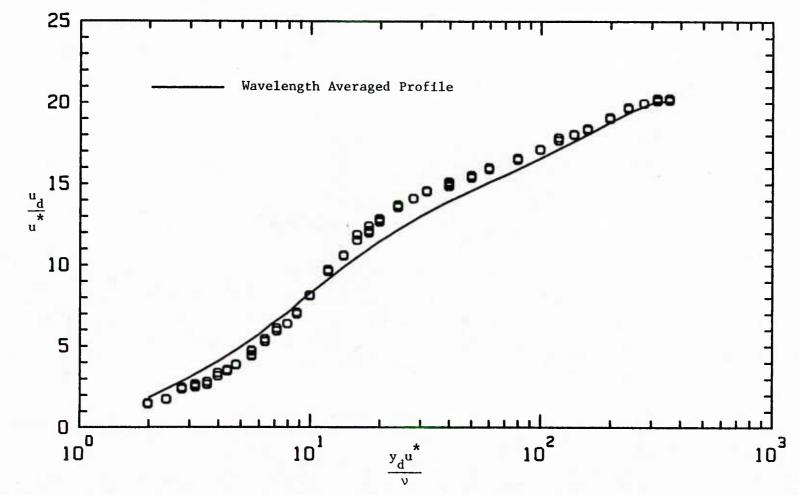


Figure 5.6 Mean Velocity Measurements, $x_d/\lambda = 0.2$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

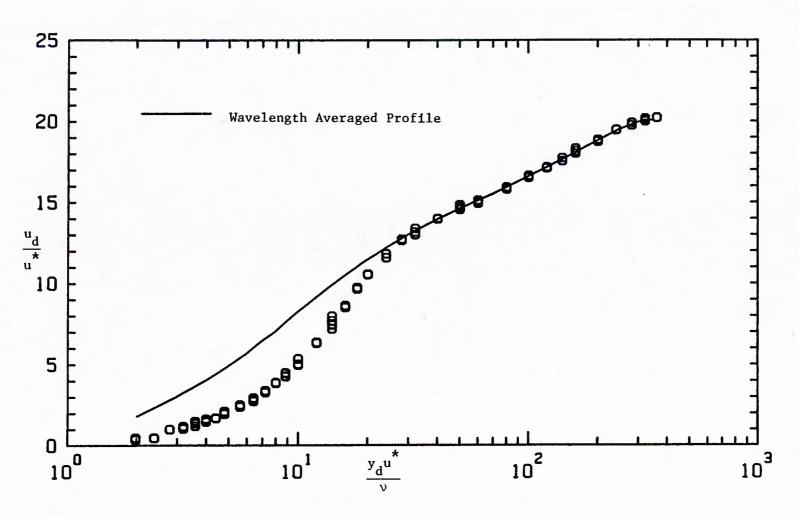


Figure 5.7 Mean Velocity Measurements, $x_d/\lambda = 0.3$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

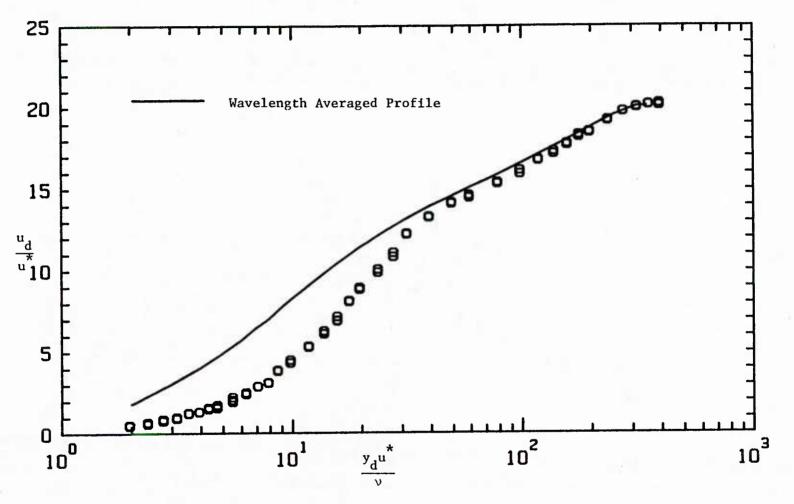


Figure 5.8 Mean Velocity Measurements, $x_d/\lambda = 0.4$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

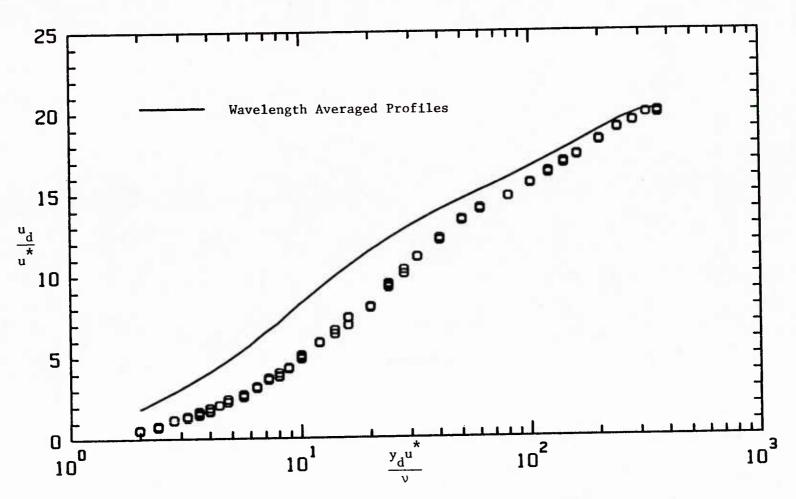


Figure 5.9 Mean Velocity Measurements, $x_d/\lambda = 0.5$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

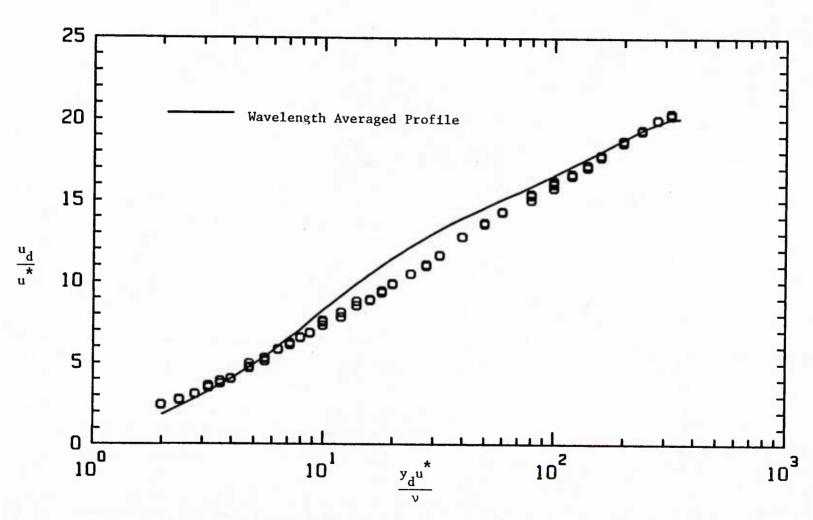


Figure 5.10 Mean Velocity Measurements, $x_d/\lambda = 0.6$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

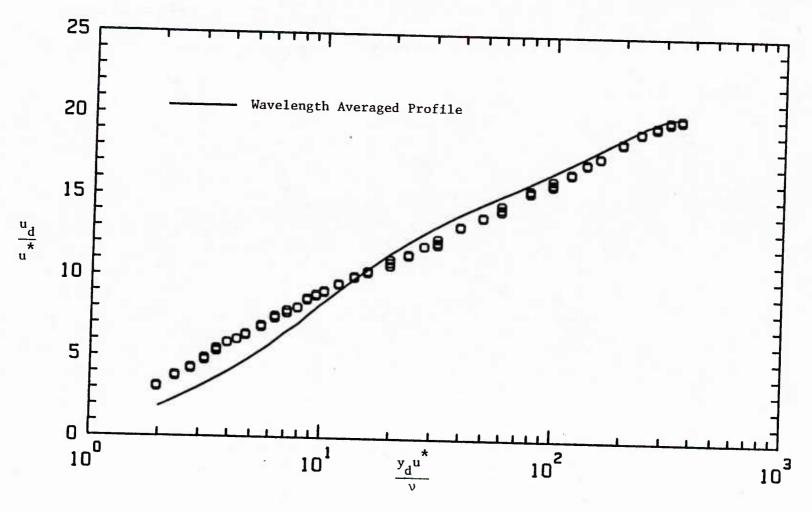


Figure 5.11 Mean Velocity Measurements, $x_d/\lambda = 0.7$, $2a_d/\lambda = 0.03125$ Re_b = 6400, $2h_d/\lambda = 1.0$

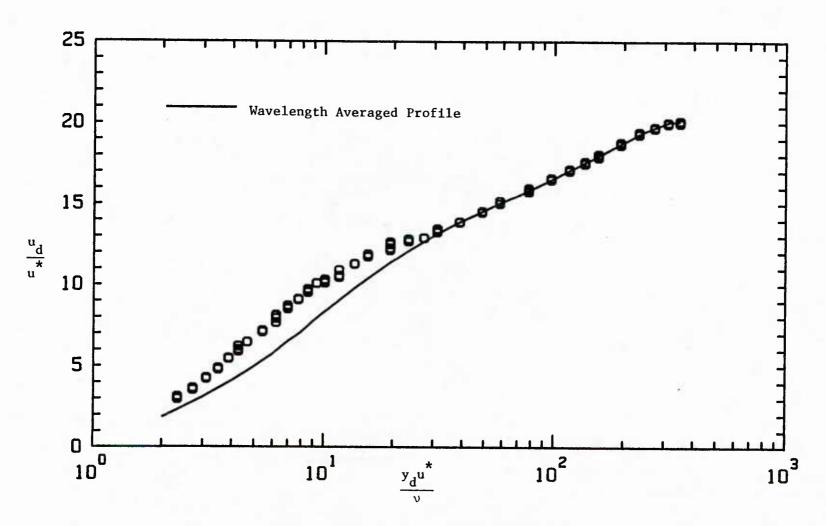


Figure 5.12 Mean Velocity Measurements, $x_d/\lambda = 0.8$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

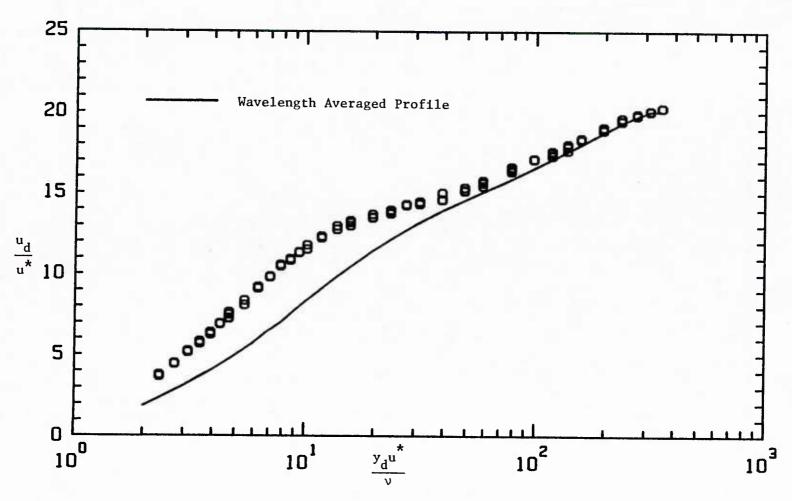


Figure 5.13 Mean Velocity Measurements, $x_d/\lambda = 0.9$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

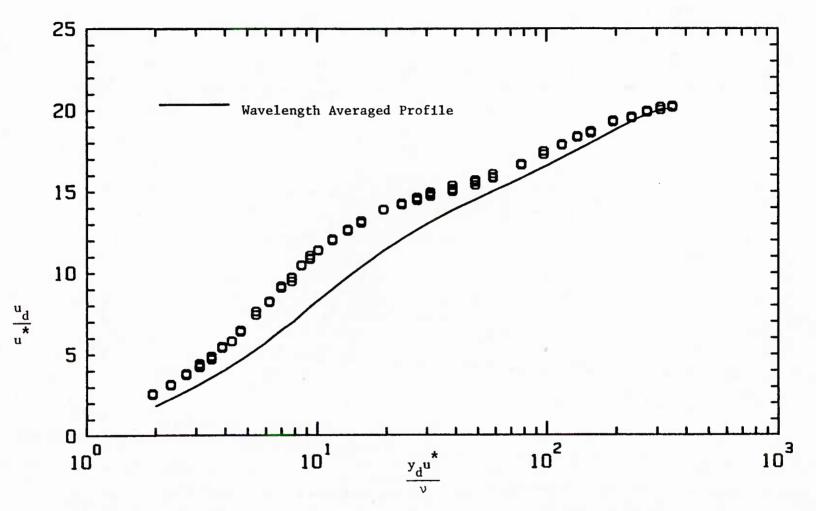


Figure 5.14 Mean Velocity Measurements, $x_d/\lambda = 1.0$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

is about 365 $y_d u^*/v$ units above the average wave height. Approximately twenty measurements were taken within the viscous wall region at each x_d/λ position. The uncertainties in the distance, $y_d u^*/v$, and the velocity, u_d/u^* , are about 0.40 and 0.25 dimensionless units respectively.

Figure 5.5-5.14 also contain the wavelength averaged profile as a reference for observing disturbances about the mean flowfield. The calculation of the average profile is discussed in Chapter 6, Section I.B. The most striking feature of these figures is that there is a lag in the reaction of the fluid to the wave which increases with increasing height.

Profiles of the streamwise intensity are given in Figures 5.15-5.24 compared with the reference wavelength averaged intensity profile. These figures show that the outer portion of the viscous wall region lags the inner portion in reacting to the wave. A detailed discussion of this behavior is given in Chapter 6, Section I.G.

IV. Results for Wave of Steepness $2a_d/\lambda = 0.05$

The conditions for the second set of data, $2a_d/\lambda = 0.05$ and $a_dv/u^* = 0.00165$, were chosen because a highly nonlinear nonseparated flowfield was expected for these conditions. Measurements of this flowfield should provide a good test of the nonlinear channel analysis for waves of finite amplitude and of turbulence Models C^* and D^* . These models have not previously been applied to predict the velocity field over waves of finite amplitude with nonseparated flows.

Mean velocity profiles are shown in Figures 5.25-5.34 compared with the wavelength averaged profile. The closest measurement to the

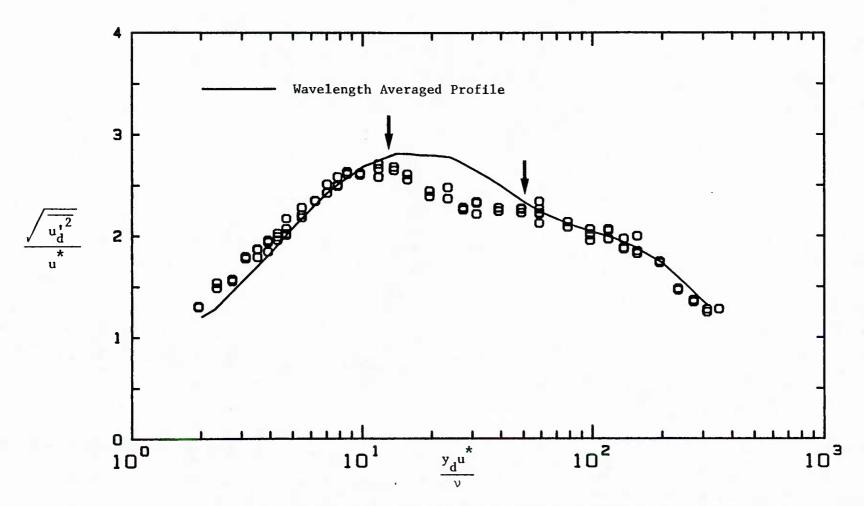


Figure 5.15 Streamwise Intensity Measurements, $x_d/\lambda = 0.1$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

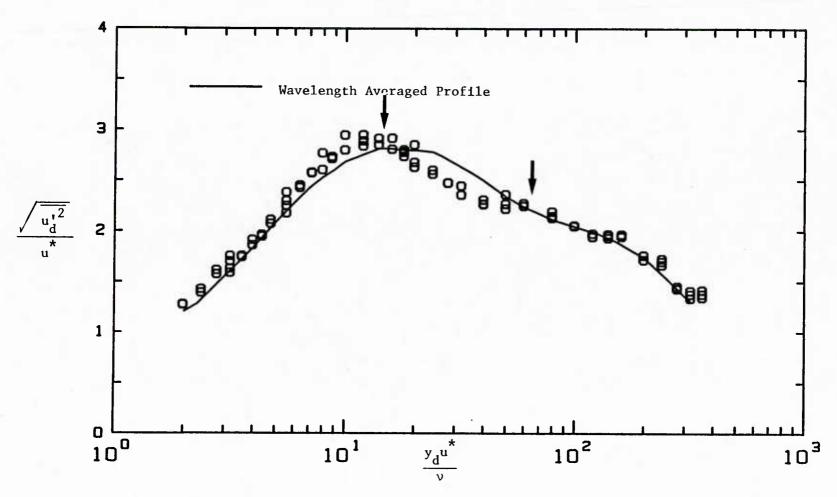


Figure 5.16 Streamwise Intensity Measurements, $x_d/\lambda = 0.2$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

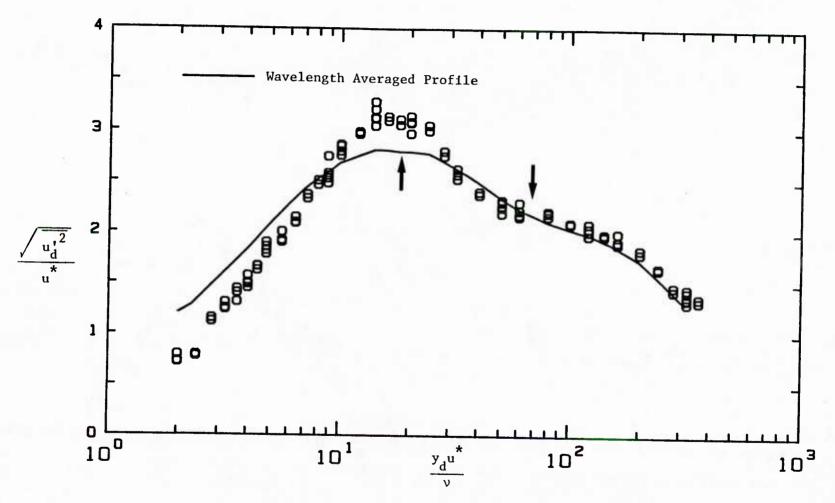


Figure 5.17 Streamwise Intensity Measurements, $x_d/\lambda = 0.3$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

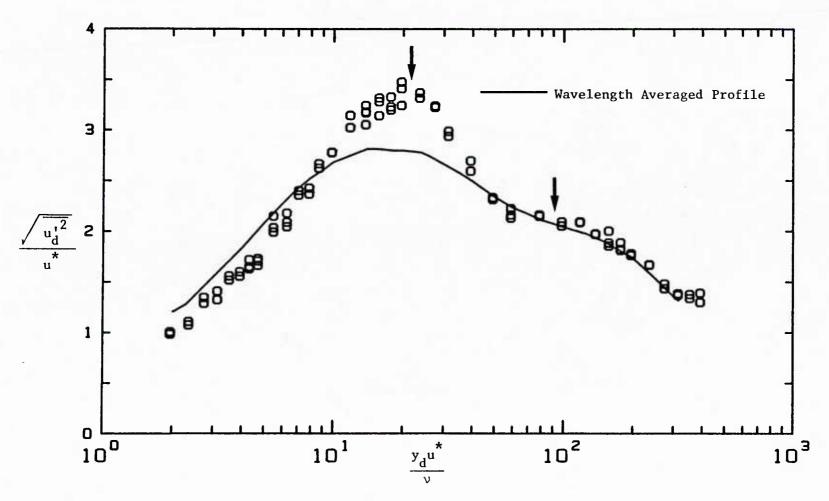


Figure 5.18 Streamwise Intensity Measurements, $x_d/\lambda = 0.4$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

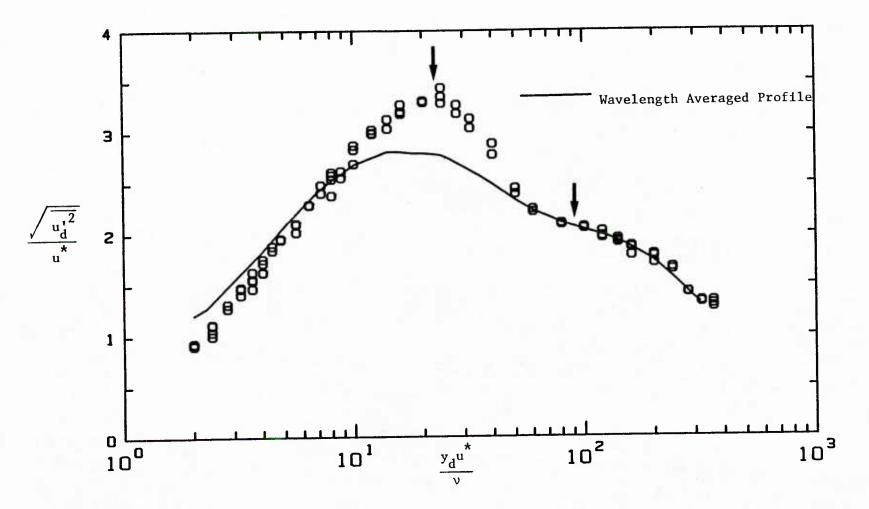


Figure 5.19 Streamwise Intensity Measurements, $x_d/\lambda = 0.5$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

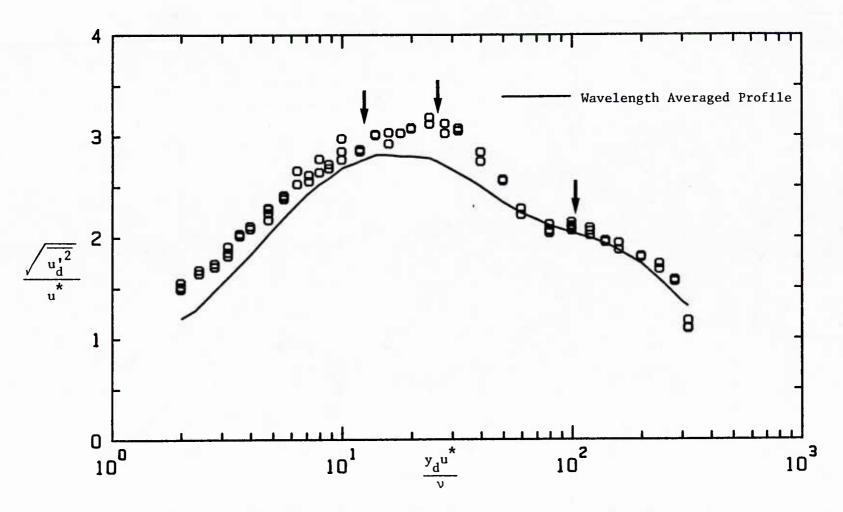


Figure 5.20 Streamwise Intensity Measurements, $x_d/\lambda = 0.6$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

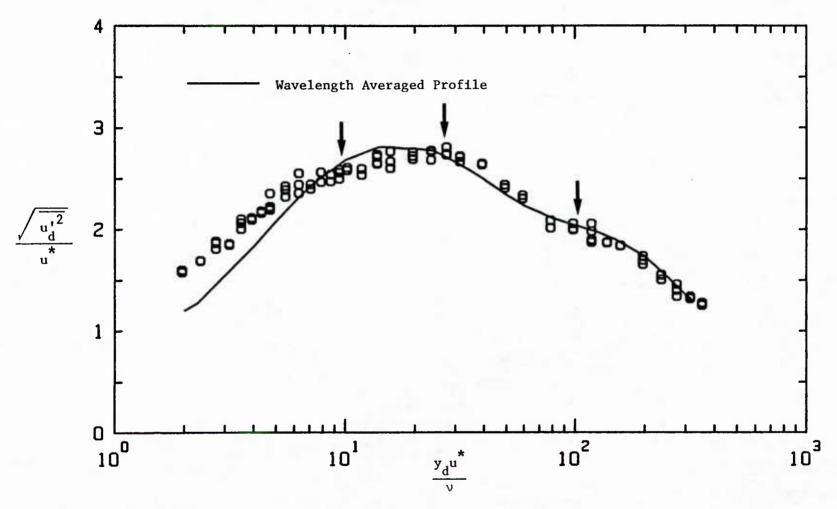


Figure 5.21 Streamwise Intensity Measurements, $x_d/\lambda = 0.7$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

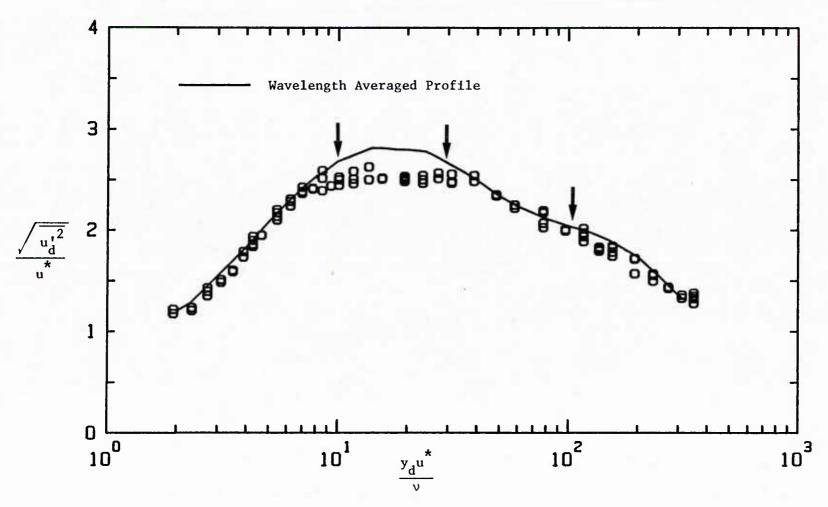


Figure 5.22 Streamwise Intensity Measurements, $x_d/\lambda = 0.8$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

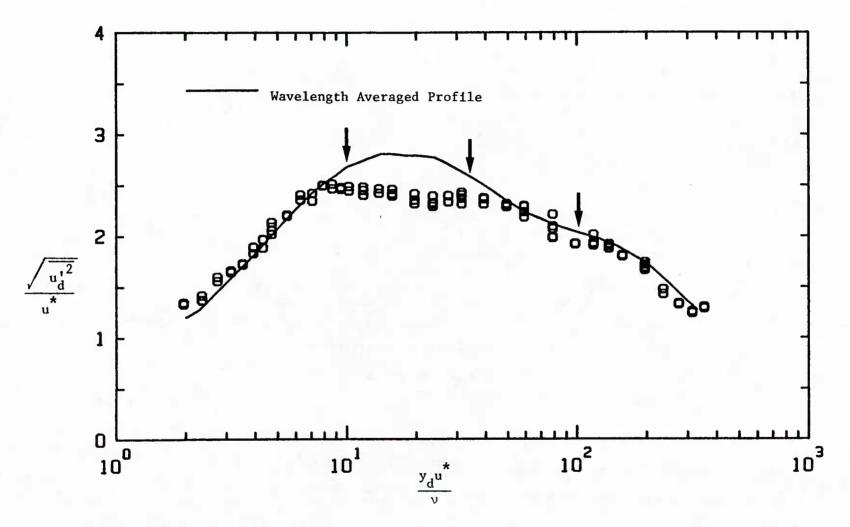


Figure 5.23 Streamwise Intensity Measurements, $x_d/\lambda = 0.9$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

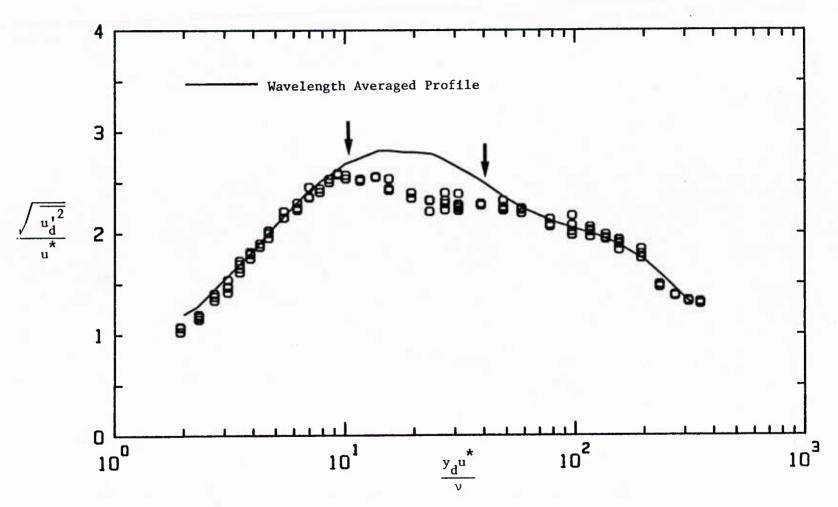


Figure 5.24 Streamwise Intensity Measurements, $x_d/\lambda = 1.0$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

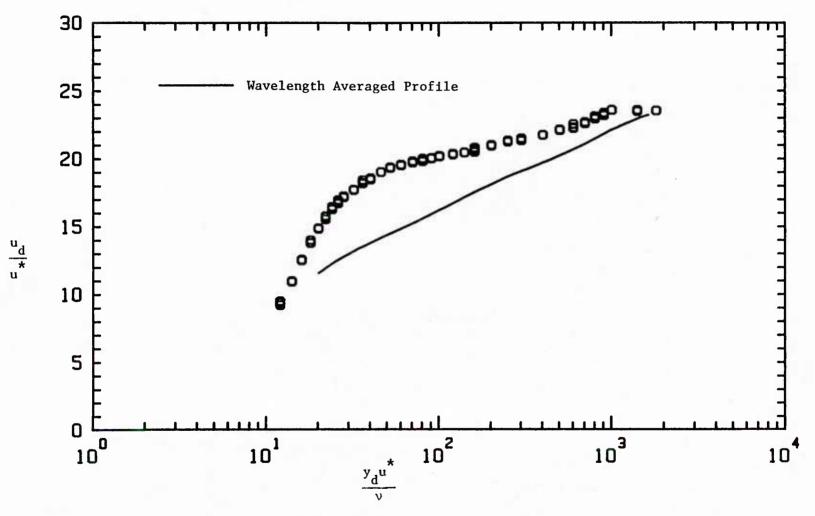


Figure 5.25 Mean Velocity Measurements, $x_d/\lambda = 0.1$, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

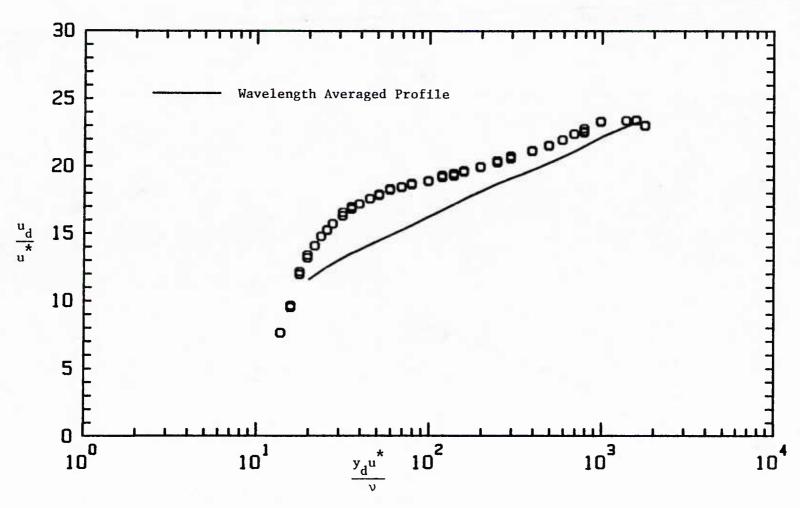


Figure 5.26 Mean Velocity Measurements, $x_d/\lambda = 0.2$, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

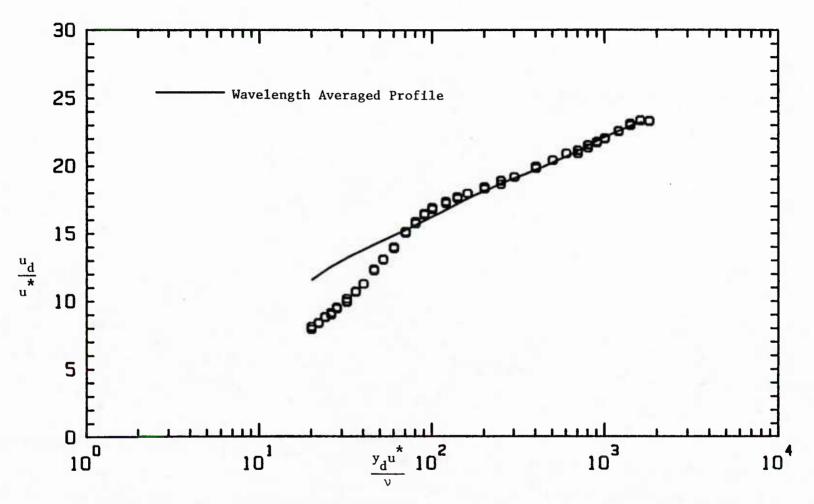


Figure 5.27 Mean Velocity Measurements, $x_d/\lambda = 0.3$, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

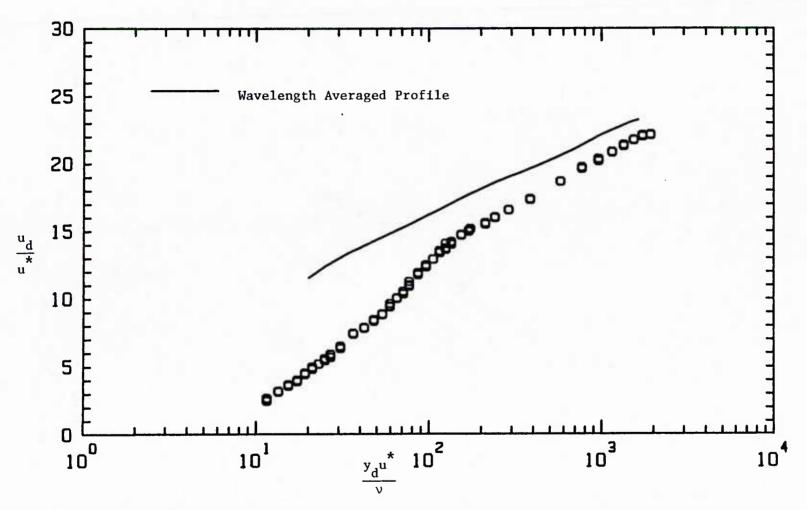


Figure 5.28 Mean Velocity Measurements, $x_d/\lambda = 0.4$, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

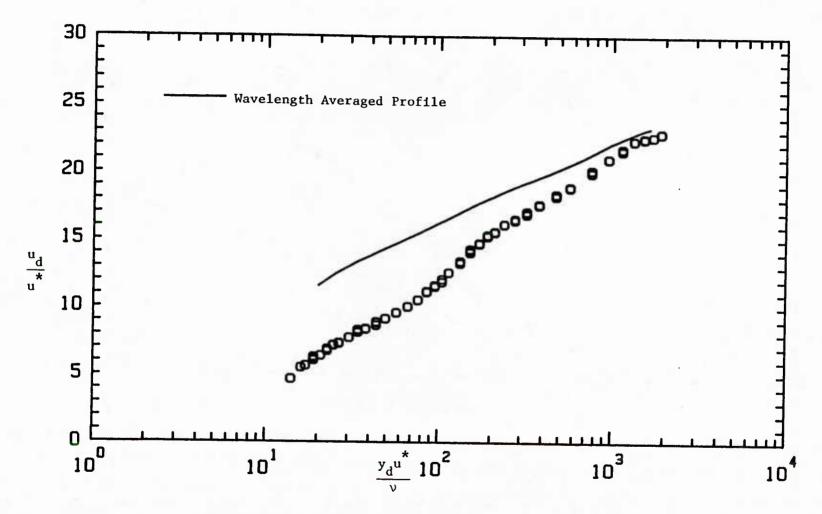


Figure 5.29 Mean Velocity Measurements, $x_d/\lambda = 0.5$, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

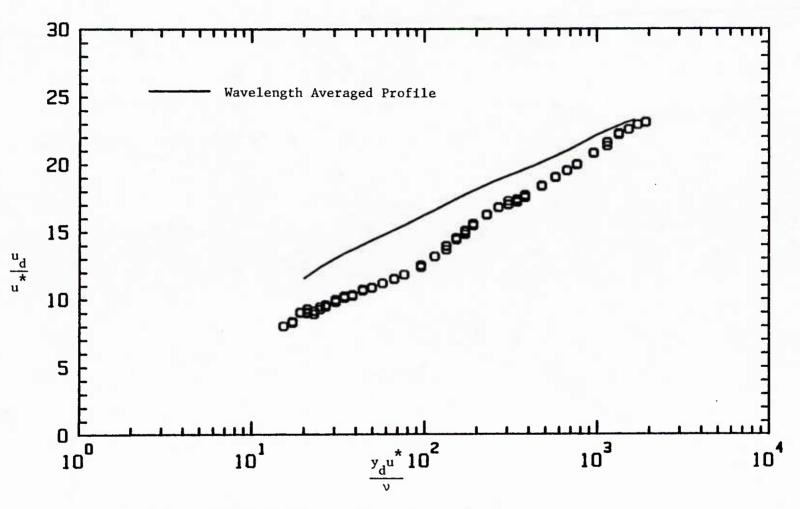


Figure 5.30 Mean Velocity Measurements, $x_d/\lambda = 0.6$, $2a_d/\lambda = 0.05$, $Re_b = 38,000$, $2h_d/\lambda = 1.0$

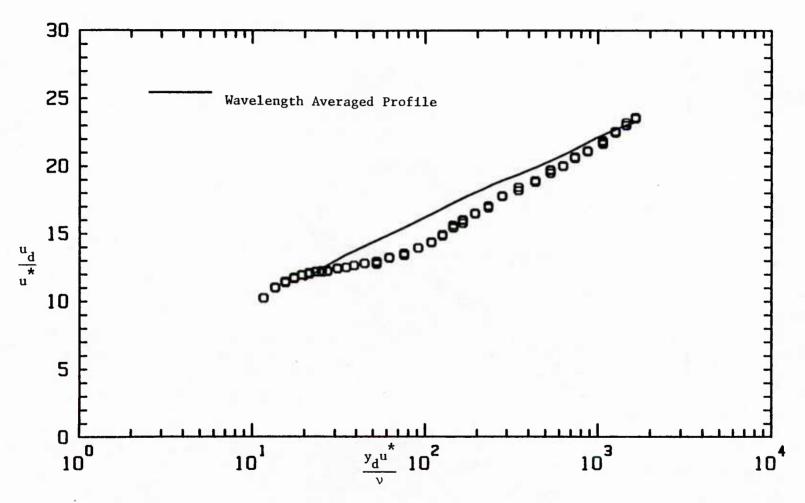


Figure 5.31 Mean Velocity Measurements, $x_d/\lambda = 0.7$, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

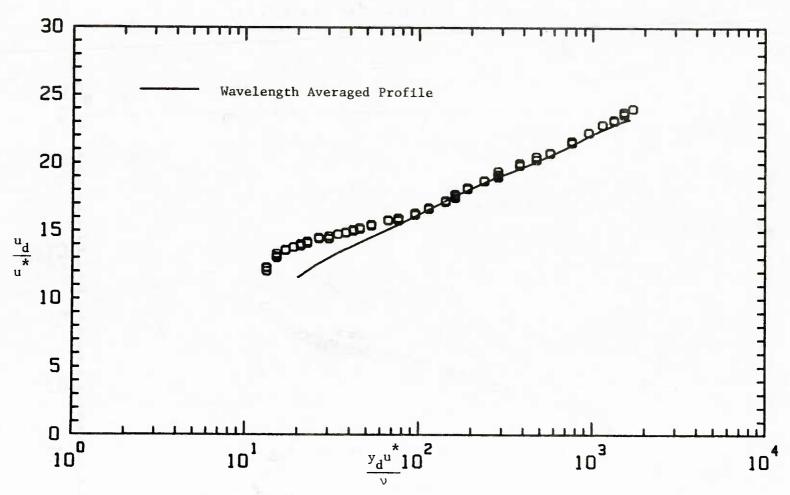


Figure 5.32 Mean Velocity Measurements, $x_d/\lambda = 0.8$, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

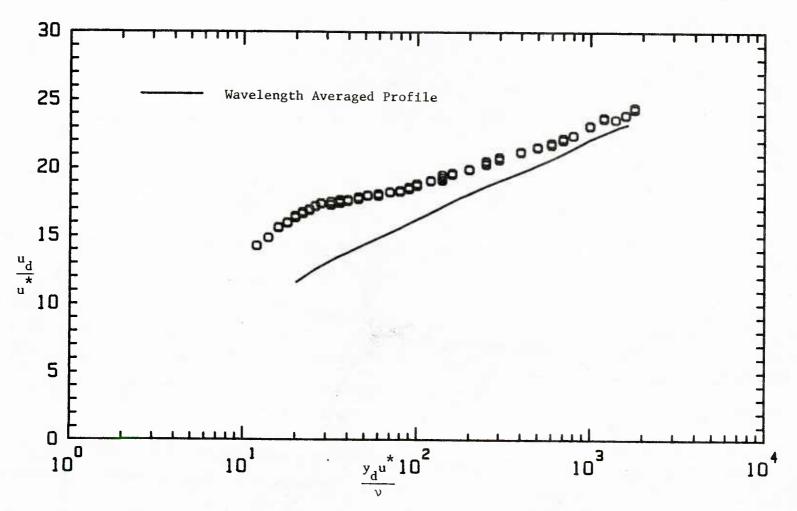


Figure 5.33 Mean Velocity Measurements, $x_d/\lambda = 0.9$, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

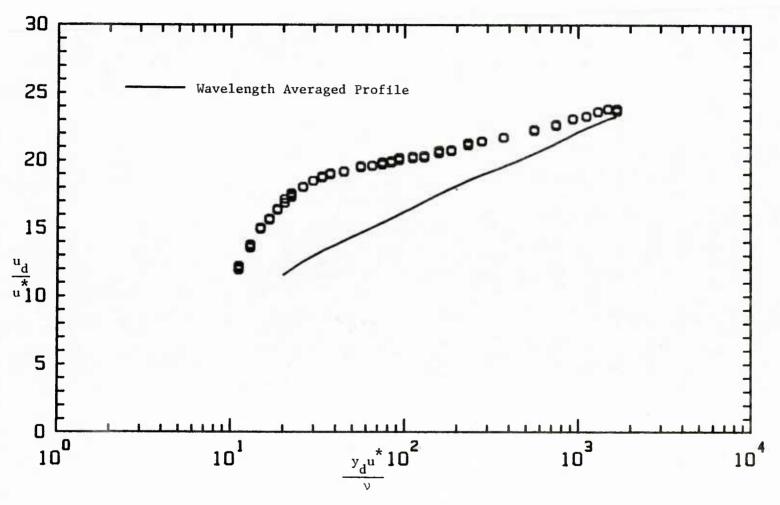


Figure 5.34 Mean Velocity Measurements, $x_d/\lambda = 1.0$, $2a_d/\lambda = 0.05$, $Re_b = 38,000$, $2h_d/\lambda = 1.0$

wave surface is $y_d u^*/v = 10$ and the channel centerline is about $1830 \ y_d u^*/v$ units above the average wave height. The measurement volume diameter was 2.6 wall units. Approximately fifteen data points were obtained within the viscous wall region. The dimensionless wave amplitude, $a_d u^*/v$, is equal to 95.2. The uncertainties in $y_d u^*/v$ and u_d/u^* are about 2.0 and 0.4 dimensionless units respectively. As in the case of the $2a_d/\lambda = 0.03125$ wave, the reference wavelength averaged profile clearly shows that the reaction of the outer flow lags that of the inner flow.

Accurate measurements of the streamwise intensities over the 0.05 wave could not be obtained due to difficulties with the frequency tracker.

The data for the $2a_{\mbox{d}}/\lambda$ = 0.03125 and 0.05 waves is tabulated in Appendix C.

CHAPTER 6

DISCUSSION OF EXPERIMENTAL RESULTS

AND COMPARISON WITH THEORY

In this chapter the velocity measurements presented in the previous chapter are analyzed. When applicable the measurements are compared with predictions from the nonlinear channel code using the turbulence Models C^* and D^* developed by Thorsness, Morrisroe and Hanratty [45] and Abrams [2]. A summary of the major conclusions of this chapter is given in Chapter 7.

I. Wave of Steepness $2a_d/\lambda = 0.03125$

This section discusses the velocity data obtained over the wave of steepness $2a_d/\lambda=0.03125$. The data are presented in several forms which are designed to show the linearity of the flowfield above this wave. The presentation includes wall stress profiles, wavelength averaged velocity profiles, mean velocity profiles, velocity responses at constant heights above the wave, profiles of waveinduced velocity perturbations and streamwise intensities.

A. Wall Stresses

Surface Shear Stress

Zilker [48] used electrochemical techniques to obtain surface shear stress measurements along the $2a_{\rm d}/\lambda=0.03125$ wave with the same flowrate, ${\rm Re}_{\rm b}=6400$, as the velocity measurements presented in this thesis. Data for the eighth and ninth wavelengths are shown in Figure 6.1 The data were fitted to the following two harmonic Fourier series by performing a least squares analysis:

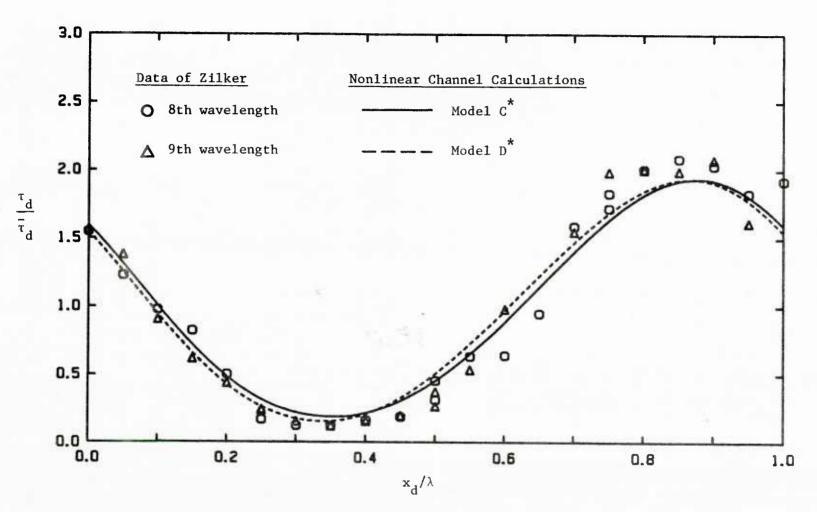


Figure 6.1 Shear Stress Response, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

$$\tau_{d} = \bar{\tau}_{d} + \sum_{n=0}^{N=2} c_{n} \sin\left(\frac{2\pi nx_{d}}{\lambda}\right) + d_{n} \cos\left(\frac{2\pi nx_{d}}{\lambda}\right). \tag{6.1}$$

The amplitudes and phases of the harmonics are defined from equation (6.1) as

$$|\hat{\tau}_{d}|_{n} = \sqrt{c_{n}^{2} + d_{n}^{2}},$$
 (6.2)

and

$$\theta_{\hat{\tau},n} = \tan^{-1} \left(\frac{-d_n}{c_n} \right)$$
 (6.3)

respectively. Table 6.1 shows the results of the Fourier fit. The wavelength averaged shear stress over the eighth and ninth waves, $\bar{\tau}_d/\rho u^{*2}=1$, is the same as would exist if the wave was replaced by a flat surface. The amplitude and phase of the first harmonic are $|\hat{\tau}_d|_1/\rho u^{*2}=0.989$ and $\theta_{\hat{\tau},1}=50.9^\circ$. The uncertainties in these quantities are approximately ± 5 percent and $\pm 5^\circ$ respectively. The ratio of the amplitude of the second harmonic to the first is $|\hat{\tau}_d|_2/|\hat{\tau}_d|_1=0.099$. This indicates a borderline linear-nonlinear response since Zilker, Cook, and Hanratty [49] noted that an observable difference from a sinusoidal variation is obtained when $|\hat{\tau}_d|_2/|\hat{\tau}_d|_1 \geq 0.116$.

The shear stress response predictions of the nonlinear channel analysis with turbulence Models C^* and D^* are also shown in Figure 6.1. A summary of a least squares Fourier analysis of these results is given in Table 6.1. Both models predict a linear response with a

	Data	Model C*	Model D*
$ \hat{\tau}_d^{\dagger} _1^{\rho u^{\star 2}}$	0.989	0.7822	0.7919
θ̂τ,1	50.9	49.8	54.5
$\bar{\tau}_{d}/\rho u^{*2}$	1	0.895	0.893
$ \hat{\tau}_{\mathbf{d}} _2/ \hat{\tau}_{\mathbf{d}} _1$	0.099	0.0808	0.0673

Table 6.1 A Comparison of Surface Shear Stress Measurements with Predictions of Nonlinear Channel Analysis, $2a_{\rm d}/\lambda$ = 0.03125, Re $_{\rm b}$ = 6400, $2h_{\rm d}/\lambda$ = 1.0

wavelength averaged shear stress reduction of about 10 percent.

The amplitude and phase of the first harmonic for both models are within the experimental error of the shear stress measurements.

2. Surface Pressure

The behavior of the surface pressure for $2a_d/\lambda=0.03125$, $2h_d/\lambda=1.0$, and $Re_b=6400$ is shown in Figure 6.2, as predicted by the nonlinear code with turbulence Models C^* and D^* . These discrete profiles were fitted to a Fourier series with two harmonics. The amplitudes and phase angles of the first harmonic are shown in Table 6.2. It should be noted that the local pressure drop due to the channel, from the upstream crest to each x_d/λ position, was added to the points in Figure 6.2 before the Fourier analysis. This ensured that only the wave-induced pressure was considered. A linear pressure drop due to the channel was assumed. In Table 6.2 it can be seen that Models C^* and D^* predict similar amplitudes and phases. No pressure data is available for comparison with the calculations.

3. Drag

The drag of the wave on the fluid can be determined from the distribution of the tangential and normal stresses at the wavy surface. The total horizontal, \mathbf{x}_{d} , component of the force at the surface is given by:

$$F_{x_{d}} = \int_{A'} (p_{d} \sin \beta - \rho \nu \omega_{d} \cos \beta) dA'$$
 (6.2)

where

$$\tan \beta = \frac{dy_d}{dx_d} \tag{6.3}$$

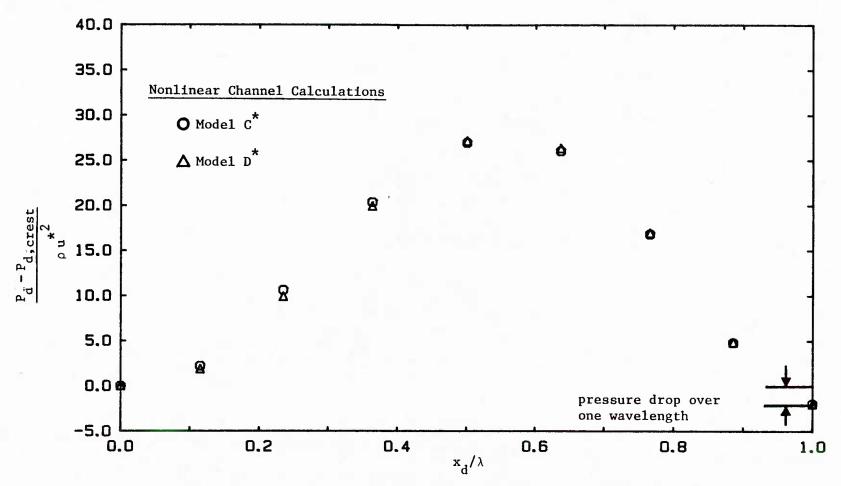


Figure 6.2 Calculated Pressure Response, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

	Model C*	Model D*	
$ \hat{p}_d _1/\rho u^{*2}$	14.38	14.58	
$\theta_{\hat{p},1}$	165.2	163.7	
$ \hat{\mathbf{p}}_{\mathbf{d}} _{2}/ \hat{\mathbf{p}}_{\mathbf{d}} _{1}$	0.0759	0.0644	

Table 6.2 Surface Pressure Results of Nonlinear Channel Analysis, $2a_d/\lambda = 0.03125$, Re_b = 6400, $2h_d/\lambda = d1.0$

is the slope of the wave surface and dA' is an infinitesimal area along the surface. It is convenient to study the components of this force by defining a skin friction drag coefficient, $C_{\rm p}$, and a form drag coefficient, $C_{\rm p}$, as follows:

$$C_{s} = -\frac{1}{\rho u^{*2}} \frac{1}{\lambda} \int_{0}^{\lambda} \rho \vee \omega_{d} \cos \beta \, dS , \qquad (6.4)$$

and

$$c_{p} = \frac{1}{\rho_{u} * 2} \frac{1}{\lambda} \int_{0}^{\lambda} p_{d} \sin \beta \, dS, \qquad (6.5)$$

where dS is a distance along the wave. In the transformed coordinates these coefficients become,

$$C_{s} = -\frac{\alpha_{d}}{\rho u^{*2}} \frac{1}{2\pi} \int_{0}^{2\pi} \rho v \omega_{d} x_{\varepsilon} d\varepsilon, \qquad (6.6)$$

and

$$C_{p} = \frac{\alpha_{d}}{\alpha_{u} \star 2} \frac{1}{2\pi} \int_{0}^{2\pi} p_{d} y_{\varepsilon} d\varepsilon . \qquad (6.7)$$

For a flat surface $C_s = 1$ and $C_p = 0$.

Drag coefficients predicted from the nonlinear channel analysis for the wave of steepness $2a_d/\lambda=0.03125$ with $Re_b=6400$ are shown in Table 6.3. It can be seen that with turbulence Models C^* and D^* there is approximately a 10 percent decrease in the skin friction drag

Turbulence Model	C _s	C _p	$\frac{C_{s}}{C_{s} + C_{p}}$	$\frac{C_{p}}{C_{s} + C_{p}}$	C _s + C _p
c*	0.895	0.190	0.825	0.175	1.09
D*	0.893	0.212	0.808	0.192	1.11

measurements of Zilker $C_s = 1.0 \pm 0.05$

Table 6.3 Drag Coefficients,
$$2a_d/\lambda = 0.03125$$
, $Re_b = 6400$, $2h_d/\lambda = 1.0$

relative to a flat surface. However, the total drag for the wave surface increases by about 10 percent due to an increase in form drag. The form drag represents almost 20 percent of the total drag for both models.

Experimentally, Zilker et al. [49] found that $C_s = 1.0 \pm 0.05$ for the above wave and flow conditions. No pressure measurements are available to determine the form drag coefficient.

B. Wavelength Averaged Mean Velocity

An average representation of the flowfield over one wavelength of the wave with $2a_d/\lambda=0.03125$ can be obtained by averaging the ten velocity profiles in Figures 5.5-5.14. The resulting wavelength averaged velocity profile is shown in Figure 6.3. The ten profiles used to construct this average are equally spaced profiles of the streamwise velocity with distances measured vertically from the wave surface as shown in Figure 6.4 for the position $x_d/\lambda=0.2$. Predictions of the same type of wavelength averaged profile by the nonlinear channel code with turbulence Models C^* and D^* are also shown in Figure 6.3. No differences between Model C^* and D^* are observed. The wavelength averaged data are slightly higher than the theory. This difference is not believed to be significant because it is within the experimental error of the velocity measurements and within errors in the friction factor data of Thorsness [44] which were used to normalize the measurements.

A second type of wavelength averaged velocity profile above the wave surface was calculated from the theoretical results. In this case the profiles to be averaged are formed along the eight

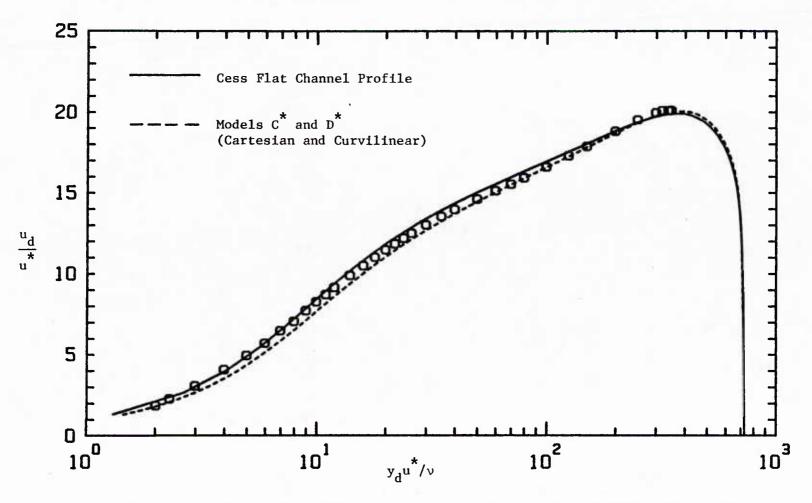


Figure 6.3 Wavelength Averaged Velocity Profiles, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

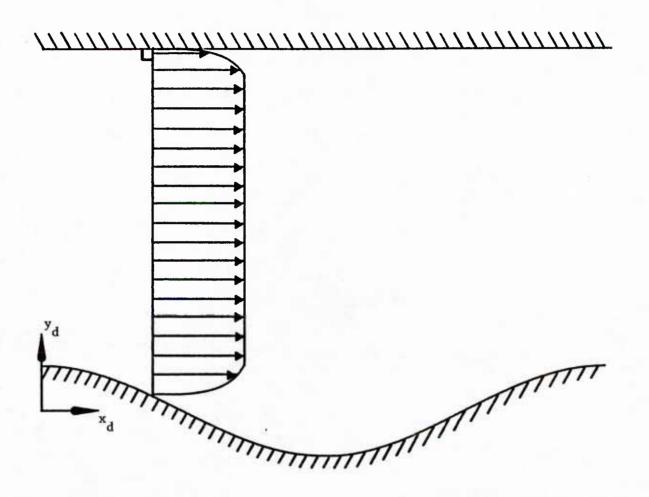


Figure 6.4 Typical Velocity Profile Used to Construct Wavelength Averaged Profile Along Cartesian Coordinates, $x_d/\lambda = 0.2$ (amplitude exaggerated)

curvilinear coordinate lines of constant ε . Distances from the wave surface are measured along these lines. All velocities are parallel to lines of constant n. That is, only velocity components in the ε -direction are considered. As an example of such a profile, Figure 6.5 shows the velocity profile along $\varepsilon = \pi/4$. It is believed that a profile averaged along such curves is the proper wavelength averaged profile to compare with the flat channel profile. This is because profiles along the curvilinear coordinates reflect the geometry of the surface in contact with the flow. The flat channel profile is included in Figure 6.3 It was found that the wavelength averaged profile along curvilinear coordinates is nearly identical to the average profile in Cartesian coordinates. This is expected for waves of small steepness.

C. Mean Velocity Profiles

The mean velocity profiles at the ten x_d/λ positions are compared in Figures 6.6-6.10 with results of the nonlinear channel code using turbulence Models C^* and D^* . There are no significant differences between the two models for a wave with $2a_d/\lambda=0.03125$ and $Re_b=6400$. Reasonably good agreement between the experimental profiles and the models is observed. The most important result is that Model C^* , which is a straightforward application of the Cess eddy viscosity profile for a flat channel, predicts a good first approximation of the velocity field over a wave. A shortcoming of both Models C^* and D^* is that the models predict smaller deviations about the wavelength averaged profile than is observed.

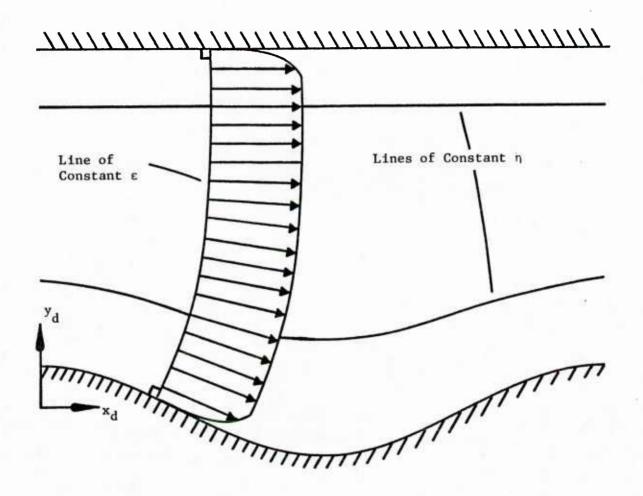


Figure 6.5 Typical Velocity Profile Used to Construct Wavelength Averaged Profile Along Curvilinear Coordinates, $\varepsilon=\pi/4$ (amplitude exaggerated)

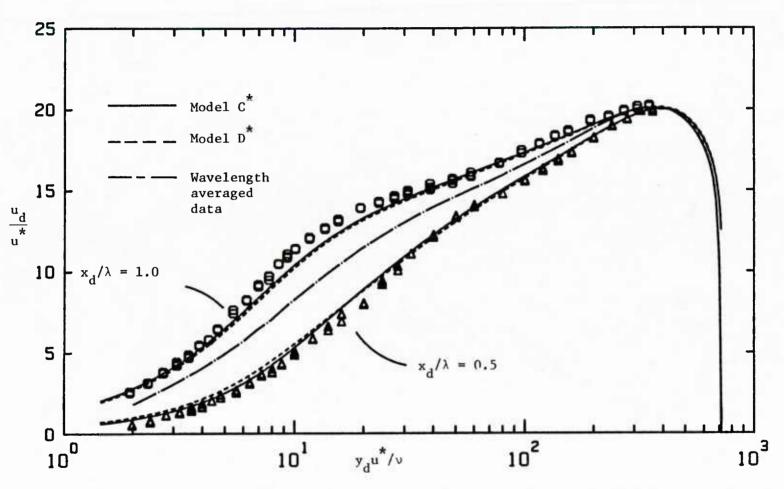


Figure 6.6 Comparison of Mean Velocity Measurements with Channel Calculations, $x_d/\lambda = 0.5$, 1.0, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

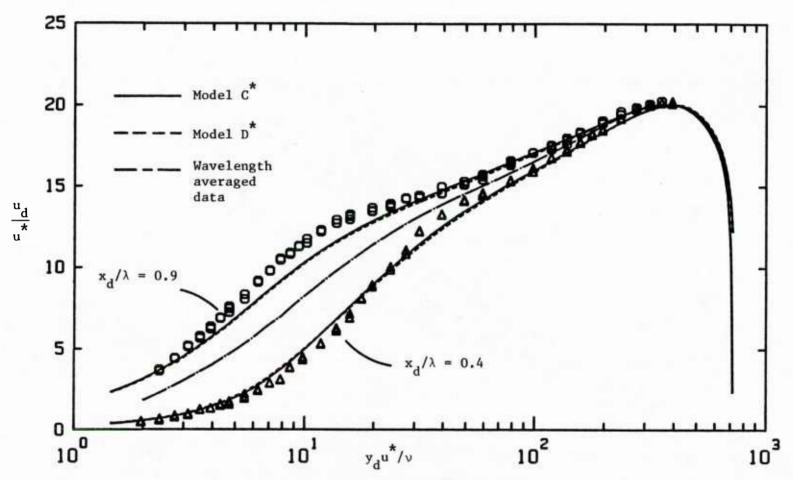


Figure 6.7 Comparison of Mean Velocity Measurements with Channel Calculations, $x_d/\lambda = 0.4$, 0.9, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

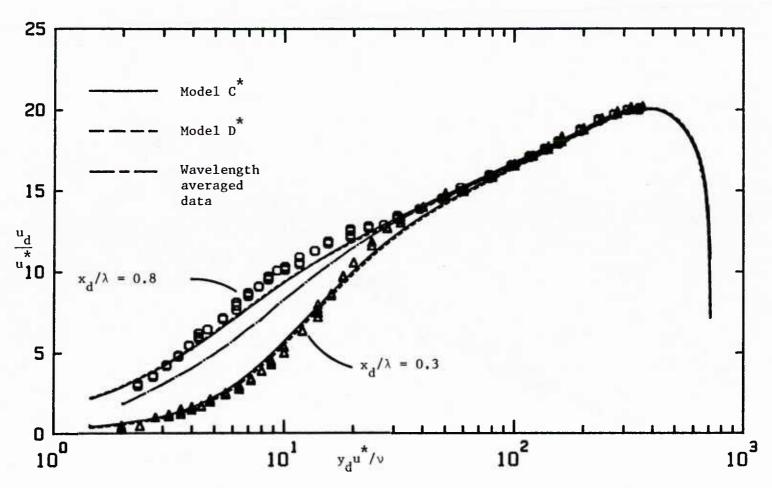


Figure 6.8 Comparison of Mean Velocity Measurements with Channel Calculations, x_d/ λ = 0.3, 0.8, 2a_d/ λ = 0.03125, Re_b = 6400, 2h_d/ λ = 1.0

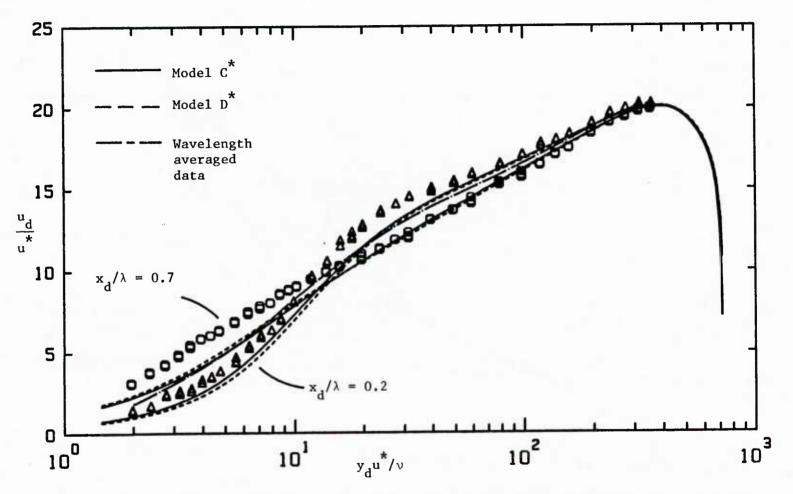


Figure 6.9 Comparison of Mean Velocity Measurements with Channel Calculations, $x_d/\lambda = 0.2$, 0.7, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

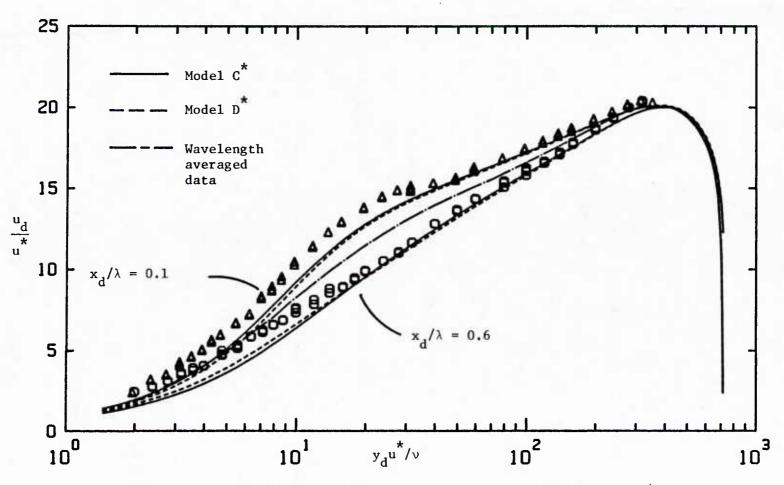


Figure 6.10 Comparison of Mean Velocity Measurements with Channel Calculations, $x_d/\lambda = 0.1$, 0.6, $2a_d/\lambda = 0.03125$, Re b = 6400, $2h_d/\lambda = 1.0$

The calculated velocity profiles were found to be independent of the type of distance y_d^{\prime} used in the Cess equation.

D. Mean Velocity Responses at Constant Heights above Wave

The entire time-averaged flowfield above the wave can be studied by plotting velocities at constant vertical heights above the surface. This is shown in Figure 6.11 with constant $y_d u^*/v$ values ranging from 5 to 300. It can be seen that the velocity field is perturbed approximately according to the shape of the wave. That is, a near linear response is observed with an associated phase and amplitude at each $y_d u^*/v$ value.

The curves in Figure 6.11 were least squares fitted to a two harmonic Fourier series to obtain quantitative information about the linearity of this flowfield. The ratio of the amplitudes of the second to first harmonics, $|\hat{\mathbf{u}}_{\mathbf{d}}|_2/|\hat{\mathbf{u}}_{\mathbf{d}}|_1$, is shown in Figure 6.12 as a function of distance above the wave surface. The maximum ratio of 0.17 indicates a weakly nonlinear response. It is suspected that this ratio is slightly higher than the true ratio because any scatter in the data of Figure 6.11 is interpreted as nonlinearities by the Fourier analysis. Models \mathbf{C}^* and \mathbf{D}^* underpredict the observed nonlinearities.

The amplitudes of the first and second harmonics of the velocity response are shown in Figure 6.13. Here it is also clear that the first harmonic dominates the second harmonic at all y_d^*/v values. Both amplitudes are zero at the wall due to the no slip condition. The amplitude of the first harmonic increases rapidly to a maximum

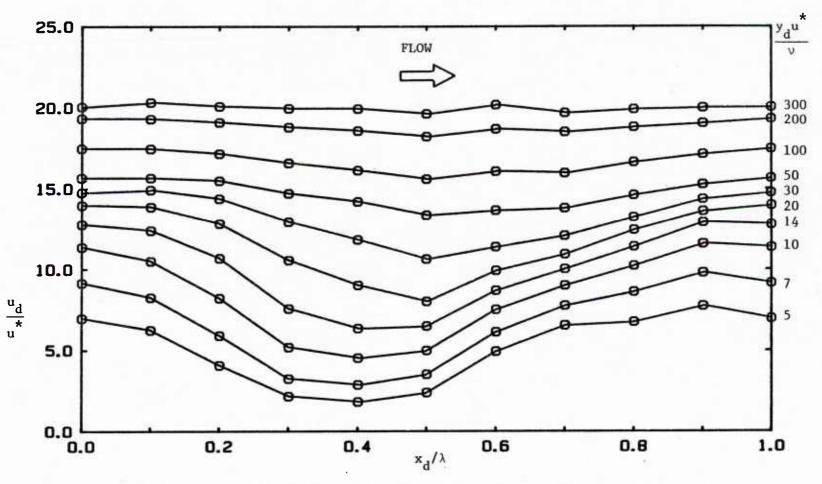


Figure 6.11 Mean Velocity Responses at Constant Heights above Wave Surface, $2a_d/\lambda = 0.0312$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

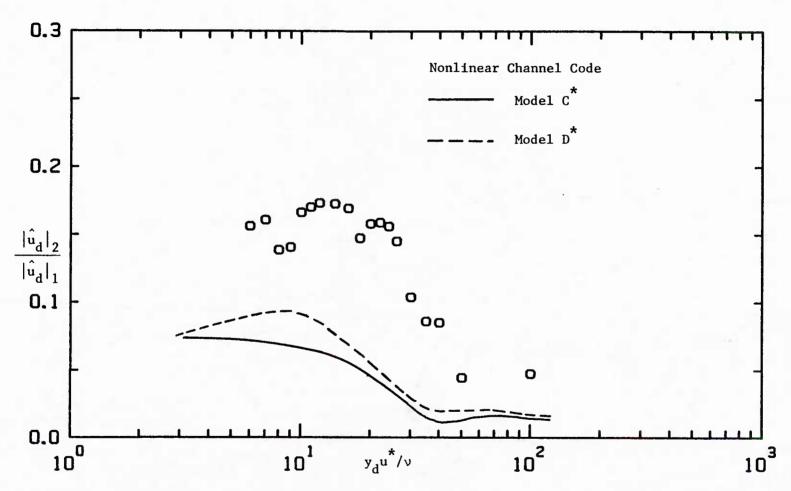


Figure 6.12 Velocity Amplitude Ratio of Second to First Harmonics, $2a_{\rm d}/\lambda$ = 0.03125, Re $_{\rm b}$ = 6400, $2h_{\rm d}/\lambda$ = 1.0

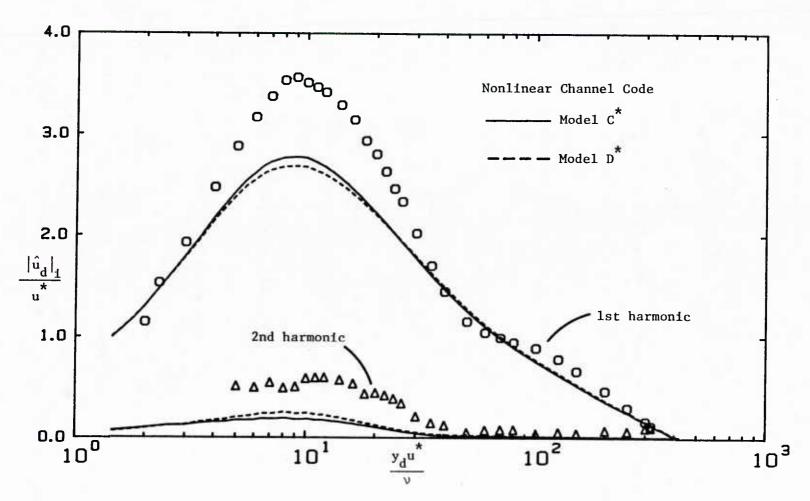


Figure 6.13 Amplitudes of First and Second Harmonics of Velocity Response, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

value of 3.6 at y_du^*/v equal to 9. This is also the approximate location of the maximum nonlinearity. Figure 6.14 shows the response at $y_du^*/v = 9$ where it is Fourier fitted to one and two harmonics. Above $y_du^*/v = 9$ the amplitude of the first harmonic decreases rapidly to about the edge of the viscous wall region and then gradually decreases to zero near the center of the channel, $y_du^*/v \cong 365$. Disturbances are small far from the wave surface because here the fluid cannot "feel" the presence of the wave below it.

Nonlinearities also become negligible near the edge of the viscous wall region. The velocity response at $y_d^*/\nu = 40$ is shown in Figure 6.15. Here it is seen that the Fourier fits to one and two harmonics are almost indistinguishable.

The amplitude predictions of Models C* and D* are also shown in Figure 6.13. Both models predict nearly identical first and second harmonic amplitudes with the same general shape as the data. However, the models significantly underestimate the amplitude observations for $4 < y_d u^*/v < 30$.

It should be noted here that there are turbulence models which predict larger velocity perturbations about the wavelength average than Models C* and D*. Abrams [2] used a linear analysis to investigate the effect of a quasilaminar model on the flowfield over a wave of infinitesimal amplitude in a boundary layer. A quasilaminar model assumes that all wave-induced turbulent quantities are zero. The computer code of Abrams was run with quasilaminar, C* and D* turbulence models for $\alpha_{\rm d} v/u^* = 0.008$ (equivalent to Re = 6400).

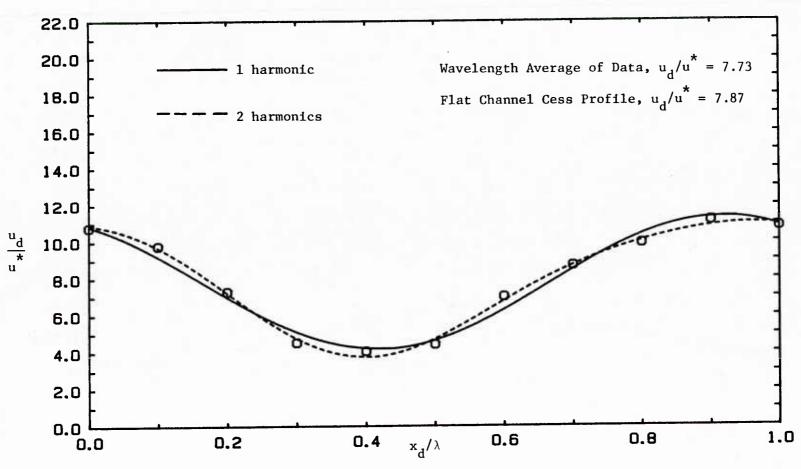


Figure 6.14 Velocity Response at $y_d u^*/v = 9$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

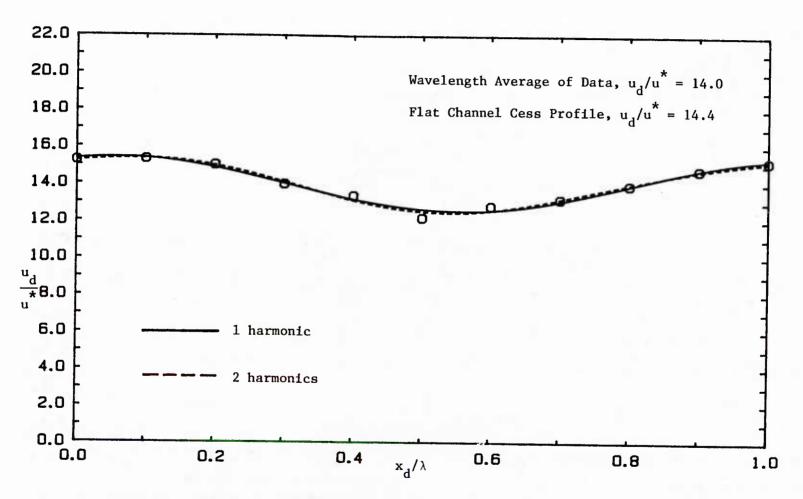


Figure 6.15 Velocity Response at $y_d u^*/v = 40$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

It was found that the quasilaminar model predicts a maximum wave-induced amplitude which is 30 percent and 37 percent higher than Models C* and D* respectively. (Profiles of velocity perturbation amplitudes calculated from the linear analysis are given in Appendix D.) However, the quasilaminar model was not adapted to the nonlinear analysis for two reasons. First, Thorsness et al. [45] and Abrams and Hanratty [4] have shown that this model cannot predict the surface shear stress over a wide range of flowrates. The model is valid only for very large values of the dimensionless wavenumber, $\alpha_{\bf d} v/u^*$. Secondly, the quasilaminar model predicts only perturbations and can strictly be applied only to waves of infinitesimal amplitudes for which the wavelength averaged velocity is known.

The quasilaminar model is mentioned above because the findings of Abrams suggest that a very simple model, with smaller wave-induced variations of the turbulence outside the near wall region than Models C^* and D^* , may provide a better fit to the velocity field.

The phase angle of the first harmonic of the velocity response, $\theta_{\hat{\mathbf{u}},1}$, is shown in Figure 6.16 as a function of $y_d\mathbf{u}^*/\nu$. This phase angle is the shift of the maximum velocity upstream of the crest. The phase angle is a maximum at the wave surface and decreases rapidly within the viscous wall region. A drop of about 20° in the phase is seen between $y_d\mathbf{u}^*/\nu=2$ and 10. A minimum value of -25° is observed at about $y_d\mathbf{u}^*/\nu=50$ and the phase tends toward zero far from the wall where the influence of the wave on the fluid is not felt.

A comparison of $\theta_{\hat{u},1}$ predicted from turbulence Models C and D is also shown in Figure 6.16. Good agreement is observed with

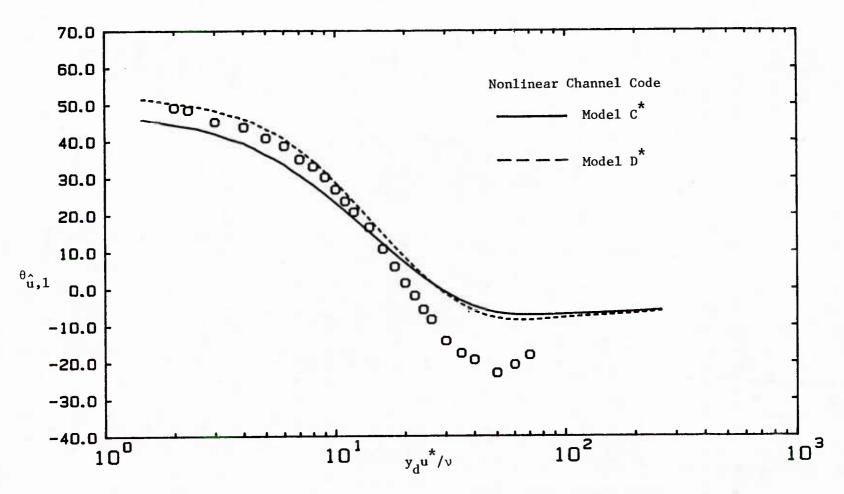


Figure 6.16 Phase Angle of First Harmonic of Velocity Response, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

both models for $y_d^*u^*/v < 20$. Neither model fits the data well outside the viscous wall region. However, the data may be in error here. It is not possible to determine accurately phase angles in this region because scatter in the data becomes comparable to the amplitude of the velocity response for large $y_d^*u^*/v$.

E. Prediction of Surface Shear Stress Response from LDV Measurements

It is of interest to know whether the LDV data for $2a_d/\lambda = 0.03125$ and $Re_b=6400$ are close enough to the wave surface to obtain the surface shear stress response. This subsection discusses determination of the amplitude and phase of the wall shear stress from the velocity measurements.

In Figure 6.13 the slope of $|\hat{\mathbf{u}}_{\mathbf{d}}|_1$ versus $\mathbf{y}_{\mathbf{d}}\mathbf{u}^*/\mathbf{v}$ at the wave surface is equal to the amplitude of the wave-induced shear stress. This quantity, $|\hat{\tau}_{\mathbf{d}}|_1$, can be determined from the velocity data provided there are points close enough to the surface to extrapolate linearly. Figure 6.17 shows a comparison of the slope obtained by extrapolating the data with $|\hat{\tau}_{\mathbf{d}}|_1$ from the electrochemical measurements of Zilker et al. [49]. It is found that the velocity data are not close enough to the wave surface to obtain the shear stress amplitude. This implies that the linear region in the velocity profiles does not extend to the closest measurements at $\mathbf{y}_{\mathbf{d}}\mathbf{u}^*/\mathbf{v}$ equal to two. A flat channel profile, by contrast, has a linear region that extends to a $\mathbf{y}_{\mathbf{d}}\mathbf{u}^*/\mathbf{v}$ value of five. The closeness of the wave-induced velocity perturbations to the wall indicates that both LDV and electrochemical techniques are necessary to study the near wall region. This point is illustrated in Figure 6.18 where mean velocity data at $\mathbf{x}/\lambda = 0.3$ are compared

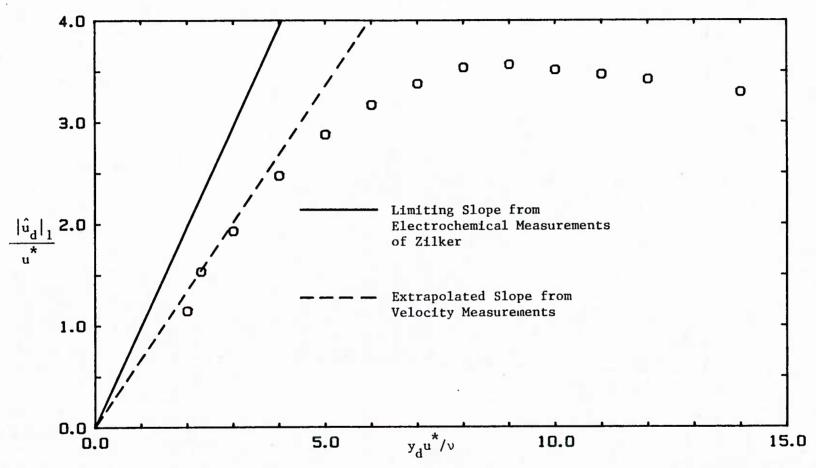
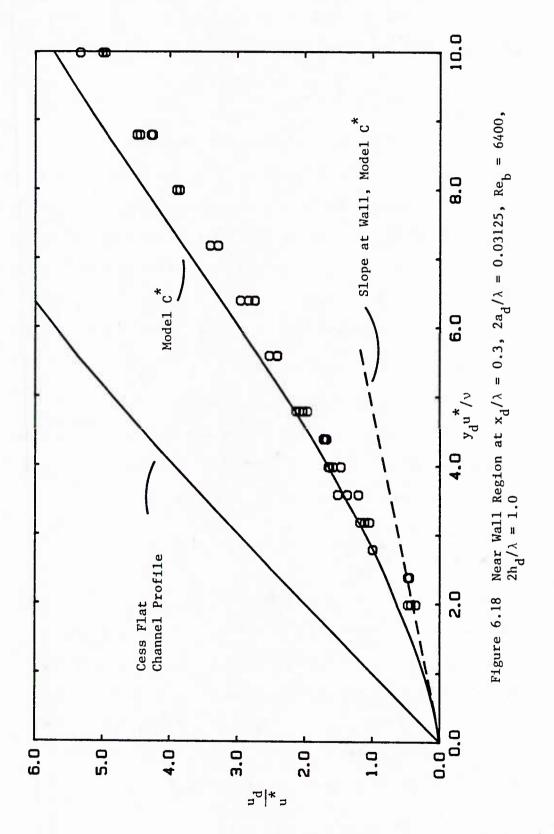


Figure 6.17 Comparison of Shear Stress Amplitude from Electrochemical and Extrapolated Velocity Measurements, $2a_d/\lambda = 0.03125$, Re_b = 6400, $2h_d/\lambda = 1.0$



with the Cess flat channel profiles and the prediction of Model C*. Model C*, which was shown in Section I.A.1. to provide a good fit to the surface shear stress, is linear only to about $y_d^{*}v_d^{*}$ equal to one at this position.

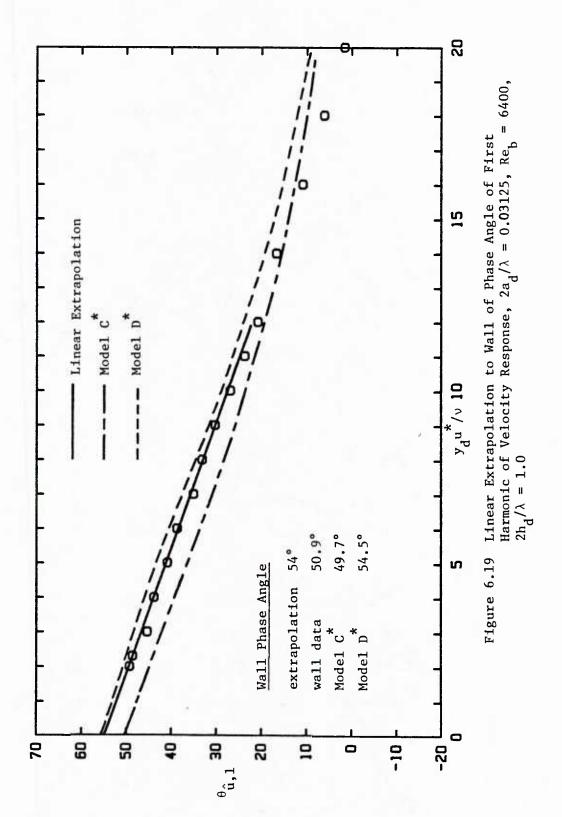
The phase angle of the velocity at the wave surface is equal to the phase angle of the shear stress. The data in Figure 6.16 can be extrapolated linearly to the wall to obtain a shear stress phase angle, $\theta_{\hat{\tau},1}$, of 54 degrees. See Figure 6.19. The extrapolated and calculated phases are within the experimental error of the electrochemical measurements of Zilker et al. Thus for a wave with $2a_d/\lambda = 0.03125$ and $Re_b = 6400$, IDV techniques can be used to measure the phase angle, but not the amplitude, of the surface shear stress response.

F. Wave-Induced Velocity Perturbations

The flowfield over a wave surface may be thought of as a waveinduced perturbation about the wavelength averaged profile. Thus the flowfield is given as,

$$u_d(x_d, y_d) = \overline{U}_d(y_d) + \hat{u}_d(x_d, y_d)$$
 (6.2)

where $\hat{u}_d(x_d, y_d)$ is the perturbation and $u_d(x_d, y_d)$ and $\overline{U}_d(y_d)$ are the total and wavelength averaged velocities respectively. Measured profiles of $\hat{u}_d(x_d, y_d)$ are shown in Figures 6.20-6.24. By presenting only the perturbations, rather than the total velocity profiles, the effect of the wave on the mean flowfield is isolated. The profiles were obtained by subtracting the experimental wavelength averaged profile in Figure 6.3 from the total velocity profiles in Figures 5.5-5.14.



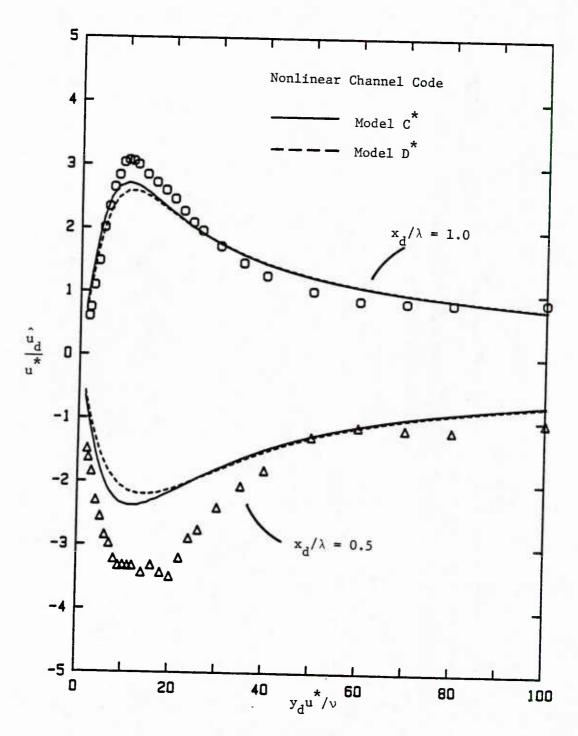


Figure 6.20 Wave-Induced Velocity Perturbations, $x_d/\lambda = 0.5$, 1.0, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

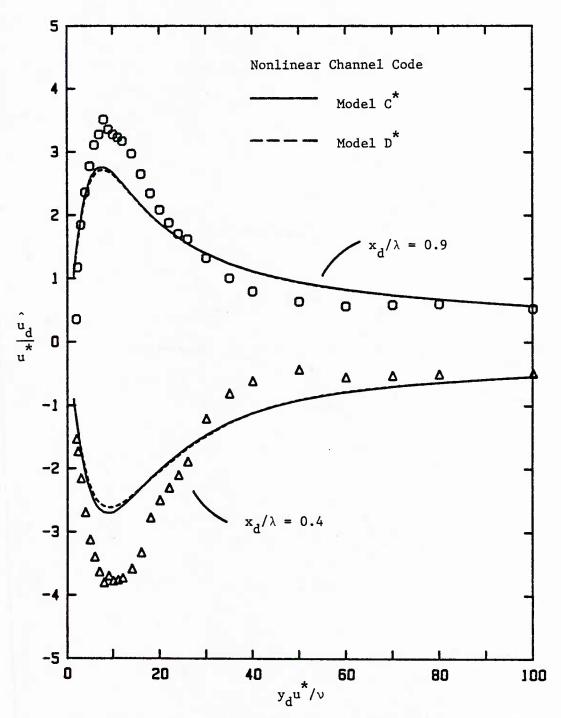


Figure 6.21 Wave-Induced Velocity Perturbations, $x_d/\lambda = 0.4$, 0.9, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

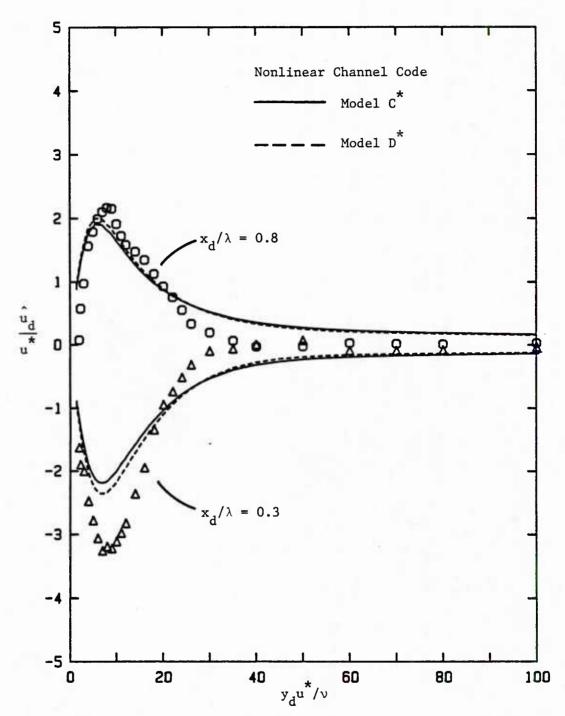


Figure 6.22 Wave-Induced Velocity Perturbations, $x_d/\lambda = 0.3$, 0.8, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

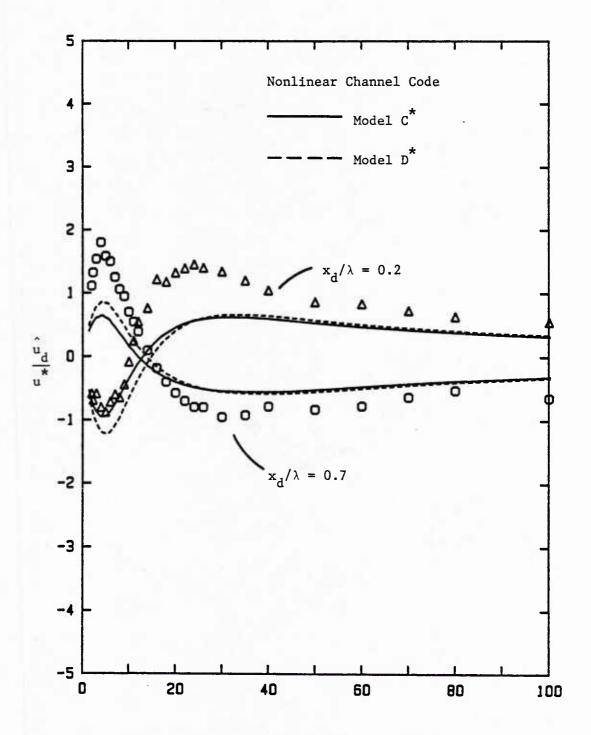


Figure 6.23 Wave-Induced Velocity Perturbations, $x_d/\lambda = 0.2$, 0.7, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

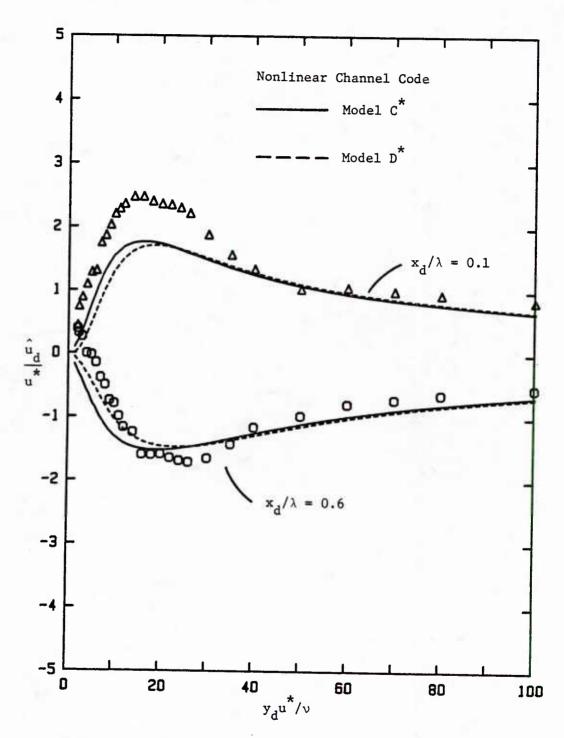


Figure 6.24 Wave-Induced Velocity Perturbations, $x_d/\lambda = 0.1$, 0.6, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

The profiles of the wave-induced velocity perturbations are given in pairs at positions 180° apart along the wave surface. Abrams [2] has shown that for a perfectly linear response the perturbations are equal in magnitude and opposite in sign at half wavelength intervals. The data show that to a first approximation this characteristic of linear behavior is observed. However, small deviations can be seen. For instance, the magnitude of the perturbations at x_d/λ = 0.3, 0.4, and 0.5 are larger than at the corresponding 180° distant positions of x_d/λ = 0.8, 0.9, and 1.0. The fluid in the trough region is moving slower than is expected from linear theory. This is not surprising since the conditions $2a_d/\lambda = 0.03125$ and $Re_b = 6400 (\alpha_d v/u^* = 0.008)$ place this set of data close to the separated region. See Figure 3.1. Although no instantaneous separation was observed, the flow may be undergoing "incipient" separation. The location of this pre-separation behavior is consistent with the measurements of Kuzan [26] which show that separation first appears at approximately $x_d/\lambda = 0.4$.

A comparison of the data with predictions from the nonlinear channel code each using turbulence Models C and D is also shown in Figures 6.20-6.24. Here the calculated wavelength averaged profiles are used as the mean flowfield. Both models underpredict the disturbances in the viscous wall region. This is expected from previous comparisons of the theory with mean velocity profiles (Section I.C.) and the results of the Fourier analysis of the velocity field (Section I.D.).

G. Streamwise Intensities

The wavelength averaged profile of the streamwise intensity is shown in Figure 6.25. As with the case of the mean velocities, the intensities are averaged at constant heights measured vertically above the wave surface. Intensity measurements obtained over a flat surface in the same channel are also shown in Figure 6.25. A slight increase above flat channel intensities is observed in the viscous wall region.

Figure 6.26 gives all ten intensity profiles in Figure 5.15-5.24 plotted together. This figure shows the "envelope" of perturbation about the wavelength averaged profile. A maximum perturbation of ± 20 percent about the average occurs at $y_d^*/v = 24$. The majority of the disturbances are found within the viscous wall region.

The observed deviations from the wavelength averaged intensity profile can be qualitatively explained in terms of pressure gradient effects on the turbulence. Because of the compression of the streamlines at the wave crest and the spreading of the streamlines at the trough the fluid pressure varies along the wave surface. This gives rise to a periodically varying pressure gradient along the wave surface that is roughly equal to that predicted by inviscid Kelvin-Helmholtz theory. That is, the pressure gradient is positive for $0 \le x_d/\lambda \le 0.5$ and negative for $0.5 \le x_d/\lambda \le 1.0$. Experimental studies [6,7,22,23,28,29,31] of turbulent boundary layers in slowly converging or diverging sections reveal that strong negative (favorable) pressure gradients cause a damping of turbulence close to the wall, and that positive (adverse) pressure gradients have

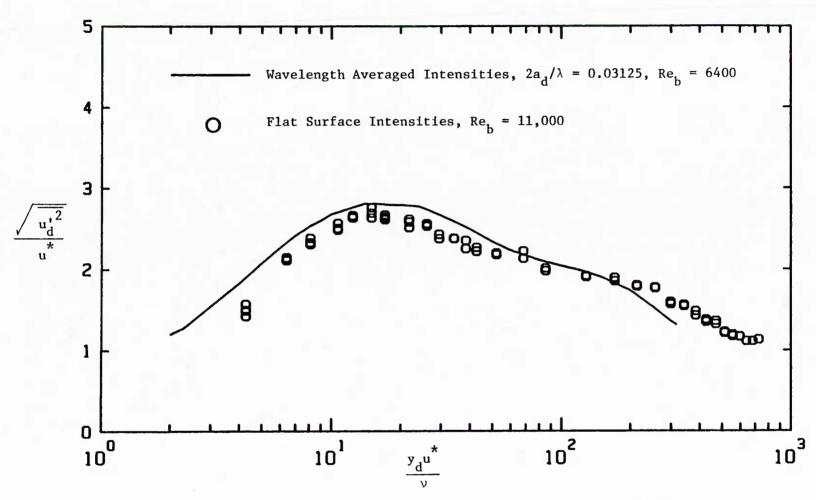


Figure 6.25 Comparison of Wavelength Averaged Intensity Profile with Flat Surface Intensity Profile

Legend for Figure 6.26

x_d/λ		Symbol
0.1		
0.2		◁
0.3	18	\triangleright
0.4		Δ
0.5		∇
0.6		\Diamond
0.7		M
0.8		+
0.9		>-
1.0		0

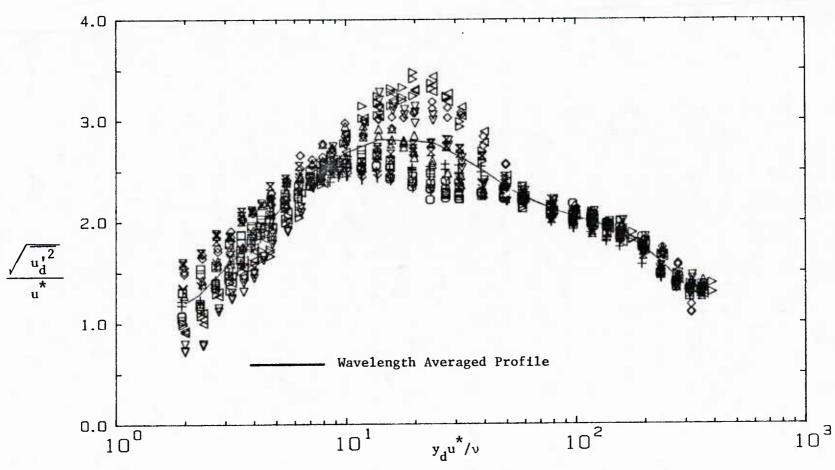


Figure 6.26 Envelope of Perturbations about Wavelength Averaged Intensity, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

just the opposite effect. These observations are confirmed by calculations of Finnicum [19] involving simple eddy modeling of the viscous wall region with constant pressure gradients. One might look for a similar phenomenon to occur at wave surfaces. However, in this case the pressure gradient is varying rapidly in the flow direction and its effect might not be as great as would be observed for an equilibrium flow because the flow does not adjust instantaneously.

The calculations in Section I.A. indicate that for $2a_d/\lambda=0.03125$ and $Re_b=6400$ the pressure field near the wave surface is shifted only slightly (~15°) downstream. Thus if the flow were to adjust instantaneously to the local pressure gradients, an enhancement and dampening of turbulence would be observed at approximately $0.0 \le x_d/\lambda \le 0.5$ and $0.5 \le x_d/\lambda \le 1.0$ respectively. However, lags in the reaction of the turbulence to the pressure gradients are observed. Figures 5.15-5.24 show that for $10 < y_d u^*/\nu < 60$ the actual positions of enhancement and dampening of the streamwise intensity are $0.3 \le x_d/\lambda \le 0.6$ and $0.8 \le x_d/\lambda \le 0.1$. It is also observed for $10 < y_d u^*/\nu < 60$ that this lag is a function of height above the wave surface with the lag increasing with increasing height. Turbulence Models C^* and D^* do not take into account this effect. Model C^* does not lag turbulence quantities and Model D^* uses a single lag constant at all heights.

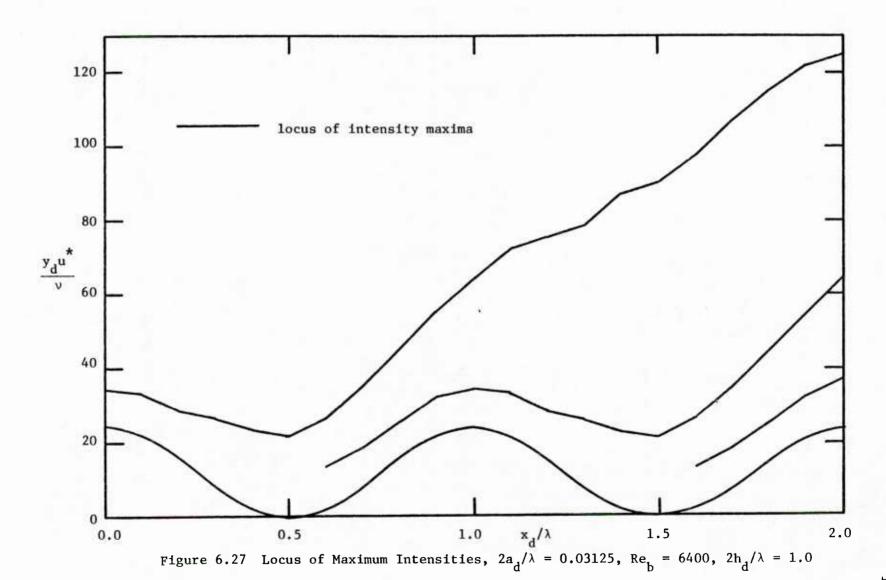
For $y_d^*u^*/v > 60$ the intensities at all positions are approximately the same as the wavelength average. The influence of the wave is minimal here because inertial forces dominate the pressure gradient forces.

An interpretation of the intensity results below $y_d^*/\nu = 10$ is less certain due to scatter in the responses. However, the data suggests that this portion of the intensity field responds faster to the local pressure gradient than the outer viscous wall region.

It should be noted that the pressure gradients along a wave surface are very large. The maximum negative pressure gradient predicted by the nonlinear channel code for $2a_d/\lambda=0.03125$ and $Re_b=6400$ is about 10 times the value of constant pressure gradients observed to cause relaminarization over a flat surface. Relaminarization was not observed. Thus an attenuation of the effect of the pressure gradients is seen as well as a lag.

The locations of the local intensity maxima in Figures 5.15-5.24 (marked by arrows) can be explained by drawing an analogy between the flowfield over a wave and a classical shear layer. This concept was first suggested by Buckles, Adrian and Hanratty [10]. The flowfield over a wave is similar to a shear layer because rapidly moving fluid from the crests passes over slowly moving fluid in the troughs. Figure 6.27 traces the loci of the intensity maxima over two wavelengths. The initial peak at $x_d/\lambda = 0.0$ becomes the second peak at about $x_d/\lambda = 0.6$ and then becomes the third peak at about $x_d/\lambda = 1.6$. This figure illustrates the "layering" effect of previous shear layers as their remnants pass over any given wave.

A two harmonic Fourier analysis of the intensity measurements was performed. The ratio of the amplitude of the second harmonic to the first, $|\mathbf{I}_2|/|\mathbf{I}_1|$, is shown in Figure 6.28. It can be seen



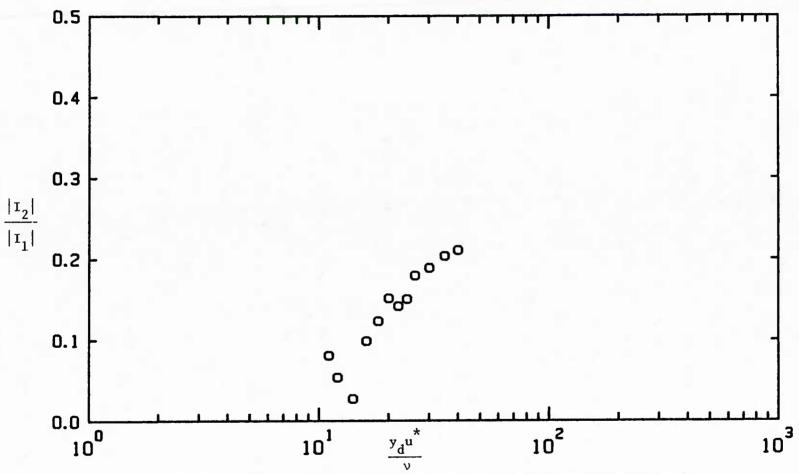


Figure 6.28 Intensity Amplitude Ratio of Second to First Harmonics, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

that the intensity response is nearly linear for $10 < y_d^*u^*/v < 40$. The results outside this range may be in error because here the amplitudes are small and of the same order as the scatter in the data.

The amplitudes of the first and second harmonics of the intensity response are given in Figure 6.30. The first harmonic is "spike" shaped with a maximum at $y_d^*/\nu = 24$. The second harmonic has a maximum at approximately the same height above the wave but is much smaller and flatter. Figure 6.29 shows the intensity response at $y_d^*/\nu = 24$ fitted to one and two harmonics. The amplitude of the intensity disturbance is negligible above $y_d^*/\nu = 60$. The response at $y_d^*/\nu = 60$ is given in Figure 6.31.

The phase shift upstream of the crest of the first harmonic of the intensity response is given in Figure 6.32. The phase varies from 222° at $y_d u^*/v = 10$ to 142° at $y_d u^*/v = 50$. The maximum intensity is in phase with the trough at about $y_d u^*/v \approx 28$.

II. Wave of Steepness $2a_d/\lambda = 0.05$

This section analyzes the velocity measurements for the wave of steepness $2a_d/\lambda=0.05$ with $Re_b=38,800$. The results, which are presented in the same form as in the previous section, show a flowfield with more nonlinear character than found over the $2a_d/\lambda=0.03125$ wave. The ability of turbulence Models C* and D* to predict this behavior is discussed.

A. Wall Stresses

1. Surface Shear Stress

The surface shear stress responses predicted by the nonlinear channel code with turbulence Models C * and D * are shown in

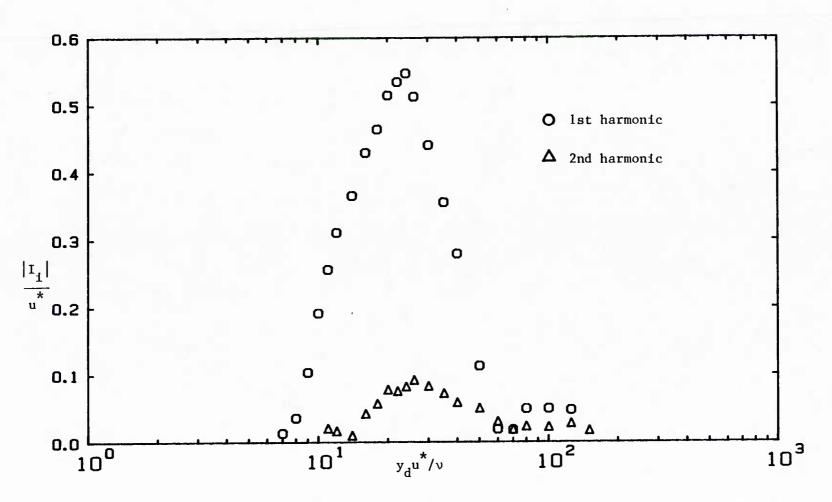


Figure 6.29 Amplitudes of First and Second Harmonics of Intensity Response, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

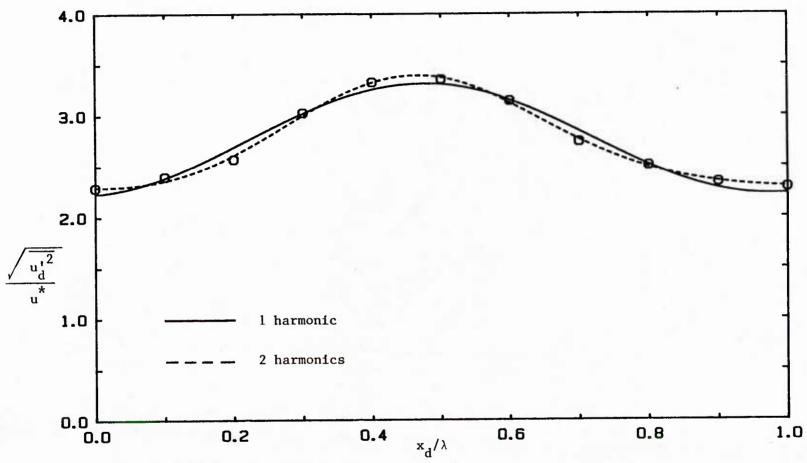


Figure 6.30 Intensity Response at $y_d^*/v = 24$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

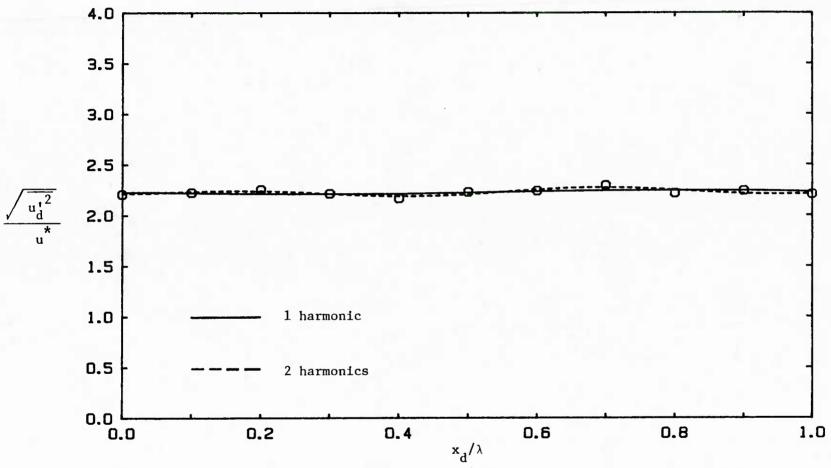


Figure 6.31 Intensity Response at $y_d u^*/v = 60$, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

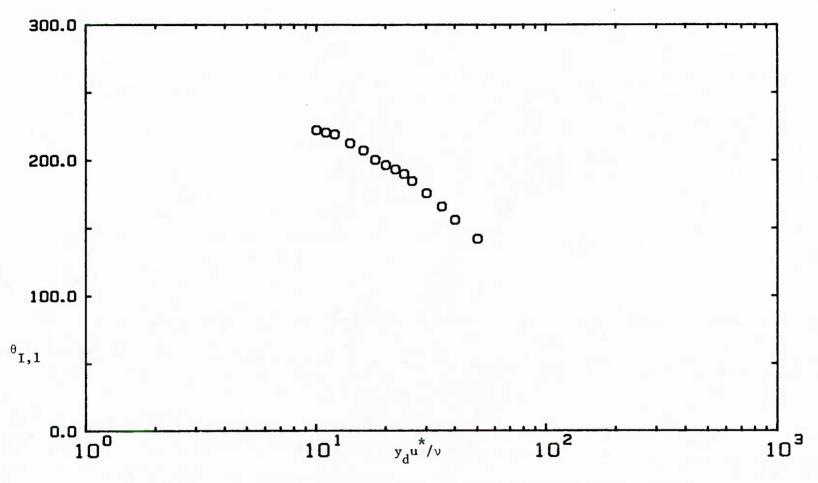


Figure 6.32 Phase Angle of First Harmonic of Intensity Response, $2a_d/\lambda = 0.03125$, $Re_b = 6400$, $2h_d/\lambda = 1.0$

Figure 6.33. This figure gives both the discrete grid points and the four harmonic Fourier fits of the spectral analysis. Recall that the code uses fitted curves to evaluate derivatives of quantities in the flow direction.

Figure 6.33 shows that Models C^* and D^* predict deviations from linearity for $2a_d/\lambda=0.05$ and $Re_b=38,800$. This is expected since $a_d u^*/\nu=95.2$. Results of the code's spectral analysis are given in Table 6.4. Considerable differences between the models are seen in the degrees of linearity, in the amplitudes, and in the phases. Model D^* predicts the most nonlinear response with $|\hat{\tau}_d|_2/|\hat{\tau}_d|_1=0.203$ as compared to 0.126 for Model C^* . The amplitude and phase of the first harmonics are $|\hat{\tau}_d|_1/\rho u^{*2}=0.7027$ and 0.5637 and $\theta_{\hat{\tau},1}=48.5$ and 62.5 for Models C^* and D^* respectively. Both models predict a wavelength averaged shear stress that is approximately 10 percent below that found in a flat channel at the same flowrate. This is about the same reduction observed for the $2a_d/\lambda=0.03125$ wave.

There are no shear stress data available for comparison with the above calculations. However, both models considerably underpredict the nonlinearitries since Zilker [48] observed $|\hat{\tau}_d|_2 / |\hat{\tau}_d|_1 = 0.317$ for $2a_d/\lambda = 0.05$ with a smaller dimensionless wave amplitude of $a_d u^*/\nu = 80.3$. Models C* and D* also underpredict the phase angle of the shear stress. Zilker found that for a fixed flowrate the first harmonic of nonseparated nonlinear shear stress responses is approximately the same as that obtained over a wave with small enough steepness to give a linear response. Abrams and Hanratty [4]

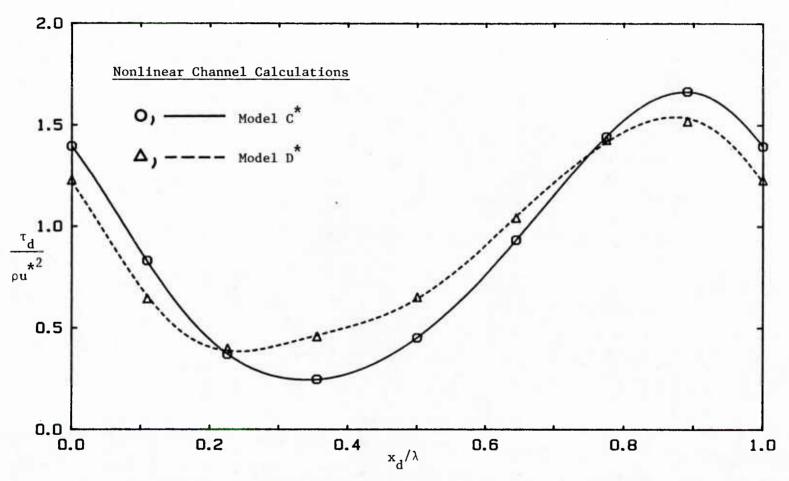


Figure 6.33 Calculated Surface Shear Stress Response, $2a_d/\lambda = 0.05$, Re_b = 38,800, $2h_d/\lambda = 1.0$

	Model C*	Model D*	
$ \hat{\tau}_d _1/\rho u^{\star 2}$	0.7027	0.5637	
$^{ heta}\hat{ au}$,1	48.5	62.5	
τ _d /ρu ^{*2}	0.880	0.899	
$ \hat{\tau}_{d} _2/ \hat{\tau}_{d} _1$	0.126	0.203	
$ \hat{\tau}_{\mathbf{d}} _{3}/ \hat{\tau}_{\mathbf{d}} _{1}$	0.015	0.053	

Table 6.4 Predictions of First Harmonic of Surface Shear Stress Response, $2a_d/\lambda = 0.05$, Re_b = 38,800, $2h_d/\lambda = 1.0$

measured a linear response and a phase angle of 79 \pm 5° for $2a_d/\lambda = 0.014$ and $Re_b = 38,800$.

The shape of the Model D* response agrees qualitatively with that of all nonlinear shear stress responses observed by Zilker. The model exhibits a gradual variation of the wall shear stress on the windward side of the wave and a steep variation on the leeward side.

2. Surface Pressure

Predictions of the surface pressure by the nonlinear code with turbulence Models C* and D* are shown in Figure 6.34. The results of a two harmonic Fourier analysis of these discrete profiles is given in Table 6.5. Both models predict a linear response with nearly identical first harmonic amplitudes and phases. No data are available for comparison with these calculations.

3. Drag

Drag coefficients predicted by the nonlinear channel analysis are shown in Table 6.6. Both Models C* and D* give approximately a 10 percent decrease in the skin friction drag relative to a flat surface. The total drag for the wave surface increases by about 20 percent due to form drag which represents about 25 percent of the total drag for both models.

B. Wavelength Averaged Mean Velocity

The experimental wavelength averaged velocity profile over the wave with $2a_d/\lambda=0.05$ is shown in Figure 6.35. This profile was obtained by averaging the ten profiles in Figures 5.25-5.34 and is thus constructed along Cartesian coordinates as discussed in

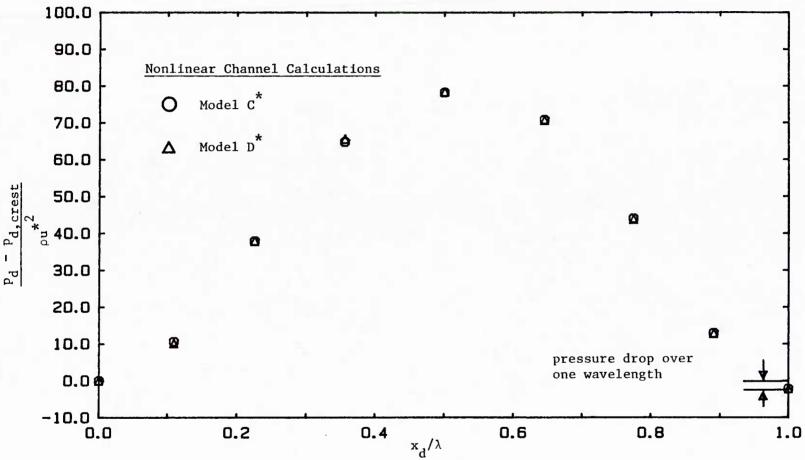


Figure 6.34 Calculated Pressure Response, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

	Model C*	Model D*	
p̂ _d 1/pu*2	39.49	39.73	
θ̂ρ,1	174.5	174.8	
$\left \hat{\mathbf{p}}_{\mathbf{d}}\right _{2}/\left \hat{\mathbf{p}}_{\mathbf{d}}\right _{1}$	0.108	0.106	

Table 6.5 Surface Pressure Results of Nonlinear Channel Analysis, $2a_d/\lambda = 0.05$, Re_b = 38,000, $2h_d/\lambda = 1.0$

Turbulence Model	C _s	C _p	$\frac{c_s}{c_s + c_p}$	$\frac{C_p}{C_s + C_p}$	c _s + c _p
c *	0.880	0.315	0.736	0.264	1.19
D *	0.899	0.296	0.752	0.248	1.20

Table 6.6 Drag Coefficients, $2a_d/\lambda = 0.05$, $Re_b = 38,800, 2h_d/\lambda = 1.0$

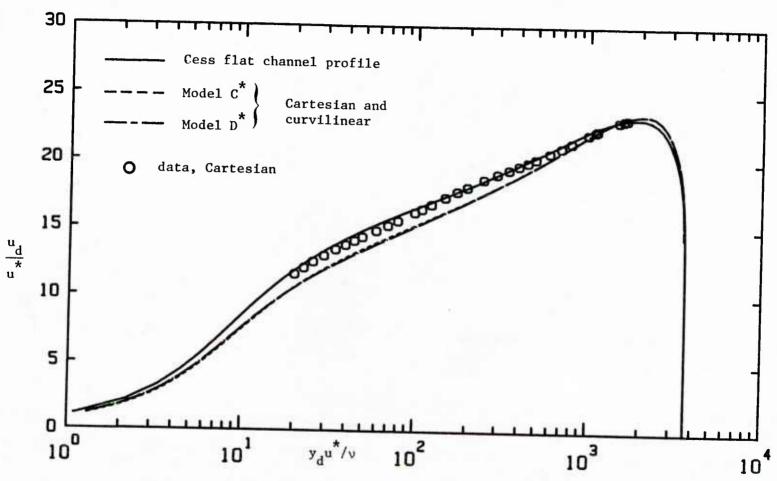


Figure 6.35 Wavelength Averaged Velocity Profiles, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

Section I.B. and shown in Figure 6.4. The Cartesian wavelength averaged profiles predicted by the nonlinear channel code with turbulence Models C^* and D^* are also shown in Figure 6.35. The differences between Models C^* and D^* are negligible. The wavelength averaged data are higher than the theory. This difference is believed to be slightly greater than the experimental error.

Predictions by the nonlinear code of wavelength averaged profiles formed along the curvilinear coordinates (Figure 6.5) were found to be nearly identical to the average profiles in Cartesian coordinates. The Cess flat channel profile is included in Figure 6.35. The calculated wavelength averaged profiles are significantly lower than the flat channel profile. The reason for this behavior is not known.

All of the wavelength averaged profiles discussed above are normalized with flat channel wall parameters.

C. Mean Velocity Profiles

The mean velocity profiles for the wave with $2a_d/\lambda=0.05$ are shown in Figures 6.36-6.40, where they are compared with predictions of the nonlinear channel code with turbulence Models C^* and D^* . Significant differences between the two models are seen for $y_d u^*/\nu < 20$. In this region Model D^* predicts smaller perturbations about the mean flowfield than Model C^* . Both models considerably underestimate the measured disturbances at all heights above the wave.

The steepness of $2a_d/\lambda = 0.05$ was found to be small enough that the calculated profiles are independent of the type of distance y_d used in the Cess equation. See equation (3.31).

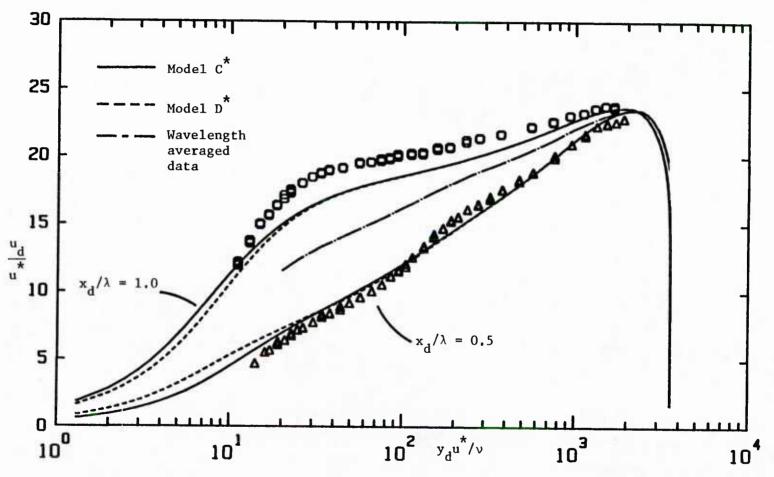


Figure 6.36 Comparison of Mean Velocity Measurements with Channel Calculations, $x_d/\lambda = 0.5$, 1.0, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

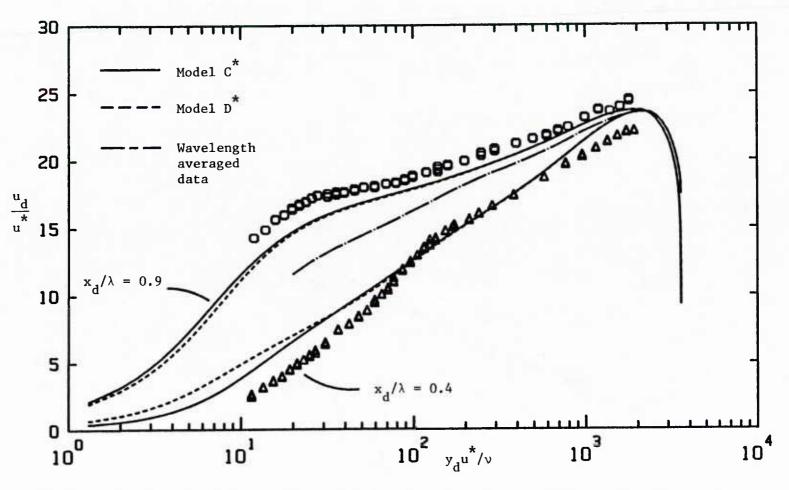


Figure 6.37 Comparison of Mean Velocity Measurements with Channel Calculations, $x_d/\lambda = 0.4$, 0.9, $2a_d/\lambda = 0.05$, $Re_b = 38,800$ $2h_d/\lambda = 1.0$

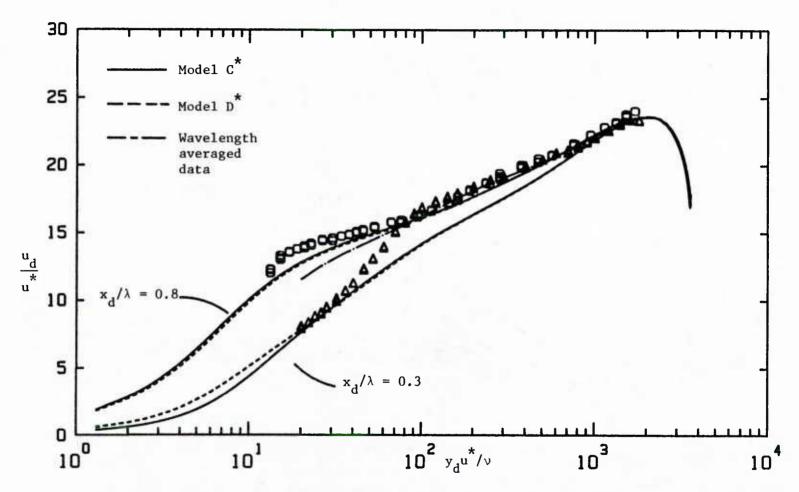


Figure 6.38 Comparison of Mean Velocity Measurements with Channel Calculations, x_d/λ = 0.3, 0.8, $2a_d/\lambda$ = 0.05, Re_b = 38,800, $2h_d/\lambda$ = 1.0

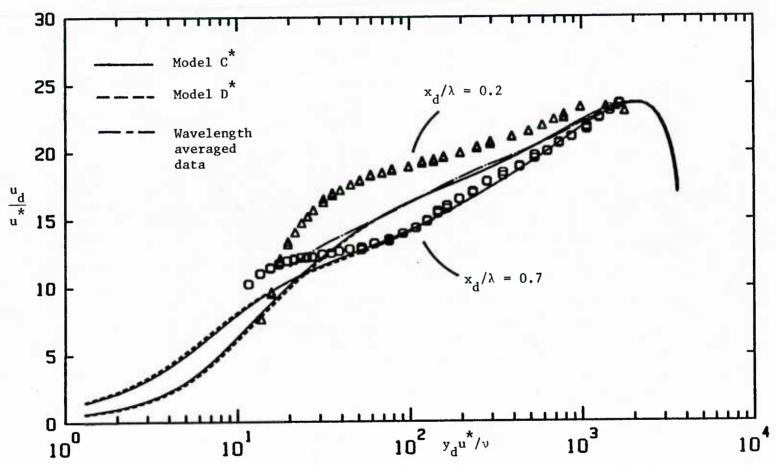


Figure 6.39 Comparison of Mean Velocity Measurements with Channel Calculations, $x_d/\lambda = 0.2$, 0.7, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

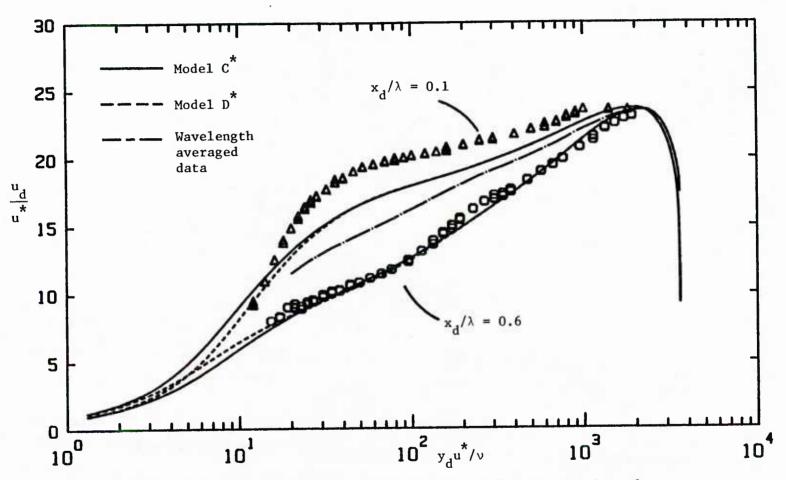


Figure 6.40 Comparison of Mean Velocity Measurements with Channel Calculations, $x_d/\lambda = 0.1$, 0.6, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

D. Mean Velocity Responses at Constant Heights above Wave

The velocity field at constant vertical heights above the wave surface is shown in Figure 6.41. The heights range from $y_d^*/\nu = 20.4$ to $y_d^*/\nu = 1500$. Moderate departures from a linear response are observed for roughly $y_d^*/\nu < 100$. Here the velocity responses vary gradually on the windward side of the wave and steeply on the leeward side. This is the same shape that Zilker et al. [49] observed for nonlinear shear stress responses.

A two harmonic least squares Fourier analysis was performed on the curves in Figure 6.41. Figure 6.42 shows the ratio of the amplitude of the second to first harmonic as a function of distance above the wave. The response is observed to be nonlinear ($|\hat{\mathbf{u}}_{\mathbf{d}}|_2 / |\hat{\mathbf{u}}_{\mathbf{d}}|_1 > 0.116$) for $\mathbf{y}_{\mathbf{d}}\mathbf{u}^*/\lambda < 100$ with a maximum ratio of 0.21 at $\mathbf{y}_{\mathbf{d}}\mathbf{u}^*/\nu = 35$. These nonlinearities are surprisingly weak when it is considered that the dimensionless wave amplitude, $\mathbf{a}_{\mathbf{d}}\mathbf{u}^*/\nu$, of the $2\mathbf{a}_{\mathbf{d}}/\lambda = 0.05$ wave is 95.2/12.3 = 7.7 times that for the $2\mathbf{a}_{\mathbf{d}}/\lambda = 0.03125$ wave. The observed nonlinearities are underpredicted by both Models C and D.

Amplitudes of the first and second harmonics of the velocity response are shown in Figure 6.43. The shape of these profiles is similar to that found over the $2a_d/\lambda=0.03125$ wave. The maximum value of the first harmonic amplitude is 5.6 at $y_du^*/\nu=26$. Figure 6.44 shows the response at $y_du^*/\nu=26$ where it is fitted to one and two harmonics. The amplitude of the second harmonic reaches a maximum at approximately $y_du^*/\nu=35$. Figure 6.45 shows the linear velocity response at $y_du^*/\nu=100$.

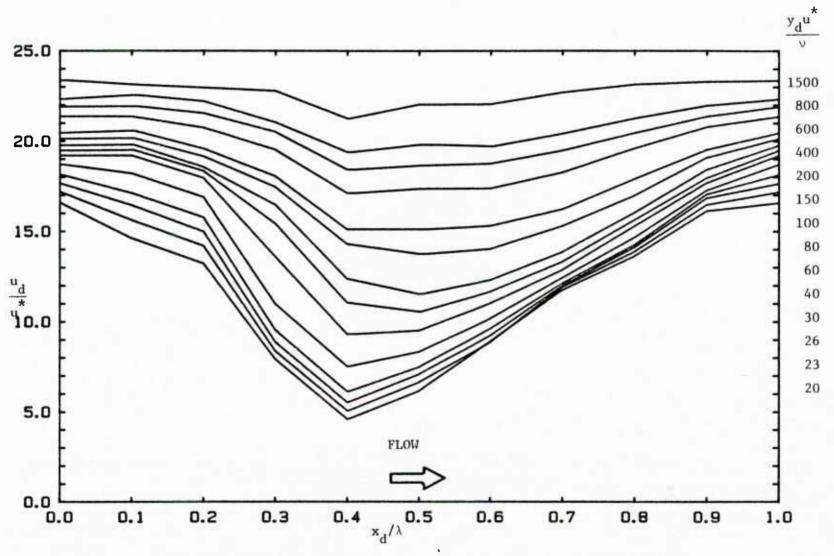


Figure 6.41 Mean Velocity Responses at Constant Heights above Wave Surface, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

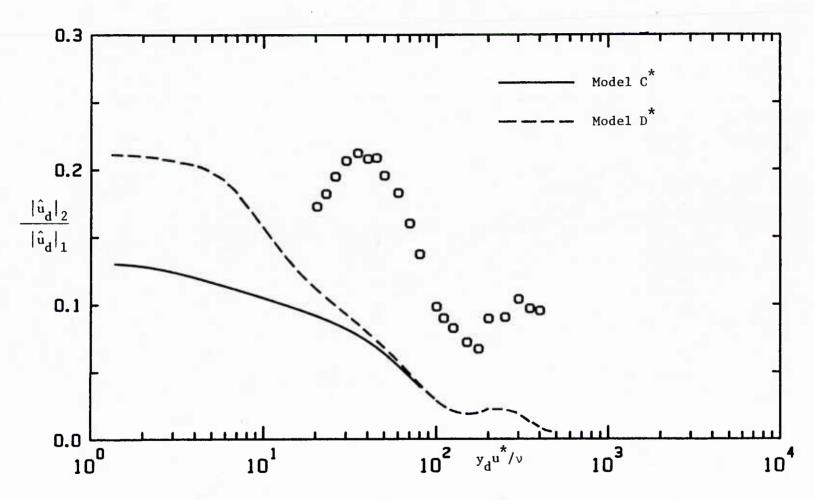


Figure 6.42 Velocity Amplitude Ratio of Second to First Harmonics, $2a_{\rm d}/\lambda$ = 0.05, Re_b = 38,800, $2h_{\rm d}/\lambda$ = 1.0

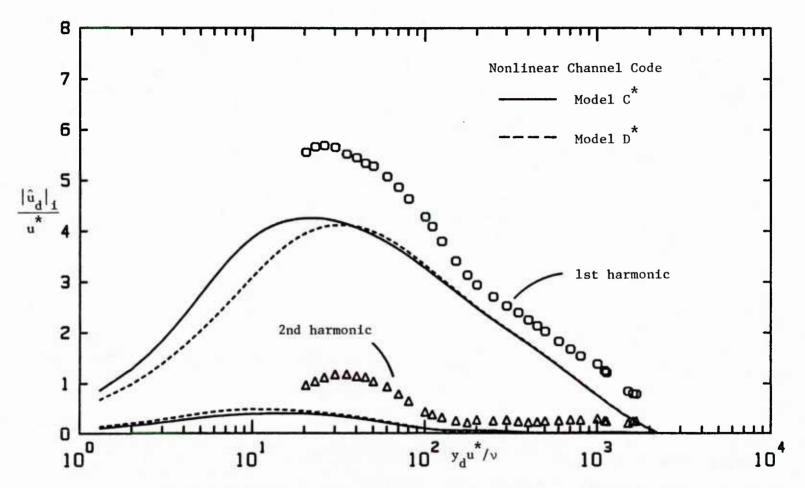


Figure 6.43 Amplitude of First and Second Harmonics of Velocity Response, $2a_d/\lambda$ = 0.05, Re $_b$ = 38,800, $2h_d/\lambda$ = 1.0

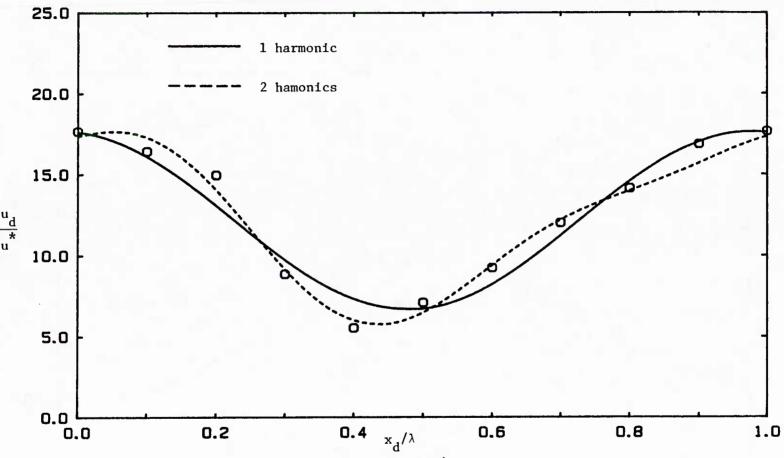


Figure 6.44 Velocity Response at $y_d^*/v = 26$, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

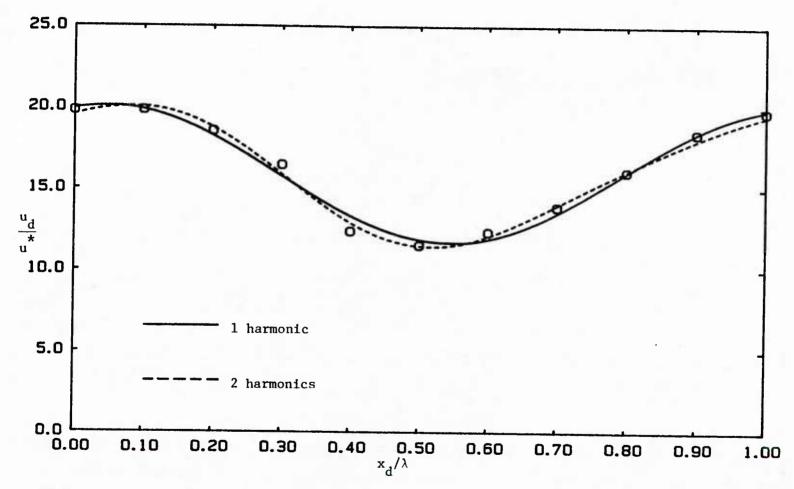


Figure 6.45 Velocity Response at $y_d^* v = 100$, $2a_d \lambda = 0.05$, $Re_b = 38,800$, $2h_d \lambda = 1.0$

Figure 6.43 differs from Figure 6.13 for the wave with $2a_d/\lambda=0.03125$ in that the disturbances for the 0.05 wave extend well outside the viscous wall region. This is consistent with the linear theory calculations of Abrams [2] which predict that the penetration of disturbances increases with decreasing dimensionless wavenumber, $\alpha_d v/u^*$.

The amplitude predictions of Model C* and D* are also shown in Figure 6.43. Both models predict profiles with the same general shape as the data. The first harmonic responses of the two models are nearly identical for $y_d u^*/v > 40$. Below $y_d u^*/v = 40$ Model C* gives larger first harmonic amplitudes than Model D*. The second harmonic responses are similar for both turbulence models.

Models C* and D* significantly underestimate the amplitude observations for $y_d^* v < 100$. The explanation for the "failure" of these models is the same as given in Section I.D. for the wave with $2a_d/\lambda = 0.03125$ and $Re_b^* = 6400$. It is suggested that only a very simple model, with small wave-induced variations of the turbulence outside the near wall region, will provide a good fit to this portion of the velocity field. Supporting evidence for the above statement was obtained by running the linear boundary layer program of Abrams [2] with quasilaminar, C* and D* turbulence models for $\alpha_d v/u^* = 0.00165$ (equivalent to $Re_b^* = 38,800$). It is found that the quasilaminar model predicts a maximum wave-induced amplitude which is 41 percent and 42 percent higher than Models C* and D* respectively. However, it should not be forgotten that a quasilaminar model cannot predict the near wall region for

small dimensionless wavenumbers, α_d^{u}/ν. Abrams has shown that for linear waves with $\alpha_d^{u}/\nu=0.00165$ it is necessary to use a model, such as Model D*, where turbulence properties are a function of the pressure gradient.

Determination of the amplitude of the shear stress response from the LDV measurements in Figure 6.43 is not possible because the closest measurements are well outside the viscous sublayer.

The phase angle of the first harmonic of the velocity response is shown in Figure 6.46. A value of 15.8° is observed at the closest measurement location of $y_d u^*/v = 20$. The phase angle falls to a minimum value of -16.9° at $y_d u^*/v = 125$ and tends toward zero far from the wall. The accuracy of the phase angles for $y_d^*u^*/v > 400$ is low because here scatter in the data becomes a significant fraction of the response amplitudes. Prediction of the phase angle by the nonlinear channel code with turbulence Models C^{\star} and D^{\star} are also shown in Figure 6.46. As in the case of the $2a_d/\lambda = 0.03125$ wave, neither model fits the data well outside the viscous wall region. The measurements approach the calculations at small $y_d u^*/v$ but do not extend close enough to the wave surface to test either model in the near wall region. Thus obtaining the phase angle of the wall shear stress by extrapolating the data to the wall is not possible for $2a_d/\lambda = 0.05$ and $Re_h = 38,800$. Electrochemical techniques are necessary the measure the wall shear stress response.

E. Wave-Induced Velocity Perturbations

Measured profiles of the wave-induced velocity perturbations about the experimental wavelength averaged profile are shown in

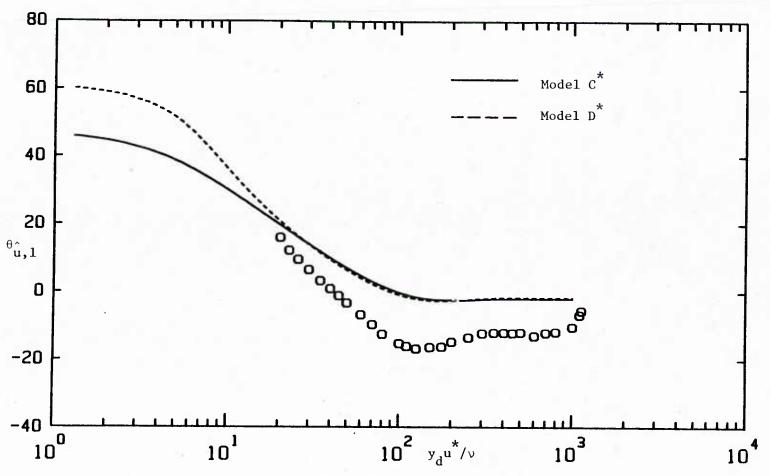


Figure 6.46 Phase Angle of First Harmonic of Velocity Response, $2a_d/\lambda$ = 0.05, Re_b = 38,800, $2h_d/\lambda$ = 1.0

Figures 6.47-6.51. These figures also contain predicted perturbations, by the nonlinear channel code with turbulence Models C* and D*, about calculated wavelength averaged profiles. It should be pointed out that in Figures 6.47-6.51 differences between the data and calculations are not due to differences in the experimental and calculated wavelength averaged profiles as is the case in Figures 6.47-6.51 for the mean velocity profiles. Both models underpredict the disturbances in the viscous wall region but have the same general shape as the data.

Figures 6.47-6.51 clearly show that disturbances penetrate outside the viscous wall region.

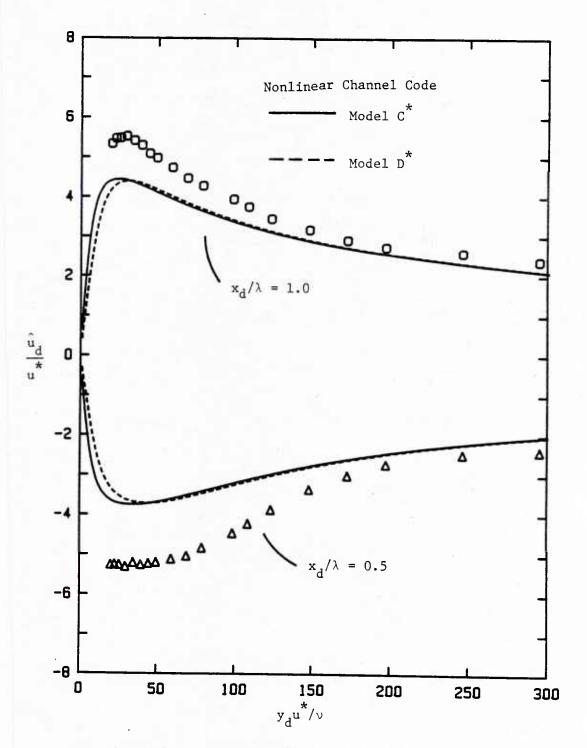


Figure 6.47 Wave-Induced Velocity Perturbations, $x_d/\lambda = 0.5$, 1.0, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda^d = 1.0$

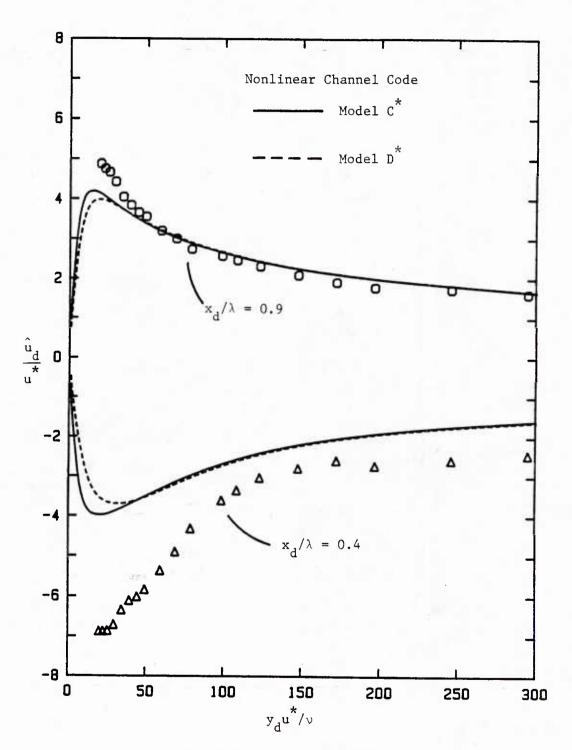


Figure 6.48 Wave-Induced Velocity Perturbations, $x_{\rm d}/\lambda = 0.4,~0.9,~2a_{\rm d}/\lambda = 0.05,~{\rm Re_b} = 38,800, \\ 2h_{\rm d}/\lambda = 1.0$

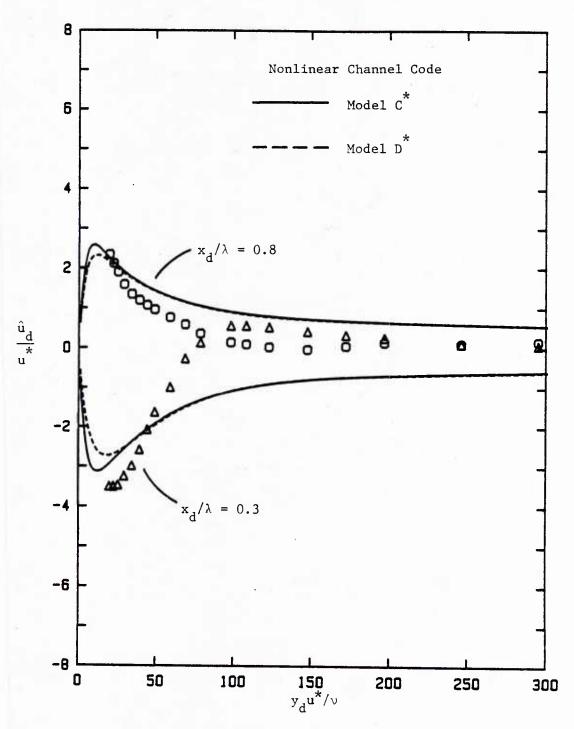


Figure 6.49 Wave-Induced Velocity Perturbations, $x_{\rm d}/\lambda = 0.3, \ 0.8, \ 2a_{\rm d}/\lambda = 0.05, \ {\rm Re}_{\rm b} = 38,800, \\ 2h_{\rm d}/\lambda = 1.0$

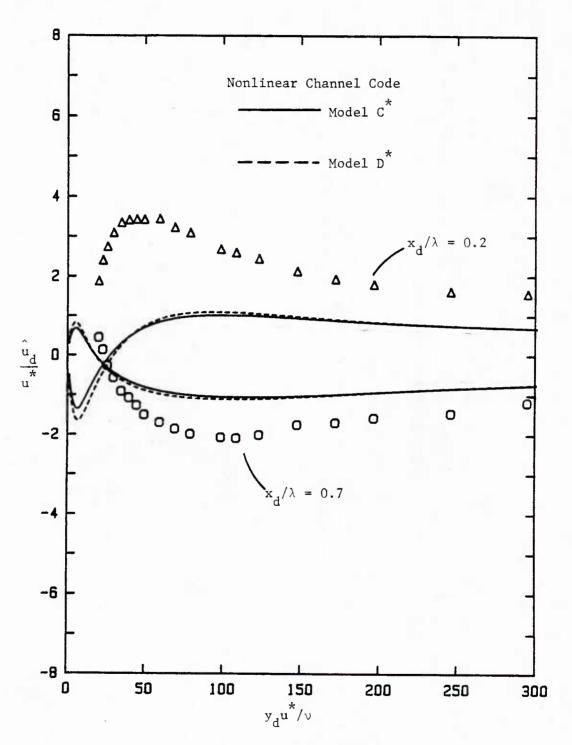


Figure 6.50 Wave-Induced Velocity Perturbations, $\begin{array}{c} x_d/\lambda = 0.2, \; 0.7, \; 2a_d/\lambda = 0.05, \; \text{Re}_b = 38,800, \\ 2h_d/\lambda = 1.0 \end{array}$

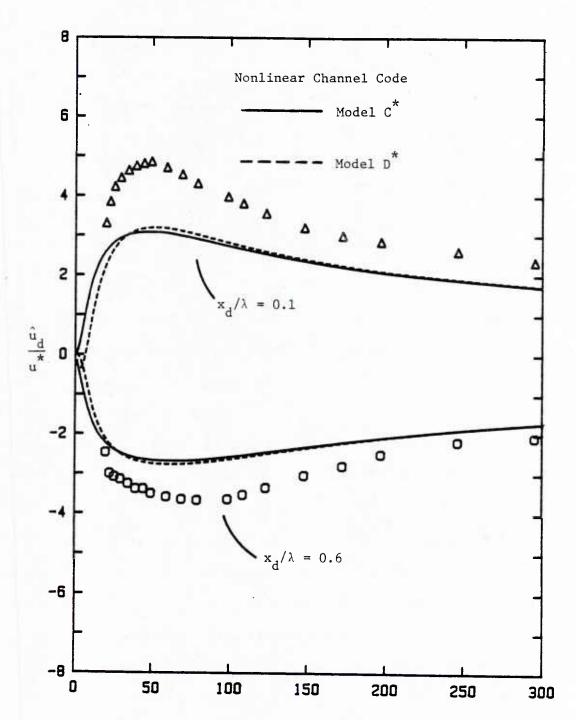


Figure 6.51 Wave-Induced Velocity Perturbations, $x_d/\lambda = 0.1$, 0.6, $2a_d/\lambda = 0.05$, $Re_b = 38,800$, $2h_d/\lambda = 1.0$

CHAPTER 7

SUMMARY AND CONCLUSIONS

This chapter summarizes the goals of this thesis, the approach taken to achieve these goals, and the major results which have emerged from the experiments and computations.

I. Goals and Approach

The purpose of the experimental effort was to extend previous studies of nonseparated flow over wavy surfaces by obtaining detailed measurements of the velocity field. Earlier investigators concentrated on the measurement of the surface shear stress and pressure and made only limited velocity measurements. This study presents the first set of velocity data with sufficient measurements to give an accurate representation of the spatial variation in the viscous wall region, $y_d u^*/v < 40$. The viscous wall region is of particular interest because the majority of wave-induced disturbances occur here and measurements within this region can be used as a test of the turbulence models of Thorsness [45] and Abrams [2]. Previous tests of their models, which are the best to date, have been limited to comparisons with surface stress data.

Two sets of velocity measurements over waves on the bottom wall of a channel were obtained at conditions corresponding to flows where linear and nonlinear shear stress responses are observed. The conditions were $2a_d/\lambda = 0.3125$, $Re_b = 6400$ and $2a_d/\lambda = 0.05$, $Re_b = 38,800$ respectively. The wavelength of the waves was 2 in. and the ratio of the channel height to the wavelength, $2h_d/\lambda$, was equal to one. The

measurements were taken with a single-channel dual-beam laser-Doppler velocimeter operated in the forward scatter mode. The unique feature of the LDV used in this study is an optics system containing two beam expanders. The beam expanders provided a small enough measurement volume to perform velocity measurements as close to the wave surface as $y_d^{-1}/v = 2$ and 10 for the waves with $2a_d/\lambda = 0.03125$ and 0.05 respectively. Fifteen to twenty data points were taken vertically within the viscous wall region and the measurements extended to the center of the channel. Good spatial resolution in the streamwise direction was achieved by conducting velocity measurements every tenth of a wavelength. Accurate location of the LDV was obtained with a lead screw type traversing mechanism which was constructed for this experiment. Careful filtering and seeding of the fluid was found to be critical for taking accurate LDV measurements.

The primary purpose of the computational effort was to extend the linear theory calculations of Thorsness [45] and Abrams [2] by developing a nonlinear computer code for predicting the flowfield above finite amplitude waves. The velocity measurements in this thesis were obtained over finite amplitude waves where the application of linear theory is uncertain. A secondary goal of the computational work was to perform the above calculations for a channel flow rather than a boundary layer as did Thorsness and Abrams. This is because all of the wavy surface measurements from this laboratory have been conducted in a channel. The computer code solves the nonlinear Reynolds-averaged Navier-Stokes equations using spectral methods in the flow direction and finite differences in the vertical

direction. For computational ease the wave surface was transformed to a flat surface via a conformal mapping. An explicit stretching in the vertical direction was introduced to resolve the steep velocity gradients near the wave and the top wall of the channel. Storage requirements were lowered with the use of a sparse matrix solver. The code is a modification of a boundary layer program by McLean [32].

Future applications of the nonlinear channel program may include the study of wave generation, drag reduction, asymmetric waves, and compliant surfaces. The program was also developed to be used as a "tool" for testing new turbulence models.

II. Results

Mean velocity responses at constant vertical heights above the wave of steepness $2a_d/\lambda=0.03125$ with $Re_b=6400$ were Fourier analyzed. The degree of linearity of the flowfield, the wavelength averaged flowfield, and the amplitudes and phases of the wavelinduced responses were determined.

A weakly nonlinear flowfield is observed. This is consistent with the electrochemical shear stress measurements of Zilker [48] which show a borderline linear-nonlinear shear stress response for the same flow conditions. The maximum ratio of the amplitude of the second to first harmonics was found to be 0.17 at about $y_d^*u^*/v = 12$. Nonlinearities are negligible outside the viscous wall region.

The wavelength averaged flowfield is observed to be nearly the same as that found in a flat channel.

The majority of the wave-induced disturbances occur within the viscous wall region. The amplitude of the first harmonic is zero at the wave surface and rises sharply to a maximum of 3.6 plus units at $y_d u^*/v = 9$. This amplitude represents a 46% disturbance about the wavelength averaged velocity field. Above $y_d u^*/v = 9$ the amplitude of the first harmonic decreases rapidly to about the edge of the viscous wall region and then gradually decreases to zero at the center of the channel, $y_d u^*/v \approx 365$. At $y_d u^*/v = 40$ and 300 the disturbances about the mean flowfield were about 10% and 1% respectively.

A streamwise sequence of the mean velocity profiles clearly shows that the inner flow precedes the outer flow in reacting to pressure gradient changes along the wave surface. The inner flow responds more rapidly since the inertia of the fluid is less here than in the core. The phase angle of the first harmonic of the mean velocity response is a quantitative measure of these lags. The phase angle was found to vary rapidly in the viscous wall region. A maximum phase angle, with respect to the downstream crest, of 49° is observed at $y_d u^*/v = 2$ and phase has a minimum value of -23° at about $y_d u^*/v = 50$ and tends toward zero far from the wall where the influence of the wave on the fluid is not felt.

The streamwise turbulent intensity responses over the $2a_d/\lambda=0.3125$ wave were also Fourier analyzed. The wavelength averaged profile of the intensity shows a slight increase above flat channel intensities. A near linear response is observed for $10 < y_d^* v_d < 40$. A maximum disturbance of 20% about the wavelength average occurs at

 $y_d^*u^*/v = 24$. The amplitude of the wave-induced variation of the intensity is almost zero above $y_d^*u^*/v = 60$.

The periodic variation of the turbulent intensity along the wave is consistent with constant pressure gradient experiments in other laboratories [6, 7,22,23,28,29,31]. It has been observed that strong negative (favorable) pressure gradients cause a dampening of turbulence close to the wall, and that positive pressure gradients (adverse) have just the opposite effect. However, in this case the pressure gradient is varying rapidly in the flow direction and the flow does not adjust instantaneously as it would for an equilibrium flow. Lags in the reaction of the turbulent intensity to the spatially varying pressure gradient are observed, with the reaction of the inner flow preceding the outer flow. The phase angle of the intensity response, with respect to the downstream crest, is 222° at $y_d^*u^*/v = 10$ and 142° at $y_d^*u^*/v = 50$. As a reference, instantaneous reaction of the fluid corresponds to a phase angle of about 270° since the variation of the pressure gradient along the wave is roughly that predicted by inviscid Kelvin-Helmholtz theory.

The above observation of the u-intensity lagging in reaction to a pressure gradient provides some physical basis for the highly empirical Model D*. However, a better test of this model would be a comparison with uv-intensities. Experiments to measure the Reynolds stress with a two-component LDV are currently being designed in this laboratory. These measurements will provide a more direct test of turbulence models.

The LDV measurements are close enough to the wave surface to extrapolate linearly to obtain the phase angle but not the amplitude of the shear stress response. The extrapolated phase angle of 54° agrees with the electrochemical measurements of Zilker [48]. The amplitude of the shear stress response could not be obtained because the linear region in the velocity profiles does not extend to the closest measurements at $y_d u^*/v = 2$.

The mean velocity responses above the wave of steepness $2a_d/\lambda=0.05$ with Re_b = 38,800 were also Fourier analyzed. The responses over this wave showed moderate departures from linear behavior for $y_d^*u^*/\nu<100$. The maximum value of the ratio of the amplitude of the second harmonic to first harmonics is 0.21 at about $y_d^*u^*/\nu=35$. The nonlinearities are surprisingly weak when it is considered that the dimensionless wave amplitude, $a_d^*u^*/\nu$, of this wave is 7.7 times that for the $2a_d/\lambda=0.03125$ wave. The velocity responses varied gradually on the windward side of the wave and steeply on the leeward side. This is the same shape that Zilker [48] observed for all nonlinear shear stress responses. However, shear stress measurements of Zilker under similar conditions showed much greater non-linearities at the wave surface than observed above the wave.

As in the case of the $2a_d/\lambda=0.03125$ wave, the wavelength averaged flowfield was found to be very close to that observed in a flat channel.

The shape of the first harmonic amplitude profile is similar to that found over the $2a_d/\lambda = 0.03125$. However, in this case the disturbances extend well outside the viscous wall region. This is

consistent with the linear calculations of Abrams [2] which show that the penetration of disturbances increases with decreasing dimensionless wavenumber, $\alpha_{\rm d} v/u^*$. The two sets of data suggest that this penetration is given by $(\alpha_{\rm d} v/u^*)(y_{\rm d} u^*/v)={\rm constant.}$ A maximum amplitude of 5.6 plus units is observed at $y_{\rm d} u^*/v=26$. By coincidence, this is also a 46 percent disturbance about the wavelength averaged flowfield. Above $y_{\rm d} u^*/v=26$ the disturbances decrease rapidly to $y_{\rm d} u^*/v=200$ and then gradually to the center of the channel, $y_{\rm d} u^*/v\approx 1830$.

The phase angle of the first harmonic varied rapidly between the wave surface and $y_d^*/\nu = 100$. A value of 15.8° was observed at $y_d^*/\nu = 20$. A minimum value of -16.9° was found at $y_d^*/\nu = 125$ and the phase angle tended toward zero far from the wall. As found for the $2a_d/\lambda = 0.03125$ wave, the rapid phase changes are a result of mean velocity variations in the inner flow preceding the outer flow.

The nonlinear channel calculations were performed with turbulence Models C* and D* developed by Thorsness [44] and Abrams [2]. Both models used the Cess eddy viscosity profile which is an empirical equation derived by matching van Driest's wall region law with Reichardt's middle law. The Cess profile was chosen for the computations because it gives a good fit of eddy viscosity data in a flat channel and provides a smooth transition between the inner and core regions. For Model C* the flat channel value of the van Driest parameter is used in the Cess equation. However, turbulence properties are allowed to vary in the flow direction because the eddy viscosity is a function of the local shear stress and turbulent

stresses are a function of the local rate of strain. This model is appealing because it is a simple extension of the widely accepted Cess equation for a flat channel. In Model D* the effect of pressure gradients on the turbulence is taken into account. The van Driest parameter is used as a scale factor for governing the thickness of the viscous wall region. This parameter is assumed to be a simple polynomial function of the pressure gradient with a single lag constant used to relax the flow. Model D* was investigated because Abrams [2] has shown that it is necessary to include the effect of pressure gradients on the turbulence to predict the surface shear stress.

Three different types of physical distances from the wave surface in the Cess equation were investigated: normal, Cartesian, and curvilinear. It was found that the results are independent of the type of distance for waves of steepness $2a_d/\lambda \leq 0.05$.

The agreement between the computations and measurements is best for the wave of steepness $2a_d/\lambda=0.03125$ with $Re_b=6400$ and for these conditions the results using turbulence Models C^* and D^* are very similar.

Models C* and D* both predict the observed near linear response of the velocity field over the $2a_d/\lambda=0.03125$ wave. However, the models significantly underpredict the weak nonlinearities found in the experimental velocity responses.

The amplitude and phase of the surface shear stress predicted by both models are within the experimental error of the electrochemical measurements of Zilber [48]. Zilker also observed a wavelength averaged shear stress which was the same as the flat channel value. Models C^* and D^* predict a shear stress reduction of about 10 percent.

Turbulence Models C* and D* predict identical wavelength averaged velocity profiles over the $2a_d/\lambda=0.03125$ wave that are within the experimental error of the wavelength averaged velocity data.

A comparison between the experimental mean velocity profiles and the mean profiles from Models C* and D* shows reasonably good agreement. Small differences between the two models is observed. The most important result for this wave is that Model C*, which is an eddy viscosity model developed for a flat channel, predicts a good first approximation of the velocity field. However, two shortcomings of Models C* and D* are observed. First, both models predict smaller disturbances about the wavelength averaged profile than is found experimentally. Secondly, the observed variation of the phase angle of the velocity with height above the wave is larger than predicted.

Computations with turbulence Models C^* and D^* were also performed for the wave of steepness $2a_d/\lambda=0.05$ with $Re_b=38,800$. In general, agreement between the calculations and measurements is not as good as for the wave of lower steepness. However, the results are still semi-quantitative. Significant differences between the predictions of Models C^* and D^* are observed.

Models C^* and D^* correctly predict a nonlinear response of the velocity field. However, both models significantly underestimate observed nonlinearities. Model C^* is particularly poor because this

model predicts a weakly nonlinear response. The shape of the Model D* response is qualitatively the same as the data. That is, the predicted velocity responses vary gradually on the windward side of the wave and steeply on the leeward side.

As in the case of the $2a_d/\lambda=0.03125$ wave, the wavelength averaged velocity profiles predicted by Models C* and D* are nearly identical. However, these profiles are significantly lower than the measured wavelength average. The reason for this difference is not known.

The observed amplitude of the first harmonic of the velocity response for the wave with $2a_d/\lambda = 0.05$ is considerably underpredicted by both Models C* and D*. Linear theory calculations with a quasilaminar turbulence model suggest that larger disturbances about the wavelength averaged flowfield are obtained with models predicting smaller wave-induced variations of the turbulence than Models C^{\star} and D*. However, Abrams [2] has shown that such models cannot predict the wall shear stress over a wide range of flowrates. Furthermore, models with small wave-induced variations do not predict strong nonlinearities. Thus there is an apparent contradiction in producing both the large wave-induced disturbances and the large nonlinearities which are observed in the data. It is not known how to "design" a turbulence model to resolve this problem. A lag constant in Model D that is a function of height above the wave may provide some improvement. However, it is suggested that a more fundamental approach such as a k-ε closure or solution of the unaveraged Navier-Stokes equations be investigated.

The variation with height of the phase angle of the velocity is underpredicted by Models C * and D * .

In summary, measurements were obtained of the viscous wall region over waves with nonseparated flows. It was found that the behavior of both the mean velocity field and the streamwise intensity field can be explained in terms of pressure gradient variations induced by the wave surface. It is observed that the outer flow lags the inner flow in reacting to the local pressure gradient. Of particular interest is a periodic enhancement and dampening of the streamwise intensity which is consistent with experiments for constant pressure gradient flows. A nonlinear computer code was developed to solve for the flowfield over finite amplitude waves in a channel. Two eddy viscosity turbulence models were investigated; one designed for a flat channel, and one where turbulent stresses are a function of the pressure gradient and relaxed with a single lag constant. Both models give semi-quantitative results but underpredict disturbances about the wavelength average flowfield, variations in the phase of the velocity, and nonlinearities.

NOMENCLATURE

a _d	Dimensional wave amplitude (cm)
A	van Driest parameter
A'	Dimensional area along wave surface, see equation (6.2) (cm^2)
Ā	Average van Driest parameter, see equation (3.32)
Ъ	Stretching coefficient in equation (3.23)
b _i	Coefficients in orthogonal transformation, see equations (3.8) and (3.9)
c _n	Coefficients in Fourier series defined by equation (6.1)
C'p	Local wall pressure coefficient defined by Sigal
C _p	Pressure drag coefficient defined in equation (6.5)
C _s	Skin friction drag coefficient defined in equation (6.4)
d_n	Coefficients in Fourier series defined by equation (6.1)
f	Fanning friction factor
F _x d	Dimensional \mathbf{x}_d component of the total force that the fluid exerts on the wave (dyne)
$^{\rm h}$ d	Dimensional half height of channel (cm)
I _n	Dimensional amplitude of nth harmonic of wave-induced streamwise intensity (cm/s)
J	Jacobian of orthogonal transformation defined by equations (3.8) and (3.9)
k ₁ ,k ₂	Coefficients defined in equation (3.32)
k _L	Lag parameter defined in equation (3.33)
^p d	Dimensional time-averaged pressure (dyne/cm ²)
^p d,crest	Dimensional time-averaged pressure at crest $(dyne/cm^2)$
$ \hat{p}_{d} _{n}$	Dimensional amplitude of nth harmonic of wave-induced surface pressure $(dyne/cm^2)$

p ⁺	Dimensionless pressure gradient in $\mathbf{x}_{\mathbf{d}}$ direction
Peff	Dimensionless effective pressure gradient defined by equation (3.54)
Re _b	Channel Reynolds number based on bulk velocity and half channel height
R _{ij}	Dimensional components of the time-averaged turbulent stress tensor (dyne/cm ²)
S	Dimensional distance along wave surface, see equations (6.4) and (6.5) (cm)
$s_{\tt ij}$	Dimensional components of the time-averaged rate of strain tensor $(1/s)$
u*	Friction velocity for flat surface (cm/s)
^u d	Dimensional time-averaged velocity in x_d direction (cm/s)
u'd	Dimensional fluctuating component of turbulent velocity in x_d direction (cm/s)
$\hat{\mathbf{u}}_{\mathbf{d}}$	Dimensional wave-induced velocity in x _d direction (cm/s)
$ \hat{\mathbf{u}}_{\mathbf{d}} _{\mathbf{n}}$	Dimensional amplitude of nth harmonic of wave-induced velocity in x_d direction (cm/s)
u _b	Bulk channel velocity (cm/s)
\bar{v}_d	Dimensional wavelength averaged velocity in x_d direction (cm/s)
$^{\rm v}$ d	Dimensional time-averaged velocity in y_d direction (cm/s)
vd	Dimensional fluctuating component of turbulent velocity in y_d direction (cm/s)
x _d	Dimensional horizontal Cartesian coordinate (cm)
y _d	Dimensional vertical Cartesian coordinate (cm)
y'd	Dimensional normal, Cartesian, or curvilinear distance from the wave surface as illustrated in Figure 3.5 (cm)
У _Т	Dimensional height of channel top wall in Cartesian coordinates (cm)
z	Unstretched coordinate defined by equation (3.23)

Greek	
a _d	Dimensional wavenumber (cm)
β	Angle between the wave surface and the horizontal, see equation (6.3) (°)
Y _k	Fourier coefficients in equations (3.27)-(3.29)
n	Dimensional transformed coordinate defined by equations (3.8) and (3.9)
${\sf n_T}$	Dimensional height of channel top wall in transformed coordinates (cm)
θI,n	Phase lag of nth harmonic of wave-induced streamwise intensity from downstream crest (°)
$^{ heta}\hat{p}$,n	Phase lag of nth harmonic of wave-induced surface pressure from downstream crest (°)
θ̂τ,n	Phase lag of nth harmonic of wave-induced surface shear stress from downstream crest (°)
$^{ heta}$ û,n	Phase lag of nth harmonic of wave-induced velocity in \mathbf{x}_{d} direction from downstream crest (°)
κ	von Karman constant
λ	Dimensional wavelength (cm)
ν	Kinematic viscosity (cm ² /s)
ν _t	Turbulent viscosity (cm ² /s)
ε	Dimensional transformed coordinate defined by equations (3.8) and (3.9)
ρ	Density of fluid (gm/cm ³)
^τ d	Dimensional surface shear stress (dyne/cm)
₹d	Dimensional wavelength averaged surface shear stress (dyne/cm)
$ \hat{\tau} _n$	Dimensional amplitude of nth harmonic of wave-induced surface shear stress (dyne/cm ²)
τ _w	Dimensional wall shear stress for flat surface (dyne/cm ²)

 φ Dimensional dependent variables in equations (3.24)-(3.29) which define finite difference and spectral approximations (cm²/s) or 1/s)

 $\psi_{\rm d}$ Dimensional time-averaged stream function (cm²/s)

 $\omega_{ ext{d}}$ Dimensional time-averaged vorticity (1/s)

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APPENDIX A

LISTING OF NONLINEAR CHANNEL
COMPUTER PROGRAM

```
TEXT
      PROGRAM MAIN
C
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA.JN1.JS1
      COMMON/PVAR/PO.P(2600), PS(2600), PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/XYD/PXX(2600), PYY(2600), PXY(2600)
      COMMON/WVAR/W(2600), WS(2600), WN(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200),Z2(200),Z3(200),Z1H(200),Z2H(200),Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/TRANS/SX(2600),SY(2600),SXX(2600),SXY(2600)
     & ,SXS(2600),SYS(2600),SXSY(2600)
      COMMON/MAT/DJ(300000), ICI(300000), IRP(3000), MAXA
      COMMON/AMAT/ABD(32,32), IPVT(32)
      COMMON/EDVIS/T(2600), TN(2600), TNN(2600), TXX(2600),
                     TYY(2600), TXY(2600), TS(2600), TSS(2600),
     &
                     TW(2600), TWSS(2600), TWNN(2600), TT(2600),
                     EX(2600), AU(32), AS(32)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      COMMON/CDATA/XXX(400)
      COMMON/FRED/RH
      COMMON/KONST/CC1
      COMMON/KUZ/ETAT
      COMMON/TEST1/INDEX1
      COMMON/BUM/NDUK
      DIMENSION F1(2600),F(2600)
C**
      WRITE(52, 1001)
1001 FORMAT(' **TURBULENT CALCULATION SPECTRAL EQNS 2NTH MODES**'
     &,/,' ** REVISION 12/10/85 MODEL C* OR D*,
     &,/,' ** USING THE CESS EDDY VISCOSITY PROFILE **')
      WRITE(52, 1005)
 1005 FORMAT(' THIS PROGRAM IS A MODIFICATION OF THE BOUNDARY
     & LAYER CODE BY MCLEAN TO THE CASE OF CHANNEL FLOW ')
      WRITE(52, 1004)
1004 FORMAT(' MODIFIED BY K.A. FREDERICK & J.D. KUZAN ',/)
      WRITE(52, 1003)
1003 FORMAT(' THE DISTANCES USED TO EVALUATE THE EDDY VISCOSITY
     & ARE ALONG LINES OF CONSTANT XI ')
C##
      PI=4.DO*DATAN(1.DO)
      LDA=32
      DEL=1.D-6
      DEL2=DEL+DEL
C**
      GENERATE CONFORMAL MAP & COMPUTE JACOBIAN
C**
      COMPUTE SCALE FACTORS FOR STRETCHING
```

```
CALL INIT(ST)
      NE=NP1*M
      PARAMETERS FOR SPARSE MATRIX SOLVER
      CHKT=.0001D0
      PIVT=.0001D0
C**
      INITIALIZE DATA FOR FFT
      CALL CINIT(NP1)
      CALL HSET(ST)
C**
      COMPUTE BOUNDARY CONDITIONS
      CALL FLEXBC(F)
C**
      GENERATE INITIAL GUESS FOR STREAMFUNCTION
      CALL GUESS(F)
      INDEX1=0
C**
      START OF NEWTON ITERATION
100
      INDEX1=INDEX1+1
      COMPUTE STREAMFUNCTION DERIVATIVES...VORTICITY & DERIVS **
C**
      CALL PPRIME(F1)
      CALL XYDER
      CALL VORT
      CALL WPRIME(F1)
C**
      COMPUTE EDDY VISCOSITY
      CALL MIX(F)
      CALL EDDY(F)
C**
      COMPUTE RESIDUAL
      CALL RES(F)
      DO 250 NI=1,NP1*MP2
C**
      PRINT OUT RESIDUALS
      WRITE(54, 101)NI,F(NI)
  101 FORMAT(1X, 15, 3X, F30.20)
250
      CONTINUE
      CLOSE(54)
      XA=O.DO
      DO 200 I=1,NP1*MP2
      XB=DABS(F(I))
200
      IF (XA.LT.XB) XA=XB
C**
      PRINT OUT MAXIMUM RESIDUAL
      WRITE(53, 1002) INDEX1, XA
      CLOSE(53)
1002 FORMAT(' INDEX1= ',13, ' MAXIMUM RESIDUAL IS: ',E12.6)
      IF (XA.LT.1.D-6) GOTO 1000
      IF (XA.GT.1.D7) GOTO 5000
      IF (INDEX1.EQ.10) GOTO 1000
      CALL PRESSURE(F)
C**
      COMPUTE JACOBIAN AND SOLVE LINEAR SYSTEM
C**
      (SPARSE MATRIX SOLVER BY M.A. STADTHERR)
      CALL FDJAC(F,F1)
      CALL TRANPR(NE)
      CALL LUISOL(NE, CHKT, PIVT, F, F1)
C**
      UPDATE STREAMFUNCTION, AT THE INTERIOR POINTS ONLY
      DO 300 I=1,NP1*M
      P(I+NP1)=P(I+NP1)-F1(I)
300
      CONTINUE
```

NRQ=(NP1*MP2)-((2*NP1)-1)P(NP1*MP2-NP1)=P(NRQ)PRINT OUT STREAMFUNCTION SO THAT PROGRAM CAN BE C** RESTARTED IF COMPUTER GOES DOWN C DO 301 I=1,NP1*MP2 WRITE(56,*) I,P(I) 301 CLOSE(56) GOTO 100 C** END OF NEWTON ITERATION CONTINUE 1000 OUTPUT RESULTS: NORMAL AND TANGENTIAL STRESSES , DRAG COEFF, ETC. * C** CALL PRESSURE(F) CALL EXIT 5000 STOP **END** C**

```
SUBROUTINE INIT(ST)
C**
C**
      SUBROUTINE TO GENERATE COORDINATE SCALINGS
C**
      IMPLICIT REAL*8(A-H.O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200),Z2(200),Z3(200),Z1H(200),Z2H(200),Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/TRANS/SX(2600),SY(2600),SXX(2600),SXY(2600)
     & ,SXS(2600),SYS(2600),SXSY(2600)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      COMMON/FRED/RH
      COMMON/KUZ/ETAT
      DIMENSION PSJ(32)
C**
C**
      INPUT PARAMETERS
      DATA RK, A, RK1, RKL/0.48D0, 33.D0, -35.D0, 1800.D0/
      DATA RH, RE, C/O.2DO, 77.89DO, O.DO/
      DATA M, YT, BZ, N/59, 1.DO, 5.0DO, 31/
C**
      WRITE(52,1001)A,RK1,RKL
      FORMAT(' VAN-DRIEST: A=',F5.2,' K1=',F6.2,' KL=',F7.2)
1001
      WRITE(52,2000)RH
2000 FORMAT(' 2A/LAMBDA=',F12.5)
      WRITE(52,2001)RE
      FORMAT(' REYNOLDS NUMBER=',F10.4)
      WRITE(52,2002)C
2002 FORMAT(' C/U*=',F6.3)
      WRITE(52,2003)M
2003
      FORMAT(' # OF VERT INTERIOR MESH PTS =',15)
      WRITE(52,2004)YT
```

```
2004 FORMAT(' 2H/LAMBDA=',F6.3)
      WRITE(52,2005)BZ
      FORMAT(' VERT. STRETCHING PARAM.=',F5.2)
2005
      WRITE(52,2006) N,RK
      FORMAT(' # OF HORIZ. INTERIOR MESH PTS =',14,'VON KARMAN=',F5.2)
2006
      AMP=PI*RH
      ZT=2.DO*PI*YT
      REI=1.DO/RE
      NP1=N+1
      NP2=NP1+1
      N2=NP2+NP1
      N3=NP1+N2
      MP1 = M + 1
      MP2=M+2
      DX=2.DO*PI/NP1
C**
      COMPUTE FOURIER COEFFICIENTS OF CONFORMAL MAP
      CALL WALL(AMP, ZT, YO, PHS, B)
C**
C**
      COMPUTE STRETCHING & VERTICAL SCALE FACTORS
C**
      CALL WHY(YO,ZT,BZ)
      DO 10 J=0,MP1
      J1=J+1
      Z1H(J1)=Z1(J1)/2.D0
      Z2H(J1)=Z2(J1)/2.D0
      Z3H(J1)=Z3(J1)/2.D0
      ZA(J1)=Z1(J1)*Z1(J1)*Z1(J1)/2.D0
      ZB(J1)=3.D0*Z1(J1)*Z2(J1)
      Z1S(J1)=Z1(J1)*Z1(J1)
10
      CONTINUE
C**
C**
      JACOBIAN OF TRANSFORMATION
C**
      NJ=-N
      DO 130 J=0,MP1
      NJ=NJ+NP1
      PSI=-DX
      DO 120 I=0,N
      PSI=PSI+DX
      NI = I + NJ
      XS=1.D0
      XN=O.DO
      XSS=0.DO
      XSN=O.DO
      DO 110 I1=1,14
      SN=DSIN(I1*PSI)
      CS=DCOS(I1*PSI)
      CH=DCOSH(I1*(ETAT-ETA(J+1)))/DSINH(I1*ETAT)
      SH=DSINH(I1*(ETAT-ETA(J+1)))/DSINH(I1*ETAT)
      XS=XS+B(I1)*CS*CH
      XN=XN-B(I1)*SN*SH
      XSS=XSS-I1*B(I1)*SN*CH
```

```
XSN=XSN-I1*B(I1)*CS*SH
110
      CONTINUE
      XJ=1.DO/(XS*XS+XN*XN)
      JA(NI)=XJ
      JS1(NI)=-2.D0*XJ*(XS*XSS+XN*XSN)
      JN1(NI)=-2.D0*XJ*(XS*XSN-XN*XSS)
      XJ3=XJ*XJ*XJ
      XA=XS*(3.DO*XN*XN-XS*XS)
      XB=XN*(3.DO*XS*XS-XN*XN)
      SX(NI)=XS*XJ
      SY(NI) = -XN*XJ
      SXS(NI)=SX(NI)*SX(NI)
      SYS(NI)=SY(NI)*SY(NI)
      SXSY(NI)=SX(NI)*SY(NI)
      SXX(NI)=XJ3*(XSS*XA-XSN*XB)
120
      SXY(NI)=XJ3*(XSS*XB+XSN*XA)
130
      CONTINUE
C**
      TERMS FOR MIXING LENGTH
C**
      COMPUTE TANGENTIAL DISTANCES AT SURFACE
      ST=0.D0
      DO 135 I=1,NP1
135
      ST=ST+1.DO/DSQRT(JA(I))
      ST=DX*ST/(2.DO*PI)
      SC=RK1/(0.6D0*RE*DSQRT(ST*ST+(RKL/RE)**2))
      ET(1)=SC
      ETM(1)=1.D0
      DO 150 I=1,N
      S=-0.5D0/DSQRT(JA(1))-0.5D0/DSQRT(JA(I+1))
      DO 140 K=0,I
140
      S=S+1.DO/DSQRT(JA(K+1))
      S=DX*S
      TEE=S-I*DX*ST
      ETM(I+1)=DEXP(-TEE*RE/RKL)
150
      ET(I+1)=SC/ETM(I+1)
C**
C**
C**
      CALCULATE Y DISTANCES FOR EDDY VISCOSITY BY GOING
      ALONG COORDINATE OF CONSTANT XI
C
C
      (DISCRETE ARC LENGTH CALCULATION)
      DO 186 I=1,NP1
      NN=0
      SUM=0.DO
      SUM1=0.DO
      PSJ(I)=((I-1)/8.D0)*2.D0*PI
      DO 176 J=0,NP1*MP2-NP1,NP1
      NI = I + J
      NN=NN+1
      DO 90 K=1,14
      A1=DSINH(K*(ETAT-ETA(NN)))
      A2=DSINH(K*ETAT)
      SUM=SUM+(B(K)/K)*DCOS(K*PSJ(I))*A1/A2
  90
      CONTINUE
```

```
DO 95 KK=1,14
       A3=DCOSH(KK*(ETAT-ETA(NN)))
       A4=DSINH(KK*ETAT)
      SUM1=SUM1+(B(KK)/KK)*DSIN(KK*PSJ(I))*A3/A4
  95 CONTINUE
      XX = (SUM1 + PSJ(I))
      Y=(ETA(NN)+YO-SUM)-AMP*DCOS(XX)
      IF(J.EQ.0)GOTO 170
      DN(NI)=DN(NI-NP1)+RK*DSQRT((XOLD-XX)**2 + (YOLD-Y)**2)
      DB(NI) = -(DN(NI)/RK)*RE/A
      IF(NI.GT.NP1*MP2-NP1)THEN
      DMAX=DN(NI)
      END IF
 170 XOLD=XX
      YOLD=Y
      SUM=0.DO
      SUM1=0.DO
176
      CONTINUE
      NSQT=NP1*MP2-NP1
      NSQR=((NP1*MP2-NP1)/2)
      PO 172 J=NSQT,NSQR,-NP1
      NI = I + J
      DN(NI)=DMAX-DN(NI)
      DB(NI) = -(DN(NI)/RK)*RE/A
 172
      CONTINUE
186
      CONTINUE
      PETURN
      END
C**
C**
      SUBROUTINE WALL (AMP, ZT, YO, PHS, B)
C**
C**
      COMPUTE FOURIER COEFFICIENTS OF CONFORMAL MAP
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      DIMENSION X(15), Y(15), Z(15), B(1), A(5), F(15), IPVT(15), DJ(15, 15)
C**
      LDJ=15
      N = 14
C**
      PARAMETERS FOR A RIGID SINUSOIDAL WALL
      WRITE(52, 1001)
      FORMAT(' SINUSOIDAL WAVE PROFILE')
      A(1)=AMP
      A(2)=0.D0
      A(3)=0.D0
      A(4) = 0.D0
      A(5)=0.D0
      PHS=1.D0
      NP 1=N+1
      INDEX=0
      PI=4.DO*DATAN(1.DO)
      XA=PI/NP1
```

```
C**
      INITIAL GUESS
      DO 10 I=1,NP1
      Z(I)=(I-1)*XA
10
      B(I)=0.D0
      B(1) = -AMP
      Y0=0.D0
C**
      COMPUTE RESIDUAL
20
      INDEX=INDEX+1
      DO 40 I=1,NP1
      S1=0.D0
      S2=0.D0
      DO 30 J=1,N
      S1=S1+B(J)*DSIN(J*Z(I))/(J*DTANH(J*ZT))
30
      S2=S2+B(J)*DCOS(J*Z(I))/J
      X(I)=S1+Z(I)
      Y(I)=Y0-S2
      S1=0.D0
      DO 35 I1=1,5
35
      S1=S1+A(I1)*DCOS(I1*X(I))
40
      F(I)=S1-Y(I)
      XA=0.DO
      DO 50 I=1,NP1
      XB=DABS(F(I))
50
      IF(XB.GT.XA)XA=XB
      IF (XA.LT.1.D-10) GOTO 1000
      IF (XA.GT.10.D0) GOTO 5000
      IF (INDEX.GT.10) GOTO 5000
C**
      COMPUTE RESIDUAL
      DO 70 I=1,NP1
      S1=0.D0
      DO 55 I1=1,5
      S1=S1+I1*A(I1)*DSIN(I1*X(I))
55
      DO 60 J=1,N
      DJ(I,J)=(DCOS(J*Z(I))-S1*DSIN(J*Z(I))/DTANH(J*ZT))/J
60
70
      DJ(I,NP1)=-1.DO
      JOB=0
      CALL DGEFA(DJ,LDJ,NP1,IPVT,INFO)
      CALL DGESL(DJ,LDJ,NP1,IPVT,F,JOB)
      DO 80 I=1,N
80
      B(I)=B(I)-F(I)
      Y0=Y0-F(NP1)
      GOTO 20
1000
      CONTINUE
      RETURN
5000
      WRITE(52, 1002)
      FORMAT(' THE CONFORMAL MAPPING DID NOT CONVERGE')
1002
      CALL EXIT
      END
C**
      SUBROUTINE WHY(YO,ZT,BZ)
C**
      IMPLICIT REAL*8(A-H,O-Z)
```

```
IMPLICIT INTEGER*4(I-N)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200),Z2(200),Z3(200),Z1H(200),Z2H(200),Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/KUZ/ETAT
C**
C**
      COMPUTE STRETCHING IN THE NORMAL DIRECTION
C**
C**
C**
      MODIFIED TO STRETCH AT BOTH TOP AND
C**
      BOTTOM WALLS
C**
C**
      DZ=1.DO/MP1
      ETAT=ZT-YO
      C1=DATAN(BZ)
      C2=DATAN(-BZ)
      C3=BZ*ETAT
      C4=BZ**2.D0
      C5=BZ*4.D0
      C6=C1/ETAT
      C7=C6*C5
      ETA(1)=0.DO
      DO 18 J=0,MP1
      Z8=J*DZ
      A1=(1-2.D0*Z8)
      A11=DATAN(-BZ*A1)
      A2=A1**2.D0
      IF (J.EQ.O) THEN
      ETA(1)=0.D0
      GO TO 1
      END IF
      ETA(J+1)=ETAT*((A11-C2)/(2.D0*C1))
1
      ETA(1)=0.D0
      Z1(J+1)=((1.D0+C4*A2)*C1)/C3
      Z2(J+1)=((C1/ETAT)*(-C5*A1))*Z1(J+1)
      Z3(J+1)=(C7*((-A1*Z2(J+1))+(2.D0*(Z1(J+1)**2.D0))))/DZ
      Z2(J+1)=Z2(J+1)/DZ
      Z1(J+1)=Z1(J+1)/DZ
18
      CONTINUE
      RETURN
      END
C**
C**
      SUBROUTINE HSET(ST)
C**
C**
      COMPUTES FACTORS TO TAKE DERIVATES BY FFT
C**
      COMPUTES FACTORS TO SHIFT PHASE BY FFT
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
```

```
COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
C**
      PI2=2.D0*PI
      RN=1.DO/NP1
      NH=NP1/2-1
      STS=ST*ST
      RS=(RKL/RE)**2
      DO 20 I=0,NH
      HS(I+1)=RN*I
      HSS(I+1)=-I*I*RN
      SCI=DSQRT((STS+RS)/(STS+I*I*RS))
      IF (I.EQ.0) SCI=1.DO
      PHI=DATAN(I*RKL/(RE*ST))
      SHR(I+1)=RN*DCOS(PHI)*SCI
20
      SHI(I+1)=-RN*DSIN(PHI)*SCI
      DO 30 I=NH+1.N
      K=I-NP1
      HS(I+1)=RN*K
      HSS(I+1)=-K*K*RN
      SCI=DSQRT((STS+RS)/(STS+K*K*RS))
      PHI=DATAN(K*RKL/(RE*ST))
      SHR(I+1)=RN*DCOS(PHI)*SCI
30
      SHI(I+1)=-RN*DSIN(PHI)*SCI
      DO 40 I=1,NP1
40
      ZERO(I)=0.DO
      RETURN
      END
C**
C**
      SUBROUTINE FLEXBC(F)
C**
C**
      COMPUTES BOUNDARY CONDITIONS
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/WVAR/W(2600), WS(2600), WN(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
    & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/TRANS/SX(2600),SY(2600),SXX(2600),SXY(2600)
    & ,SXS(2600),SYS(2600),SXSY(2600)
      COMMON/EDVIS/T(2600), TN(2600), TNN(2600), TXX(2600),
    &
                    TYY(2600), TXY(2600), TS(2600), TSS(2600),
    &
                    TW(2600), TWSS(2600), TWNN(2600), TT(2600),
                    EX(2600), AU(32), AS(32)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
    & ,HS(32),HSS(32),ZERO(32)
```

```
& ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      DIMENSION F(1)
C**
      NJ = 1 + NP1*MP1
      BOUNDARY CONDIIONS AT WALL
C**
      DO 20 I=0,N
      P(I+1)=0.D0
      PS(I+1)=0.D0
      PSS(I+1)=0.D0
      TT(I+1)=0.D0
      T(I+1)=REI
      TS(I+1)=0.D0
      TSS(I+1)=0.D0
      PN(I+1)=-C/SX(I+1)
      US(I+1)=-JA(I+1)*PN(I+1)*PN(I+1)/2.D0
C**
      BOUNDARY CONDITIONS AT UPPER BOUNDARY
      NI = I + NJ
      TT(NI)=0.D0
      T(NI)=REI
      THE UPPER B.C.'S ON TS &TSS ARE ACTUALLY SET IN SUBR EDDY
C**
      TS(NI)=0.D0
      TSS(NI)=0.D0
    ******************
C
       THE FOLLOWING IS CALCULATED IN GUESS
C
C
C
       P(NI)=PO
C
    ***************
      PS(NI)=0.D0
      PSS(NI)=0.D0
      PN(NI)=0.D0
20
      CONTINUE
      CALL PF(NP1,US,ZERO,1,F(1),F(NP2),1)
      DO 30 I=1,NP1
      US(I)=-HS(I)*F(I+NP1)
      F(I)=HS(I)*F(I)
30
      CALL FP(NP1,US,F,1,US,F,1)
      RETURN
      END
C**
C**
      SUBROUTINE GUESS(F)
C
C**
      INITIAL GUESS FOR STREAMFUNCTION
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/CON/N, M, NP1, NP2, N2, N3, MP1, MP2, RE, REI, RK, A, C, PI, DX, RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
```

```
COMMON/SCALE/Z1(200),Z2(200),Z3(200),Z1H(200),Z2H(200),Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/EDVIS/T(2600), TN(2600), TNN(2600), TXX(2600),
                     TYY(2600), TXY(2600), TS(2600), TSS(2600),
     &
     &
                     TW(2600), TWSS(2600), TWNN(2600), TT(2600),
                     EX(2600), AU(32), AS(32)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      COMMON/TRANS/SX(2600),SY(2600),SXX(2600),SXY(2600)
     & ,SXS(2600),SYS(2600),SXSY(2600)
      COMMON/MIXL/RL(100)
      DIMENSION F(1), PSI(200), TTINIT(200)
C
      PN(1) = -C/SX(1)
C.
  .... USE THE SAME STREAMFUNCTION
      AT ALL X POSITIONS
      READ(40,*)(PSI(J),J=1,MP2)
C
      (INITIAL GUESS FOR STREAMFUNCTION MUST BE INPUT.
C
       OBTAIN INITIAL GUESS BY RUNNING FLAT CHANNEL
C
       PROGRAM.)
      DO 70 J=1,MP2
      NJ = 1 + NP 1*(J-1)
      DO 60 I=0,N
      TT(I+NJ)=TTINIT(J)
60
      P(I+NJ)=PSI(J)
70
      CONTINUE
C....STREAMFUNCTION AT UPPER BOUNDARY (MASS FLOWRATE)
      PO=P(1+NP1*MP1)
   80 CONTINUE
      RETURN
      END
C**
C**
      SUBROUTINE PPRIME(F)
C**
C**
      COMPUTE STREAMFUNCTION DERIVATIVES
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA.JN1.JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200), Z2(200), Z3(200), Z1H(200), Z2H(200), Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      DIMENSION F(1)
C**
      COMPUTE TANGENTIAL (S) DERIVATIVES
      NJ = 1
```

```
DO 20 J=1.M
      NJ=NJ+NP1
      CALL PF(NP1,P(NJ),ZERO,1,F(1),F(NP2),1)
      DO 10 I=0,N
      NI = I + NJ
      PS(NI)=-HS(I+1)*F(I+NP2)
      F(I+N2)=HS(I+1)*F(I+1)
      PSS(NI)=HSS(I+1)*F(I+1)
      F(I+NP2)=HSS(I+1)*F(I+NP2)
10
      CALL FP(NP1,PS(NJ),F(N2),1,PS(NJ),F(N2),1)
      CALL FP(NP1,PSS(NJ),F(NP2),1,PSS(NJ),F(NP2),1)
20
      CONTINUE
      COMPUTE NORMAL (N) DERIVATIVES AT INTERIOR POINTS
C**
      NJ=1
      DO 40 J=1,M
      J1=J+1
      NJ=NJ+NP1
      DO 30 I=0,N
      NI = I + NJ
      NP=NI+NP1
      NPP=NI+NP1+NP1
      NM=NI-NP1
      NMM=NI-NP1-NP1
      PZ=P(NP)-P(NM)
      PZZ=P(NP)-P(NI)-P(NI)+P(NM)
      IF (NMM.LE.O) GO TO 21
      PZZZ=P(NPP)-P(NP)-P(NP)+P(NM)+P(NM)-P(NMM)
      PNNN(NI)=ZA(J1)*PZZZ+ZB(J1)*PZZ+Z3H(J1)*PZ
21
      CONTINUE
      PN(NI)=Z1H(J1)*PZ
      PNN(NI)=Z1S(J1)*PZZ+Z2H(J1)*PZ
      UN=JA(NI)*(PNN(NI)+JN1(NI)*PN(NI)-PSS(NI)-JS1(NI)*PS(NI))
      UZ(NI)=DABS(UN)
      CONTINUE
30
40
      CONTINUE
      COMPUTES Y DERIVATIVES AT Z=0,H
      DO 50 I=0,N
      I1=I+1
      PB=P(I1+NP1)-PN(I1)/Z1H(1)
      PNN(I1)=Z1S(1)*(P(I1+NP1)+PB)+Z2H(1)*(P(I1+NP1)-PB)
      UN=JA(I1)*(PNN(I1)+JN1(I1)*PN(I1))
      UZ(I1)=DABS(UN)
      NI=I1+NP1
      NM=I1
      NP=NI+NP1
      NPP=NI+NP1+NP1
      PZ=P(NP)-P(NM)
      PZZ=P(NP)-P(NI)-P(NI)+P(NM)
      PZZZ=P(NPP)-P(NP)-P(NP)+P(NM)+P(NM)-PB
      PNNN(NI)=ZA(2)*PZZZ+ZB(2)*PZZ+Z3H(2)*PZ
50
      CONTINUE
      RETURN
```

```
END
C**
C**
      SUBROUTINE XYDER
C**
C**
      COMPUTE CARTESIAN DERIVATIVES OF STREAMFUNCTION
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/XYD/PXX(2600), PYY(2600), PXY(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200),Z2(200),Z3(200),Z1H(200),Z2H(200),Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/TRANS/SX(2600),SY(2600),SXX(2600),SXY(2600)
     & ,SXS(2600),SYS(2600),SXSY(2600)
      COMMON/TEST1/INDEX1
C**
      DO 20 J=1,M
      NJ=1+NP1*J
      J1=J+1
      DO 10 I=0,N
      NI = I + NJ
      PSN=Z1H(J1)*(PS(NI+NP1)-PS(NI-NP1))
      X1=(SXSY(NI)+SXSY(NI))*PSN-SXX(NI)*PS(NI)+SXY(NI)*PN(NI)
      PXX(NI)=PSS(NI)*SXS(NI)+PNN(NI)*SYS(NI)-X1
      PYY(NI)=PSS(NI)*SYS(NI)+PNN(NI)*SXS(NI)+X1
      PXY(NI)=SXSY(NI)*(PSS(NI)-PNN(NI))+(SXS(NI)-SYS(NI))*PSN
     & +PS(NI)*SXY(NI)+PN(NI)*SXX(NI)
10
      CONTINUE
20
      CONTINUE
      RETURN
      END
C**
C**
      SUBROUTINE VORT
C**
C**
      COMPUTE VORTICITY
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/WVAR/W(2600), WS(2600), WN(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/NEW/JA(2600),JN1(2600),JS1(2600),B(15),Y0,ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
C**
      NJ=-N
```

```
DO 20 J=0,M
      NJ=NJ+NP1
      DO 10 I=0,N
      NI = I + NJ
10
      W(NI) = -JA(NI)*(PSS(NI)+PNN(NI))
20
      CONTINUE
      RETURN
      END
C**
C**
      SUBROUTINE WPRIME(F)
C**
C**
      COMPUTE DERIVATIVES OF THE VORTICITY
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA.JN1.JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/WVAR/W(2600), WS(2600), WN(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200),Z2(200),Z3(200),Z1H(200),Z2H(200),Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      DIMENSION F(1)
C**
C**
      COMPUTE TANGENTIAL DERIVATIVES
      DO 25 J=0.M
      NJ = 1 + NP 1 * J
      CALL PF(NP1,W(NJ),ZERO,1,F(1),F(NP2),1)
      DO 10 I=0,N
      NI = I + NJ
      WS(NI)=-HS(I+1)*F(I+NP2)
      F(I+1)=HS(I+1)*F(I+1)
C**
      COMPUTE NORMAL DERIVATIVES
      IF (NI.LE.8) GO TO 10
      WN(NI)=(Z1H(J+1)*(PSS(NI-NP1)-PSS(NI+NP1))-PNNN(NI))*JA(NI)
     \& +JN1(NI)*W(NI)
10
      CONTINUE
      CALL FP(NP1,WS(NJ),F(1),1,WS(NJ),F(1),1)
25
      CONTINUE
      RETURN
      END
C**
C**
      SUBROUTINE MIX(F)
C**
C**
      COMPUTE EDDY VISCOSITY BY NEWTONS METHOD
C**
      VAN-DRIEST CORRECTION:
C**
      WALL VALUES FOR PRESSURE...LAG EQUATION FOR PRESSURE
```

```
C**
      LOCAL VALUES FOR SHEAR STRESS
C**
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/WVAR/W(2600), WS(2600), WN(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200),Z2(200),Z3(200),Z1H(200),Z2H(200),Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/AMAT/ABD(32,32), IPVT(32)
      COMMON/EDVIS/T(2600), TN(2600), TNN(2600), TXX(2600),
                     TYY(2600), TXY(2600), TS(2600), TSS(2600),
     &
                     TW(2600), TWSS(2600), TWNN(2600), TT(2600),
                     EX(2600), AU(32), AS(32)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      COMMON/BUM/NDUK
      COMMON/NFRED/NC
      COMMON/MIXL/RL(100)
      DIMENSION F(1), RES(32), QT(2600)
C**
      INDEX=0
C**
      COMPUTE TWNN FROM MOMENTUM EQN AT Z=0
      DO 10 I=0.N
      I1=I+1
10
      TW(I1)=T(I1)*W(I1)
      CALL PF(NP1, TW, ZERO, 1, F(1), F(NP2), 1)
      DO 20 I=1.NP1
      TWSS(I)=HSS(I)*F(I)
20
      F(I)=HSS(I)*F(I+NP1)
      CALL FP(NP1,TWSS,F,1,TWSS,F,1)
      DO 30 I=1,NP1
30
      TWNN(I)=WS(I)*PN(I)-TWSS(I)
C**
      START OF ITERATION FOR MIXING LENGTH
40
      INDEX=INDEX+1
      NJ=NP2
      DO 50 I=0,N
      NI = I + NJ
      TT(NI)=RL(NI)*RL(NI)*UZ(NI)
      T(NI)=TT(NI)+REI
50
      TW(NI)=T(NI)*W(NI)
C**
      COMPUTE UNSHIFTED PRESSURE TERM
      XA=0.DO
      DO 70 I=0.N
      I1=I+1
      TM=(TWNN(I1)+2.D0*Z1S(1)*TW(I1)-(Z1S(1)+Z2H(1))*TW(I1+NP1))
     \& /(Z1S(1)-Z2H(1))
      TN(I1)=Z1H(1)*(TW(I1+NP1)-TM)
```

```
70
      AU(I1)=ET(I1)*(US(I1)-TN(I1))
C**
      SHIFT THE PRESSURE BY FFT
      CALL PF(NP1,AU,ZERO,1,F(1),F(NP2),1)
      DO 80 I=0,N
      I1 = I + 1
      AS(I1)=SHR(I1)*F(I1)-SHI(I1)*F(I+NP2)
80
      F(I1)=SHR(I1)*F(I+NP2)+SHI(I1)*F(I1)
      CALL FP(NP1,AS,F,1,AS,F,1)
C**
      COMPUTE MODIFIED VAN-DRIEST FACTOR
      DO 81 I=1.NP1
      PR=ETM(I)*AS(I)
81
      AS(I)=1.DO+0.6DO*DTANH(PR)
C**
      COMPUTE THE RESIDUAL
      DO 90 I=0,N
      NI = I + NJ
C**
      COMMENT THE FOLLOWING LINE FOR MODEL D*
C
      AS(I+1)=1.0
      EX(NI)=DB(NI)*DSQRT(T(NI)*UZ(NI))/AS(I+1)
      EX(NI)=DB(NI)
C**
      CONSTANT BOUNDARY LAYER THICKNESS EQUAL TO THE HALF
C
      HEIGHT OF A FLAT CHANNEL WITH THE SAME AVERAGE
C
      CROSS SECTION
      DELTA=ZT/2.DO
      RES(NI-NP1)=RL(NI)-DN(NI)*(1.DO-DEXP(EX(NI)))
      XB=DABS(RES(NI-NP1))
90
      IF (XA.LT.XB) XA=XB
      JF (XA.LT.1.D-11) GOTO 120
      IF (INDEX.GT.100) GOTO 500
      IF (XA.GT.1.D3) GOTO 500
C**
      COMPUTE THE JACOBIAN AND SOLVE
      CALL AJAC(F)
      JOB=0
      CALL DGEFA(ABD, LDA, NP1, IPVT, INFO)
      CALL DGESL(ABD, LDA, NP1, IPVT, RES, JOB)
      DO 110 I=1,NP1
110
      RL(I+NP1)=RL(I+NP1)-RES(I)
      GOTO 40
C**
      END OF NEWTON ITERATION AT Z=O
120
      CONTINUE
      INDEX=0
C**
      START OF NEWTON FOR EDDY VISCOSITY AT INTERIOR POINTS
200
      INDEX=INDEX+1
      XA=O.DO
      DO 220 J=2,M
      NJ=1+NP1*J
      DO 210 I=0,N
      NI=I+NJ
      T(NI)=TT(NI)+REI
C**
      COMMENT THE FOLLOWING LINE FOR MODEL D*,
C**
      UNCOMMENT THE LINE FOR MODEL C*
C
      AS(I+1)=1.0
      EX(NI)=DB(NI)*DSQRT(T(NI)*UZ(NI))/AS(I+1)
```

```
IF(J.EQ.MP1/2)EX(NI) = -1000.D0
       IF(J.GT.MP1/2)EX(NI)=DB(NI)
       A1=(2.0*RK*RE*(DN(NI)/RK)/3.0)**2
       A2=(1.0-0.5*DN(NI)/(RK*DELTA))**2
       A3=(3.0-4.0*DN(NI)/(RK*DELTA)+2.0*(DN(NI)/(RK*DELTA))**2)**2
       A4 = (1.0 - EXP(EX(NI))) **2
       QT(NI)=0.5*(1.0/RE)*SQRT(1.0+A1*A2*A3*A4)-0.5*(1.0/RE)
       F(NI)=TT(NI)-QT(NI)
       XB=DABS(F(NI))
       IF (XA.LT.XB) XA=XB
 210
       CONTINUE
 220
       IF (XA.LT.1.D-11) GOTO 300
       IF (XA.GT.1.D3) GOTO 500
       IF (INDEX.GT.100) GOTO 500
       DO 240 J=2,M
       NJ=1+NP1*J
       DO 230 I=0,N
       NI = I + NJ
       Y=DN(NI)/RK
       YH=Y/DELTA
 C**
       COMMENT THE FOLLOWING LINE FOR MODEL D*,
 C**
       UNCOMMENT THE LINE FOR MODEL C*
 C
       AS(I+1)=1.0
       Z=-(RE*Y/A)*DSQRT(T(NI)*UZ(NI))/AS(I+1)
       IF(J.EQ.MP1/2)Z=-1000.D0
       ZP=(RE*Y*UZ(NI)/(2.DO*A))/AS(I+1)
       ZP=-ZP*(1.DO/DSQRT(T(NI)*UZ(NI)))
       ZZ=(1.D0/(2.D0*RE))**2
       ZZZ=(3.D0-4.D0*YH+2.D0*YH**2)**2
       ZZZ=ZZZ*(1.DO-0.5DO*YH)**2
       ZZZ=ZZZ*(2.DO*K*RE*Y/3.DO)**2
       ZZZ=ZZZ*ZZ
       DF=2.D0*ZZZ*(1.D0-DEXP(Z))*(-ZP*DEXP(Z))
       DF=DF*(1.DO/DSQRT(ZZ+ZZZ*(1.DO-DEXP(Z))**2))
       DF=1.DO-0.5DO*DF
       IF(J.GT.MP1/2)DF=1.D0
       TT(NI)=TT(NI)-F(NI)/DF
 230
       CONTINUE
 240
       CONTINUE
       GOTO 200
.. C**
       END OF NEWTON AT INTERIOR POINTS
 C**
       COMPUTE OTHER VARIABLES AT THE UPPER BOUNDARY
 300
       NJ = 1 + NP1*MP1
       DO 305 I=0,N
       NI=I+NJ
       IF (NDUK.GT.O) THEN
       JP=NC+2*NP1
       PNN(JP)=2.D0*Z1S(MP2)*(P(JP-NP1)-P(JP))
       W(JP) = -JA(JP) *PNN(JP)
       GO TO 597
       END IF
       PNN(NI)=-RE/JA(NI)
```

```
W(NI)=RE
C**
      Y DERIVATIVE AT Z=1,1-H
      PT=(PNN(NI)+2.DO*Z1S(MP2)*P(NI)-(Z1S(MP2)-Z2H(MP2))*P(NI-NP1))
597
         /(Z1S(MP2)+Z2H(MP2))
      NI=NI-NP1
      NP=NI+NP1
      NM=NI-NP1
      NMM=NI-NP1-NP1
      PZ=P(NP)-P(NM)
      PZZ=P(NP)-P(NI)-P(NI)+P(NM)
      PZZZ=PT-P(NP)-P(NP)+P(NM)+P(NM)-P(NMM)
      PNNN(NI)=ZA(MP1)*PZZZ+ZB(MP1)*PZZ+Z3H(MP1)*PZ
      WN(NI)=(Z1H(MP1)*(PSS(NI-NP1)-PSS(NI+NP1))-PNNN(NI))*JA(NI)
305
     & +JN1(NI)*W(NI)
      RETURN
500
      WRITE(52, 1001)
     FORMAT( ' BOMBED OUT COMPUTING EDDY VISCOSITY')
1001
      CALL EXIT
      END
C**
```

•

```
C**
      SUBROUTINE AJAC(F)
C**
      FINITE DIFFERENCE JACOBIAN FOR MIXING LENGTH COMPUTATION
C**
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/WVAR/W(2600), WS(2600), WN(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/AMAT/ABD(32,32), IPVT(32)
      COMMON/EDVIS/T(2600), TN(2600), TNN(2600), TXX(2600),
                     TYY(2600), TXY(2600), TS(2600), TSS(2600),
                     TW(2600), TWSS(2600), TWNN(2600), TT(2600),
     &
                     EX(2600), AU(32), AS(32)
     &
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      COMMON/MIXL/RL(101)
      DIMENSION ASP(32), ASM(32), F(1)
C**
      NJ=NP2
      DO 30 I=0,N
      NIO=I+NJ
      RLO=RL(NIO)
      RL(NIO)=RLO+DEL
      T(NIO)=RL(NIO)*RL(NIO)*UZ(NIO)+REI
      TW(NIO)=T(NIO)*W(NIO)
      CALL ASTAR(I, ASP, F)
      RL(NIO)=RLO-DEL
```

```
T(NIO)=RL(NIO)*RL(NIO)*UZ(NIO)+REI
      TW(NIO)=T(NIO)*W(NIO)
      CALL ASTAR(I, ASM, F)
      RL(NIO)=RLO
      T(NIO)=RL(NIO)*RL(NIO)*UZ(NIO)+REI
      TW(NIO)=T(NIO)*W(NIO)
      DO 10 I1=0,N
      NI=I1+NJ
      DA=(ASP(I1+1)-ASM(I1+1))/DEL2
      ABD(NI-NP1,NIO-NP1)=-DN(NI)*DEXP(EX(NI))*EX(NI)*DA/AS(I1+1)
10
      CONTINUE
      ABD(NIO-NP1,NIO-NP1)=1.DO+DN(NIO)*EX(NIO)*DEXP(EX(NIO))*RL(NIO)
     & *UZ(NIO)/T(NIO)+ABD(NIO-NP1,NIO-NP1)
30
      CONTINUE
      RETURN
      END
C**
C**
      SUBROUTINE ASTAR(I, ASN, F)
C**
C**
      COMPUTE NEW PRESSURE CORRECTION FOR MIXING LENGTH JACOBIAN
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & .RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200), Z2(200), Z3(200), Z1H(200), Z2H(200), Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/EDVIS/T(2600), TN(2600), TNN(2600), TXX(2600),
                    TYY(2600), TXY(2600), TS(2600), TSS(2600),
                    TW(2600), TWSS(2600), TWNN(2600), TT(2600),
     &
                     EX(2600), AU(32), AS(32)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      DIMENSION ASN(1), F(1), AUN(32)
C##
      DO 10 I1=1,NP1
10
      AUN(I1)=AU(I1)
      TM=(TWNN(I+1)+2.D0*Z1S(1)*TW(I+1)-(Z1S(1)+Z2H(1))*TW(I+NP2))
     \& /(Z1S(1)-Z2H(1))
      TN(I+1)=Z1H(1)*(TW(I+NP2)-TM)
      AUN(I+1)=ET(I+1)*(US(I+1)-TN(I+1))
      CALL PF(NP1,AUN,ZERO,1,F(1),F(NP2),1)
      DO 20 I1=1,NP1
      ASN(I1)=SHR(I1)*F(I1)-SHI(I1)*F(I1+NP1)
20
      F(I1)=SHR(I1)*F(I1+NP1)+SHI(I1)*F(I1)
      CALL FP(NP1, ASN, F, 1, ASN, F, 1)
      DO 30 I1=1,NP1
      PR=ETM(I1)*ASN(I1)
```

```
ASN(I1)=1.D0+0.6D0*DTANH(PR)
30
      RETURN
      END
C**
C**
      SUBROUTINE EDDY(F)
C**
      COMPUTE DERIATIVES OF EDDY VISCOSITY
C**
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/WVAR/W(2600), WS(2600), WN(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200),Z2(200),Z3(200),Z1H(200),Z2H(200),Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/TRANS/SX(2600),SY(2600),SXX(2600),SXY(2600)
     & ,SXS(2600),SYS(2600),SXSY(2600)
      COMMON/EDVIS/T(2600), TN(2600), TNN(2600), TXX(2600),
                    TYY(2600), TXY(2600), TS(2600), TSS(2600),
                     TW(2600), TWSS(2600), TWNN(2600), TT(2600),
     &
                     EX(2600), AU(32), AS(32)
     &
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      DIMENSION F(1)
C**
C**
      COMPUTE TW AT INTERIOR POINTS
      DO 10 J=2,MP1
      NJ = 1 + NP 1 * J
      DO 10 I=0,N
      NI=I+NJ
10
      TW(NI)=T(NI)*W(NI)
C**
      COMPUTE TANGENTIAL (S) DERIVATIVES OF T AND TW
      NJ=1
      DO 80 J=1,MP1
      NJ=NJ+NP1
      CALL PF(NP1,T(NJ),ZERO,1,F(1),F(NP2),1)
      CALL PF(NP1,TW(NJ),ZERO,1,F(N2),F(N3),1)
      DO 70 I=0,N
      NI = I + NJ
      XA=F(I+NP2)
      TS(NI)=-HS(I+1)*F(I+NP2)
      IF(NJ.EQ.1+NP1*MP1)TS(NI)=0.D0
      F(I+NP2)=HS(I+1)*F(I+1)
      TSS(NI)=HSS(I+1)*F(I+1)
      IF(NJ.EQ.1+NP1*MP1)TSS(NI)=0.D0
      F(I+1)=HSS(I+1)*XA
      TWSS(NI)=HSS(I+1)*F(I+N2)
70
      F(I+N2)=HSS(I+1)*F(I+N3)
```

```
CALL FP(NP1,TS(NJ),F(NP2),1,TS(NJ),F(NP2),1)
      CALL FP(NP1, TSS(NJ), F(1), 1, TSS(NJ), F(1), 1)
      CALL FP(NP1,TWSS(NJ),F(N2),1,TWSS(NJ),F(N2),1)
80
      CONTINUE
C**
      COMPUTE NORMAL (N) DERIVATIVES OF T AND TW
      NJ=1
      DO 100 J=1,M
      NJ=NJ+NP1
      J1=J+1
      DO 90 I=0,N
      NI = I + NJ
      TN(NI)=Z1H(J1)*(T(NI+NP1)-T(NI-NP1))
      TNN(NI)=Z1S(J1)*(T(NI+NP1)-T(NI)-T(NI)+T(NI-NP1))
     & +Z2H(J1)*(T(NI+NP1)-T(NI-NP1))
      CZ=TW(NI+NP1)-TW(NI-NP1)
      CZZ=TW(NI+NP1)-TW(NI)-TW(NI)+TW(NI-NP1)
      TWNN(NI)=Z1S(J1)*CZZ+Z2H(J1)*CZ
      COMPUTE CARTESIAN DERIVATIVES OF EDDY VISCOSITY
C**
      TYX=Z1H(J1)*(TS(NI+NP1)-TS(NI-NP1))
      X1=(SXSY(NI)+SXSY(NI))*TYX-SXX(NI)*TS(NI)+SXY(NI)*TN(NI)
      TXX(NI)=TSS(NI)*SXS(NI)+TNN(NI)*SYS(NI)-X1
      TYY(NI)=TSS(NI)*SYS(NI)+TNN(NI)*SXS(NI)+X1
      TXY(NI)=SXSY(NI)*(TSS(NI)-TNN(NI))+(SXS(NI)-SYS(NI))*TYX
90
     & +TS(NI)*SXY(NI)+TN(NI)*SXX(NI)
100
      CONTINUE
      RETURN
      END
C**
```

¥

```
C**
      SUBROUTINE RES(F)
C**
C**
      COMPUTE THE RESIDUAL AT INTERIOR POINTS
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & .PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/XYD/PXX(2600), PYY(2600), PXY(2600)
      COMMON/WVAR/W(2600), WS(2600), WN(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/EDVIS/T(2600), TN(2600), TNN(2600), TXX(2600),
                     TYY(2600), TXY(2600), TS(2600), TSS(2600),
     &
                     TW(2600), TWSS(2600), TWNN(2600), TT(2600),
     &
                     EX(2600), AU(32), AS(32)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      COMMON/NFRED/NC
      DIMENSION F(1)
C**
```

NJ=1

```
DO 20 J=1,M
      NJ=NJ+NP1
      DO 10 I=0,N
      NI=I+NJ
      F(NI-NP1)=WS(NI)*PN(NI)-WN(NI)*PS(NI)-TWSS(NI)-TWNN(NI)
     \& -2.D0*(PXX(NI)*TYY(NI)-2.D0*PXY(NI)*TXY(NI)
     & +PYY(NI)*TXX(NI))/JA(NI)
10
      CONTINUE
20
      CONTINUE
      RETURN
      END
C**
      SUBROUTINE FDJAC(FP,FM)
C**
C**
      FINITE DIFFERENCE JACOBIAN:
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      COMMON/PVAR/PO.P(2600), PS(2600), PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/MAT/DJ(300000),ICI(300000),IRP(3000),MAXA
      COMMON/TEST1/INDEX1
      COMMON/NFRED/NC
      DIMENSION FP(1),FM(1)
C**
      CENTERED DIFFERENCES AT INTERIOR POINTS
      FDJAC FILLS THE MATRIX COLUMN WISE
C
      THE FOLLOWING PARAMETERS ARE USED BY TRANPR AND MATRIX
      MAXA IS THE TOTAL NUMBER OF NON-ZERO ENTRIES
C
      L IS THE POSITION NUMBER; L(MAX)=MAXA
      IRP POINTS TO THE BEGINNING OF EACH NEW COLUMN
C
C
      ICI IS THE POSITION VECTOR
C
      DJ IS THE MATRIX ELEMENT
      ON EXIT FROM TRANPR, THE ELEMENTS ARE ROW ORIENTED
      MAXA=0
      L=0
      IRP(1)=1
      DO 300 J=1,M
      NJO=1+NP1*J
      DO 200 I=0,N
      NIO=I+NJO
      NC=NIO-NP1
      POLD=P(NIO)
      P(NIO)=POLD+DEL
      CALL STARDER(J,FP)
      P(NIO)=POLD-DEL
      CALL STARDER(J,FM)
      P(NIO)=POLD
      DO 130 I1=1,NE
      Q=(FP(I1)-FM(I1))/DEL2
      IF (Q.NE.O.DO) THEN
      L=L+1
```

MAXA=MAXA+1
DJ(L)=Q
ICI(L)=I1
END IF
130 CONTINUE
WRITE(58,*) MAXA
IRP(NC+1)=L+1
200 CONTINUE
WRITE(52,*)MAXA
CLOSE(58)
RETURN
END
C**

*

```
C**
      SUBROUTINE STARDER(J,F)
C**
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/NFRED/NC
      COMMON/BUM/NDUK
      DIMENSION F(1)
C**
      IF(NC.GE.NP1*M-N)NDUK=10
      CALL PPRIME(F)
      CALL XYDER
      CALL VORT
      CALL WPRIME(F)
      CALL MIX(F)
      CALL EDDY(F)
      CALL RES(F)
      NDUK=0
      RETURN
      END
C**
C**
      SUBROUTINE PRESSURE(F)
C**
C**
      OUTPUT: NORMAL AND TANGENTIAL STRESSES, DRAG COEFFICIENTS, ETC.
      IMPLICIT REAL*8(A-H,O-Z)
      IMPLICIT INTEGER*4(I-N)
      REAL*8 JA, JN1, JS1
      COMMON/PVAR/PO,P(2600),PS(2600),PN(2600)
     & ,PSS(2600),PNN(2600),PNNN(2600),UZ(2600),US(32)
      COMMON/XYD/PXX(2600), PYY(2600), PXY(2600)
      COMMON/WVAR/W(2600), WS(2600), WN(2600)
      COMMON/CON/N,M,NP1,NP2,N2,N3,MP1,MP2,RE,REI,RK,A,C,PI,DX,RKL
     & ,RK1,LDA,LDJ,NE,DEL,DEL2
      COMMON/SCALE/Z1(200),Z2(200),Z3(200),Z1H(200),Z2H(200),Z3H(200)
     & ,ZA(200),ZB(200),Z1S(200),ETA(200)
      COMMON/TRANS/SX(2600), SY(2600), SXX(2600), SXY(2600)
     & ,SXS(2600),SYS(2600),SXSY(2600)
```

```
COMMON/EDVIS/T(2600), TN(2600), TNN(2600), TXX(2600),
                    TYY(2600), TXY(2600), TS(2600), TSS(2600),
                    TW(2600), TWSS(2600), TWNN(2600), TT(2600),
     &
                    EX(2600), AU(32), AS(32)
      COMMON/NEW/JA(2600), JN1(2600), JS1(2600), B(15), YO, ZT
     & ,HS(32),HSS(32),ZERO(32)
     & ,DN(2600),DB(2600),SHR(32),SHI(32),ET(32),ETM(32)
      COMMON/FRED/RH
      COMMON/KUZ/ETAT
      DIMENSION X(200),Y(200),PR(200),SIG(200),STR(200),F(1),PSJ(20)
C**
      COMPUTE PHYSICAL COORDINATES OF WAVY SURFACE
      DO 110 I=0.NP1
      I1 = I + 1
      PSI=I*DX
      X(I1)=PSI
      Y(I1)=Y0
      DO 100 K=1.14
      X(I1)=X(I1)+B(K)*DSIN(K*PSI)/(K*DTANH(K*ETAT))
      Y(I1)=Y(I1)-B(K)*DCOS(K*PSI)/K
100
      X(I1)=X(I1)/(2.D0*PI)
110
      COMPUTE NORMAL DERIVATIVE OF TW AT WALL
C**
C**
      TN HERE IS THE NORMAL DERIVATIVE OF TW
C**
      FIRST COMPUTE BY FINITE (FORWARD) DIFFERENCES
      DO 200 I=1,NP1
      TN(I)=Z1H(1)*(-3.D0*TW(I)+4.D0*TW(I+NP1)-TW(I+NP1+NP1))
200
      WRITE(52, 1002)
      FORMAT(' TWN FROM FORWARD DIFFERENCES')
1002
      WRITE(52, 1001)(TN(I), I=1, NP1)
      FORMAT(8(2X,F12.6))
1001
      THEN COMPUTE BY USING THE MOMENTUM EQN AT THE WALL
C**
      CALL PF(NP1,TW,ZERO,1,TWSS,TWNN,1)
      DO 120 I=1,NP1
      TWSS(I)=HSS(I)*TWSS(I)
120
      TWNN(I)=HSS(I)*TWNN(I)
      CALL PF(NP1,TWSS,TWNN,1,TWSS,TWNN,1)
      DO 130 I=1,NP1
      TWNN(I)=WS(I)*PN(I)-TWSS(I)
      TM=(TWNN(I)+2.DO*Z1S(1)*TW(I)-(Z1S(1)+Z2H(1))*TW(I+NP1))
     \& /(Z1S(1)-Z2H(1))
      TN(I)=Z1H(1)*(TW(I+NP1)-TM)
130
      WRITE(52, 1003)
      FORMAT(' TWN AT Z=0 FROM EQUATION:')
1003
      WRITE(52, 1001)(TN(I), I=1, NP1)
C**
      WS HERE IS THE CROSS TERM PSIXY
      DO 140 I=1,N-1
140
      WS(I+1)=(PN(I+2)-PN(I))/(2.D0*DX)
      WS(1)=(PN(2)-PN(NP1))/(2.DO*DX)
      WS(NP1)=(PN(1)-PN(N))/(2.DO*DX)
      PRESSURE AND SHEAR DRAG COEFFICIENTS
C**
      CP=0.DO
      CS=0.D0
```

```
DO 310 I=0,N
      I1 = I + 1
      CP=CP+Y(I1)*(TN(I1)-US(I1))
310
      CS=CS-TW(I1)*SX(I1)/JA(I1)
      CP=CP/NP1
      CS=CS/NP1
      WRITE(52, 1005)CS+CP
      WRITE(52, 1006)CS, CS/(CS+CP)
      WRITE(52, 1007)CP,CP/(CS+CP)
1005 FORMAT(' THE TOTAL DRAG AT THE SURFACE IS: ',F10.7)
1006 FORMAT(' SHEAR DRAG COEFFICIENT ',F10.7,' NORMALIZED: ',F10.7)
1007 FORMAT(' PRESSURE DRAG COEFFICIENT: ',F10.7,'
                                                       NORMALIZED '
     & ,F10.7)
C**
      COMPUTE PRESSURE AT THE WAVY SURFACE
      XA=JA(1)*PN(1)*PN(1)
      DO 420 I=0,N
      I1=I+1
      PR(I1) = -(TN(1) + TN(I1))/2.D0
      DO 400 K=0.I
400
      PR(I1)=PR(I1)+TN(K+1)
      PR(I1)=(XA-JA(I1)*PN(I1)*PN(I1))/2.DO-DX*PR(I1)
      SIG(I1)=JA(I1)*(PNN(I1)+JN1(I1)*PN(I1))/RE
420
      STR(I1) = -PR(I1) - JA(I1)*(2.DO*WS(I1) + PN(I1)*JS1(I1))/RE
C**
      COMPUTE TERMS AT THE ENDPOINT: X=LAMDA
C**
      COMPUTE AMPLITUDE AND PHASE OF VARIATIONS OF PRESSURE AND SHEAR
      PR(NP2)=0.D0
      TAVE=0.DO
      S1=0.D0
      S2=0.D0
      S3=0.D0
      S4=0.D0
      SP1=0.D0
      SP2=0.D0
      DO 500 K=0.N
      XS=SX(K+1)/JA(K+1)
      S1=S1-SIG(K+1)*DSIN(2.DO*PI*X(K+1))*XS
      S2=S2+SIG(K+1)*DCOS(2.DO*PI*X(K+1))*XS
      S3=S3-SIG(K+1)*DSIN(4.DO*PI*X(K+1))*XS
      S4=S4+SIG(K+1)*DCOS(4.DO*PI*X(K+1))*XS
      SP1=SP1-PR(K+1)*DSIN(2.DO*PI*X(K+1))*XS
      SP2=SP2+PR(K+1)*DCOS(2.DO*PI*X(K+1))*XS
      TAVE=TAVE+SIG(K+1)
500
      PR(NP2)=PR(NP2)+TN(K+1)
      PR(NP2) = -DX*PR(NP2)
      TAVE=TAVE/NP1
      SAVE=2.DO*DSQRT(S1*S1+S2*S2)/NP1
      S2AVE=2.D0*DSQRT(S3*S3+S4*S4)/NP1
      PAVE=2.DO*DSQRT(SP1*SP1+SP2*SP2)/NP1
      TPH=DATAN2(S1,S2)
      TPR=DATAN2(SP1,SP2)
      TPH=180.DO*TPH/PI
      TPR=180.DO*TPR/PI
```

```
W(NP2)=W(1)
      SIG(NP2)=SIG(1)
      STR(NP2)=STR(1)+PR(1)-PR(NP2)
      WRITE(52,3000)
      DO 430 I=1,NP2
      WRITE(52,4000)X(I),W(I),PR(I),SIG(I),STR(I),SIG(I)/TAVE
430
      WRITE(52, 1008) TAVE, SAVE, S2AVE
      WRITE(52, 1009)TPH, TPR, PAVE
1008 FORMAT(' THE AVERAGE STRESS AT THE SURFACE IS: ',F12.7
     & .' ENERGY IN FUNDAMENTAL: ',F12.7,' SECOND HARMONIC:
                                                                   ',F12.7)
1009 FORMAT(' THE PHASE OF THE WALL STRESS IS: ',F12.7
& ,' WALL PRESSURE: ',F12.7,' WALL PRES AMP: ',F12.7)
3000 FORMAT(6X,'X COORDINATE',10X,'VORTICITY',11X,'PRESSURE',
     & 7X, 'TANGENTIAL STRESS', 6X, 'NORMAL STRESS', 9X, 'T/<T>')
4000 \quad FORMAT(6(4X,E16.8))
C**
C**
      ALL OF THE FOLLOWING LINES HAVE BEEN ADDED TO THE
C**
C**
      ORIGINAL MCLEAN PROGRAM
C**
      WRITE(52,6002)YO,ZT
6002
      FORMAT(//' YO=',F10.5,' ZT=',F10.5//)
      DO 50 I=1,15
      WRITE(52,6003)B(I)
6003
      FORMAT(F20.10)
  50 CONTINUE
      APLUS=RH*PI*RE
      NN=O
      DO 80 I=1.NP1
      SUM=0.DO
      SUM1=0.D0
      SUM2=0.D0
      PSJ(I)=((I-1)/FLOAT(NP1))*2.DO*PI
      DO 70 J=0,NP1*MP2-NP1,NP1
      NN=NN+1
      DO 90 K=1,14
      A1=DSINH(K*(ETAT-ETA(NN)))
      A2=DSINH(K*ETAT)
      SUM=SUM+(B(K)/K)*DCOS(K*PSJ(I))*A1/A2
  90 CONTINUE
      DO 95 KK=1,14
      A3=DCOSH(KK*(ETAT-ETA(NN)))
      A4=DSINH(KK*ETAT)
      SUM1=SUM1+(B(KK)/KK)*DSIN(KK*PSJ(I))*A3/A4
      SUM2=SUM2+(B(KK)/KK)*DCOS(KK*PSJ(I))*A3/A4
      CONTINUE
      XX=(SUM1+PSJ(I))/(2.DO*PI)
      DNDY=1.DO/(1.DO+SUM2)
      YPCART=RE*(ETA(NN)+YO-SUM)
      FACTOR=APLUS*DCOS(2.DO*PI*XX)
      YPSURF=YPCART-FACTOR
C**
      CALCULATE THE VELOCITY IN CARTESIAN COORDINATES
```

```
PY=DNDY*PN(I+J)+SY(I+J)*PS(I+J)
      WRITE(52,7000)PSJ(I),XX,ETA(NN),YPSURF,PY,DNDY,PN(I+J),
                    SY(I+J), PS(I+J)
7000 FORMAT(9F12.5)
      SUM=0.DO
      SUM1=0.DO
      SUM2=0.D0
  70 CONTINUE
      NN=0
      CONTINUE
  80
      CALCULATE THE SURFACE STRESSES IN PLUS UNITS
C**
C
      (MAGNITUDE, REAL PART, IMAGINARY PART)
      PMAG=PAVE/APLUS
      PRE=-PMAG/DSQRT((DTAN(TPR*PI/180.D0))**2+1.D0)
      PIM=PRE*DTAN(TPR*PI/180.DO)
      TMAG=SAVE/APLUS
      TR=TMAG/DSQRT((DTAN(TPH*PI/180.DO))**2+1.DO)
      TI=TR*DTAN(TPH*PI/180.DO)
      WRITE(52,7001)APLUS, PMAG, PRE, PIM, TMAG, TR, TI
 7001 FORMAT(///7F15.8)
      CLOSE(52)
      RETURN
      END
```

APPENDIX B

TABULATED FLAT CHANNEL

INTENSITY MEASUREMENTS

4.25496 4.25496 4.25496 4.25496 6.38245 6.38245 6.38245 8.08445 8.08445 10.63741	1.49553 1.48892 1.56770 1.41903 2.10770 2.14275 2.12518 2.30673 2.38107 2.32637 2.56469 2.48156	170.19876 170.19876 212.74840 212.74840 255.29814 255.29814 297.84778 297.84778	1.84975 1.89131 1.78409 1.79723 1.76228 1.77324 1.56325 1.59169
10.63741 12.33942 12.33942 12.33942 14.89237 14.89237 14.89237 17.01986 17.01986 17.01986 21.70030 21.70030	2.50131 2.63251 2.63251 2.65867 2.68927 2.63024 2.75493 2.63685 2.61059 2.66746 2.50999 2.57999	340.39752 340.39752 382.94717 382.94717 425.49689 425.49689 468.04654 510.59628 510.59628 553.14594 553.14594 595.69562	1.55674 1.54144 1.42337 1.47806 1.37529 1.34686 1.35554 1.31843 1.22445 1.20914 1.18940 1.16758 1.16314
25.95526 25.95526 25.95526	2.54287 2.52757 2.55817	595.69562 638.24530 680.79492 723.34454	1.16314 1.10855 1.10855 1.12819
29.35927 29.35927 34.03971 34.03971 38.29468 42.54964 42.54964 51.91062 51.91062 68.07952 68.07952 85.09938 85.09938 127.64912	2.37228 2.42697 2.37662 2.37445 2.24987 2.35046 2.21709 2.26517 2.19300 2.17770 2.21926 2.12962 2.00938 1.97650 1.91313 1.90217	(23.34424	1.12017

Table B.1 Flat Channel Intensity Data, $Re_b = 11,000$

APPENDIX C

TABULATED VELOCITY MEASUREMENTS OVER WAVES

$2a_{d}/\lambda = 0.03125$		$2a_{d}/\lambda = 0.05$	
Re _b	6370	38,840	
U _b (cm/s)	24.6	147.4	
u*(cm/s)	1.44	6.88	
$v(cm^2/s)$	0.009316	0.009155	
h _d (cm)	2.413	2.413	

$y_d = \frac{u^*}{v}$	u d * u	$y_{d} \frac{u^{\star}}{v}$	<u>ն</u> * u
1122222333333333333444444455566777777888991115533119977774 99337711115558888222666644422007775552266661554433319977774 112222233333333333444444555667777778889911113355993337711118 1112222233333333333344444555667777778889911113355993337711118	13583668644555674288768190657088020810880701643932777 331144021555222517999940734206320914322108977743888879326 22333334444444555555555666778888889900111112222334444444455	38.6604455555556666777797777777777777777777777	77780790927407446304218792460111829466 24592456020783347419141558856466 555560207833471777777777777777777777777777777777

Table C.1 Time-Averaged Velocity Data, $x_d/\lambda = 0.1$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_{d} \frac{u^{*}}{v}$	"d "* "u	$y_{d} \frac{u^{*}}{v}$	u d w
11222223333333333344444555556667777788899111333557777779993377711999337771111111111	3792168338598656365386538644775283819556688677770242 461792168334859865638653866477528389556688677786487770242 461792168334859865638834444455556667688899001788644677786487770242 461792168338565638834444455556667688899001111122222333333333444445555666768889900111112222233333333444445555666768889900111112222233333333444455556667688899000111112222233333333444445555666768889900011111222223333333344444555566676888990001111122222333333334444455556667688899000111112222233333333444445555666676888990001111122222333333334444455555666768889900011111222223333333344444555556667688899000000000000000000000000000000	39.577 4477 4477 49.4477 49.11665 559.111665 559.111665 559.111665 559.111665 559.111665 559.111665 559.111665 559.111665 559.111665 559.111665 559.116665 559.116666 559	84304225588284066812667170005189687651408516677777888968514051111111111111111111111111111111111

Table C.2 Time-Averaged Velocity Data, $x_d/\lambda = 0.2$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

*1 > 999990000000000000000000000000000000	u d * 0.354 0.472 0.425 0.449 0.472	y _d	9. 628 10. 525 10. 525 10. 547 11. 798
	42592220809408311906296035660810837476262228993741935134444499910111111111111111222222222333334444445556667777777889	01111446699994411111177771111444777770033399966228888844 999999999999999999999999999999	855578356693972697184726402452289982370251403089955 6555575663919975866090179864011165912287447890001111 112232333444444545555556677777778888999999000000 11111111111111111111111
	8.495 9.721		

Table C.3 Time-Averaged Velocity Data, $x_d/\lambda = 0.3$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_{d} \frac{u^{*}}{v}$	u d * u *	$y_d \frac{u^*}{v}$	$\frac{u_d}{\star}$
112222233333333444444455566677777889991113335577999933377119990011223333344555666888811133557700661111111111111222233333	28148300601117662738401800260338624843191750533279786 455678992233554765502945488917281283585199471222265369438 000000011111111111112212222233333445556666678888890012223	48.66633666616699222555888.558.6661669922255588822255588442882225558844288222555644177338844288222555555555564477555555666574533355511.000	98867 1046495576707298404111000977713833832 4444445516677777717788881899900000

Table C.4 Time-Averaged Velocity Data, $x_d/\lambda = 0.4$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	u d * u *	$y_d \frac{u^*}{v}$	u <u>d</u> *
11122222233333333333333333333333333333	00000001111111111111122222222233333333445445566667777899998110000000000000000000000000000	32.0008 40.0014 40.0014 50.000347 1000.00347 1100.0000.00777 1200.0000.00777 1200.0000.11139 8000.0000.11139 110000.11139 110000.11139 11000.11139 110000.11139 110000.11139 110000.11139	11.022880465998884666894504077759289664224133344445551166667777588872234777917318889799

Table C.5 Time-Averaged Velocity Data, $x_d/\lambda = 0.5$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	$\frac{^{\mathrm{u}}\mathrm{d}}{^{\star}}$	$y_d \frac{u^*}{v}$	$\frac{^{\mathrm{u}}d}{^{\star}}$
2222773388844400111112222333344445556677777889999111335577999377711999999999999999999	161037191293316629379249981630933049985197082430694364770046478800996770328820558852580578883488477431693427	79.121 79.121 98.9000 98.9000 98.66809 98.66859 118.42337 138.42337 1558.7.7356 99.12376 19777 2276 19776 19773 2316 4473 2316	1590304697604378914005184 0310903046976043789140051556501667948914005184 155650167777771889914999999999999999999999999999

Table C.6 Time-Averaged Velocity Data, $x_d/\lambda = 0.6$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008^d$

$y_d \frac{u^*}{v}$	ud * u	$y_{d} \frac{u^{\star}}{v}$	$\frac{^{\mathrm{u}}\mathrm{d}}{^{\star}}$
112222233333333333333334444444455556667777788999001113355554443332 1122222333333333333333444444455566677777889990011133555999333771	1450173095550059884670610182043969940130112786345333334444444555555566666666667777778788888899999900001111111111111111	31.1.1.55557777711.1.1.1.1.1.1.1.1.1.1.1.	1017350966183764495791246183761247438509644350194798579913133444455556666445534369471555666644553436947777888899947999887998

Table C.7 Time-Averaged Velocity Data, $x_d/\lambda = 0.7$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u = 0.008$

$y_d \frac{u^*}{v}$	$\frac{u}{d}$	$y_d \frac{u^*}{v}$	$\frac{u}{d}$
9966633399966339999669999933336669992226699995559922888885 99333377770044882222664444111199997755552200066655544333332 1122222233333333333333333333333	999601120672751291388826872614421757183388718405555562940 99999906451278448555656667777778788888999999900000111111111111111	207711777006622444466688888000022226666999933777118111222223333334448888777777996555111355544443333110099777777996511155544444333311100997777779964777	8611648822224493631513117513120488298755247789918 6688423885448431356716086386402545195530185385 222233333344445555671777777777777887888999999900 211111111111111111111111111111

Table C.8 Time-Averaged Velocity Data, $x_d/\lambda = 0.8$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	ud * u	$y_d = \frac{u^*}{v}$	ud *
556666778800111122223333333557799113355882277222333344444555666777778889901113355544423333444445556666477788899011133555544443332	45499061210718774278410659073827962114923421350722790 1267773411762328899245243300178459823472279159246478999227 120279333344555556666667777777888999990000111111111111111111111	5556666333999992222555888222255511117777339966 2221118886555512222775511177777339988885555555555566622227777777688844455555557777777777777777777	194391040800573723209488994905581477 42988570574468857006447683447 429855115555446889755608456771400222 4444445555555544668845677140006447800222 44444555555555446985677140006447800222

Table C.9 Time-Averaged Velocity Data, $x/\lambda = 0.9$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	ud *	$y_d \frac{u^*}{v}$	<u>u</u> d *
555522288885555222888855522225558881111551114488844 9993333777700000444488882266644111888862663333008885550033666633 9993333777700000444488882266644441119999777555222000665544433 9993333377770000044448888226664444111988822222222222222222222222222222	555522663-19-173874883505245-1991-188801-14220727280278-1-10095 5555011877242368864347846710225888801-14220727280278-1-10095 5222333333333444444444455555566677778888999999900010111212233333	00077777333333666222228888000222333336667777711115555999333366699999922255552228888441177777777777777777777777777777	1611118823801985552911134008844558174786611172972338388 87333484044664084796181866533366611518941623336663122562222 12664477879310365608866653336661151894162333666312211 144444444444155555660886666244888833225566632245598191211 1111111111111111111111111111111

Table C.10 Time-Averaged Velocity Data, $x_d/\lambda = 1.0$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	√u' _d ² /u*	$y_{d} \frac{u^{*}}{v}$	$\sqrt{\overline{u_d'}^2}/u^*$
11222223333333333333333444444445555666667777888991111335599337771111111222222233333	46431153999932749727896778622799990596758473207557744462 32545577797866453852616077786422799990596758470548766751322 3111111111111111111112222222222222	88800022222223344445555566667777880002233558888888877777777777777777777777777	2596360346141142997537997932267154375 22222312220109000099089888987744664747 22222222222222221122111111111111111

Table C.11 Intensity Data, $x_d/\lambda = 0.1$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_{d} \frac{u^{*}}{v}$	$\sqrt{\overline{u_d^{\prime}}^2}/u^*$	$y_d \frac{u^*}{v}$	$\sqrt{\overline{u_d'^2}}/u^*$
88449955550066227788889911223300888663322222999955117799 993377111155993377755555331119977888888888887777733994455 112222233333333333444445555566777778899111133557777799933771199	7941985286085888276306251067066181026398598933034079072688206284953505460477994276962093348049097264279576350222222222222222222222222222222222222	39.598 44488 49.4488 59.333877799.1177799.1897666455554 118.66766613554 118.445661358.2277998.8877.33554 118.4388.4239442223776.3358.1388.1388.1388.1388.1388.1388.1388	2.322.22.2.1.1.0.0.99.9.9.9.9.9.9.9.9.9.9.9.9.9.9.

Table C.12 Intensity Data, $x_d/\lambda = 0.2$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	$\sqrt{\overline{u_d^{\prime 2}}}/u^*$	$y_d \frac{u^*}{v}$	$\sqrt{\overline{u_d^{\prime 2}}}/u^*$
11111112222222222222222222222222222222	694517989351907580331156218205489738429772503566506548 777771143404130048602668819501094962067547255496842081390 11111111111111111111111111111111111	23333333333333333333333333333333333333	49494707833800906075776401890634796727753553762360 5688379594226071549979519168999174681993946732556163 0901090775654332212121210000909999887664444333333

Table C.13 Intensity Data, $x_d/\lambda = 0.3$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	$\sqrt{\overline{u_d^{\prime 2}}}/u^*$	$y_d \frac{u^*}{v}$	$\sqrt{\overline{u_d^{\prime}}^2}/u^*$
5556677880011222333355577799113377227777722288883334444556	809331943551456862946493262060937251889056678133637217	188839999922555888911777333996622	8798566477771047902777750664893113333
993377115559933366644422220088667773388884449999555566778859	9001233455557666770191003334667701021121313242471623388	18885599992216558884448558877733188444999555566777777666665555555566777779911733555555544499966222	820125544888776667276673333333
1122223333333333444444555666677777889911333355577779993377119	91111111111111111221222222222222233333333	1888599999225558884449999333333333333333333333333333	2222222222111111111111111111111

Table C.14 Intensity Data, $x_d/\lambda = 0.4$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_{d} \frac{u^{*}}{v}$	$\sqrt{\overline{u_d'^2}}/u^*$	$y_{d} \frac{u^{*}}{v}$	$\sqrt{\overline{u_d^{'2}}}/u'$
11111111222222222222333333333444444455556677788889990003336668 0000444488222266660000000000000000000000	7315628699139163020286133936209345715856082359996141899299990001111111111111111111111111111	28.021 022663339922000033992210000000000000000000000	55694226249737795557388668206603953445 2017889441986419555738866820758342200000099999878777766444332223 333222222222221111111111111111

Table C.15 Intensity Data, $x_d/\lambda = 0.5$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_{d} \frac{u^*}{v}$	$\sqrt{\overline{u_d'^2}}/u^*$	$y_d \frac{u^*}{v}$	$\sqrt{\overline{u_d'^2}}/u^*$
8884499555000667777888991122233000886633229955117799888 999333771115555997777888999112223300088664422007733994455443 1112222233333333444445556677777889999111335577993377111999999	852286363180269475784012795645001001378427541001420926 554667789800001021224345656676787988000900001182274334467 1111111111122222222222222222222222222	59.117 779.117 799.117 98.8997 98.8997 118.6676 118.6676 118.4535 1198.2235 11977.355 11977.355 11977.355 11977.351 11977.351 11977.351 11977.351 11977.351 11977.351 11977.351 11977.351 11977.351 11977.351 11977.351 11977.351	4041814194754169556246809 212001168185469556246809 2222222222211111111111111111111111111

Table C.16 Intensity Data, $x_d/\lambda = 0.6$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	$\sqrt{\frac{1}{u_d^2}}/u^*$	$y_{d} \frac{u^{*}}{v}$	$\sqrt{\overline{u_d^{\prime 2}}}/u^*$
11222222333333333344444445555666777778889999001111111111111122222223333333333355577777788999900111222333344444455556667777788899990011111111111111111111111111	660672066999191188899227257360472833343731202197226660223 556688888000010111322343534495663598709313449661588760 5778657677667780	44455566339999222255588822551117773333399966 372221008885577618882255111777733333333333333333333333333333	00168332417951337400449322171115684693 74361684339981135133740044993221711156847693 2222222222222222221211111111111111111

Table C.17 Intensity Data, $x_d/\lambda = 0.7$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	$\sqrt{\overline{u_d^{'2}}}/u^*$	$y_d \frac{u^*}{v}$	$\sqrt{\overline{u_d'^2}}/u^*$
330000777330066333330003333666699933366699933399993366633333399 3332220000998866555554411188888855533000775555999933663333399 333222000099886655554411188888855533000775555999933663333399 333222000077733006693333399	802805599548282312356395844408002956441517711593991771 122224334555778889899101122333334444927502900791236 122224334555577888989910112233333444455344554564554455554	955511114400668888800022222244445555599993337771115555 106633399922222222222222233336669999999999	905567479976222289539711717171864086848611741993399110 905544545332210109999988788202337601946315214477 222222222222222211121111111111111

Table C.18 Intensity Data, $x_d/\lambda = 0.8$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_{d} \frac{u^{*}}{v}$	$\sqrt{\overline{u_d^{\prime 2}}}/u^*$	$y_d \frac{u^*}{v}$	$\sqrt{\overline{u'_d}^2}/u^*$
55566677788001111222233333557799113355882227722223334444445556667777788990011112222333344444455566777778899001111335559993333557799113355882227722223334444444555667777788990011111315559993333771	939436613889824373839268429484037963901137949451927669 24616596421289986631385905014999167584480261591519291392 333343556677888889910100123443445444444444333342333333	288556666333399999222222558888555666555111117777733399998888555555555555555555555555	522444355347540115888429610427980364333556814 349776181038981912120120932709908036433353308 34977612012012099909993270990803644772355308 2222222222222222112211121111111111111

Table C.19 Intensity Data, $x_d/\lambda = 0.9$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

$y_d \frac{u^*}{v}$	$\sqrt{\overline{u_d^{\prime 2}}}/u^*$	$y_{d} = \frac{u^*}{v}$	$\sqrt{\frac{1}{u_d^{1/2}}}/u^*$
33330000777733333000066663300003336669993339922555228 9999337777000044488882266664441118855533300077775599336663339 99993337777000044488882266664441118855533300077775599336663339 99993333777700000444888822666644411189555333000777755599336663339 9999333333333333333333333	53777442352744446413383630800075450700479935731953416098 27649707373169925119469925995114922554003922778631245331930 000111433454466877889259912222223434444555555555555454332 111111111111111111111111121122222222	88855551111111111111111111111111111111	1323252576339138129040971416833374840672467582633731557219821867148681153339235777165520337439228848386787123191222222222222222222222222222222222

Table C.20 Intensity Data, $x_d/\lambda = 1.0$, $2a_d/\lambda = 0.03125$, $\alpha_d v/u^* = 0.008$

y _d u*	ud * u	y _d u*	20. 991
66667788800011122233334444577222773333344444772227733333444444 00000000000000000000000000	184545408067596690033680135429944209875553423219888473 199900223334455577777788889999999999999999999999999	200.105 200.132 250.132 300.158 300.158 300.2158 300.2263 600.3166 600.3166 700.3669 700.3669 700.4474 900.474 900.474 900.55238 1400.794	94386665226762519456213200091 99438333833383776194566166666651 9923434771025256199231256656551 22222222222222222222222222222

Table C.21 Time-Averaged Velocity Data, $x_d/\lambda = 0.1$, $2a_d/\lambda = 0.050$, $\alpha_d v/u^* = 0.00165$

$y_d \frac{u^*}{v}$	u d * u *	$y_d \frac{u^*}{v}$	ud * u
885552299 665552299 665552299 133566155228330077 1775554444477 199113335577	7.60842 9.60842 12.190357 11.33.10225 13.10225 14.7718 14.7714 15.1656	587.073 587.073 684.918 684.918 782.764 782.764 782.764 978.455 978.455 1369.528 1565.528 1761.219	21.879 87722 21.88722 22.332 22.332 22.232 22.333 23.333 2
8855522996633007711114448899900772266555544449 93555116662688449991111222222333333333344555566779911133355	15.16566 165666 155.65566 155.65566 166.2978 17778 17778 1777 1777 1777 188.286 188.65		
97.845 117.415 117.415 136.984 136.984	18.175 18.274 18.374 18.4660 18.658 18.658 18.1600 18.199.199.199.199.199.199.199.199.199.1		·
156.553 1553 1555.691 195.691 195.691 244.6536 24933.5382 29931.322 29931.322 2993.3399 489.	19.508 19.6855 19.8955 19.998 20.19494 20.4945 20.6699 21.434		

Table C.22 Time-Averaged Velocity Data, $x_d/\lambda = 0.2$, $2a_d/\lambda = 0.050$, $\alpha_d v/u^* = 0.00165$

$y_d \frac{u^*}{v}$	$\frac{u}{d}$	$y_d \frac{u^*}{v}$	$\frac{u}{d}$
111122334455777799114477722277722277722277788800000000000000	121560296134768711799867824639741358419922515633637722 1913378891541997622320099810783478731569944269811893388 87888889990099001112233333355556667777777788888889990000	700.369 700.369 800.422 800.422 900.474 900.5527 1200.632 1400.738 1400.843 1600.848 1800.9948	289374219801550121 9389374219801550121 011052467901551963161 22222222222222222

Table C.23 Time-Averaged Velocity Data, $x_d/\lambda = 0.3$, $2a_d/\lambda = 0.050$, $\alpha_d v/u^* = 0.00165^d$

$y_d \frac{u^*}{v}$	<u>"d</u> *	$y_{d} \frac{u^{*}}{v}$	$\frac{\frac{u}{d}}{\frac{\star}{u}}$
111111115588111155888115556666777777888885553330077777 4444433333222211009988777666633008855533300777774440000 111111335577779911222446666006622773339999550066666228888 1111111111111111111111111111	161148618500559880655325291980529134529916482044228449 65441156909548911546893484391644264391648201572599224999 222233333334444455555556666777778888899900005911111111111111111111111111	114.374 1124.374 1124.374 1124.374 1123.941 1133.941 1133.941 1153.0766 1153.941 1153.941 1153.941 1153.941 1153.941 1153.941 1168.3387	383800556744183335777 40633800556744183335777 5077602113672999274411185553333666691739966498732777 114444444441555666777788899001000 114555667777188899001000 114555667777188899001000 11455566777788899001000 1145556677778889382788

Table C.24 Time-Averaged Velocity Data, $x_d/\lambda = 0.4$, $2a_d/\lambda = 0.050$, $\alpha_d v/u^* = 0.00165$

$y_d \frac{u^*}{v}$	- \frac{u}{d} *		$y_d \frac{u^*}{v}$	u d * u
7888899999990001122333555577999922550044882266119988886655555 0001009999999999999999999999999999	45555666666677777778888888889999900013972355745992220	207. 207. 207. 207. 2036. 227. 221. 332. 227. 222. 233. 233. 247. 25. 25. 26. 27. 27. 27. 27. 27. 27. 27. 27. 27. 27	9995577444499111144993388222772666 111444499111144993388222772666	1550011667 150011667 1666615114135555 1666677 168881999999999999999999999999999999999

Table C.25 Time-Averaged Velocity Data, $x_d/\lambda = 0.5$, $2a_d/\lambda = 0.050$, $\alpha_d v/u^* = 0.00165$

$y_d \frac{u^*}{v}$	" d "*	$y_d \frac{u^*}{v}$	$\frac{u_d}{\star}$
466677799999111111333555588811550066666667799114155885555005 57779900002222444666600044888333444955666666677991141557771110008866 5777990000222222222222222222222222222222	6768957098799937723287655158756227944577782731754700903 02390229010884225457892203267881660594333732726665110903 88889999889999999999999999999999999	264.2880 304.2880 304.23155 304.23155 304.233155 335500 3342.33155 335500 3380.335500 3380.3380.3380 3380.3380.3380 3380.3380.	3791457792143434365094442744841177665 72993133683882366509444274488411777665 167.166.177.177.188.199.199.100.111.177.188.199.199.100.111.17776881000

Table C.26 Time-Averaged Velocity Data, $x_d/\lambda = 0.6$, $2a_d/\lambda = 0.050$, $\alpha_d v/u^* = 0.00165$

$y_{d} \frac{u^{*}}{v}$	$\frac{u_{\underline{d}}}{*}$	$y_{d} \frac{u^{*}}{v}$	ud *
1113355777666554444411997733888822445555554422211133000 11133557777770044884422222224455555444233322119 111335577777700448884422222222244444333222119 111335577777700448884455555667779908855444433322119	55444786733010809988966554443332301682577247607963257920 222164786733010809988966554499332301682577247607963257920 2209437699910119544994994499999994443838994655550944399 0001101111111111222222222222222222222	279.6890 1990 1987 1987 1987 1987 1987 1987 1987 1987	053860684265901333322555199 78742160550444393383226666650 78888999900011112222233333

Table C.27 Time-Averaged Velocity Data, $x_d/\lambda = 0.7$, $2a_d/\lambda = 0.050$, $\alpha_d v/u^* = 0.00165$

$y_{d} \frac{u^{*}}{v}$	u/d/*	$y_{d} \frac{u^{*}}{v}$	$\frac{u_d}{\star}$
0000222233344667700333366999222255111118888333779999333555228 222213332221100998866442220088666600055557778857777414331 33355557788800226660004477711111111111111111111111111111	8467954202289177711334480848622603878915940068716399641 032561104988711690099933736761105583789159400687163996491 22223333333334444444444444444444444444	283.718 283.718 283.718 2911 378.2991 3778.28663 4772.4436 4777.45863 4772.4476.575 5566.572 1134.0113 11324.0113 11324.0113 1131.13 1131.13 1131.13 1131.13 1131.13 1131.13 1131.13	19311101488833539922555941648006 1189911997821490001112227711055048006 118991119911222222222222222222222222222

Table C.28 Time-Averaged Velocity Data, $x_d/\lambda = 0.8$, $2a_d/\lambda = 0.050$, $\alpha_d v/u^* = 0.00165$

$y_{d} \frac{u^{*}}{v}$	" <u>d</u> "*	$y_d = \frac{u^*}{v}$	ud *
20998866655533221188888855522288884499992255588111774444 888888777777777777766666666555555544333333311000999775555 1355779991113335577111111555559999999999	357632866423017754653631433221900777674443219687431838 285699234576981133322424634455686799921222345867002404 111556666667777777777777777777777777878888888	158.2990 158.22866288833355666778883223299355665877777765588332222233395556658883222233395556658883222333955566588877777765588777988955777776558877798895118852200.233395566921.13885220.21188520.211885200.211885200.211885200.211885200.211885200.211885200.211885200.211885200.211885200.211885200.211	878338187469056137955659806691 5655894245761137955659806691 999990000011154861033016759843 1119900000111111222223333333333333333333

Table C.29 Time-Averaged Velocity Data, $x_d/\lambda = 0.9$, $2a_d/\lambda = 0.050$, $\alpha_d \nu/u^* = 0.00165$

$y_{d} \frac{u^{*}}{v}$	$\frac{u}{d}$	$y_d \frac{u^*}{v}$	ud * u
222222999666441188555999337711111992222888889999999999999999911122222222	582292495504949834698644828681917252000876306161741747569222924955640472558972731625500087630616174174751113334455566767677777888888978199998778109221123269	157.000 157.7006 184.78889 1830.0559 2277.0411 2330.0559 2277.0411 369.1177 369.1177 369.1177 738.85523440 11092.9940 11092.9940 11092.9940 11092.3355 11092.14477.146662.3355 16662.16662.16662	85386952580041592228666969696619 4044766169577555737250094949004 657602343662165002256677777677 000011111122222333333333333333333333333

Table C.30 Time-Averaged Velocity Data, $x_d/\lambda = 1.0$ $2a_d/\lambda = 0.050$, $\alpha_d v/u^* = 0.00165$

APPENDIX D

COMPARISON OF LINEAR THEORY WITH VELOCITY MEASUREMENTS

Calculations of the flowfield over waves of infinitesimal amplitude were performed with the linear boundary layer code of Abrams [2]. Abrams solved the Orr-Sommerfield equation using the SUPORT code developed at Sandia Laboratories. (See references [34] and [40].) The linear analysis predicts wave-induced velocity perturbations that are normalized with the amplitude of the wave. The perturbations were multiplied by the wave amplitude in order to compare the infinitesimal wave results with the finite amplitude wave measurements. The calculations were made with three turbulence models: a quasilaminar model, Model C*, and Model D*.

The predicted amplitudes and phases of the wave-induced velocity responses for $2a_d/\lambda = 0.0125$ and $\alpha_d \nu/u^* = 0.008$ (equivalent to $Re_b = 6400$) are shown in Figures D.1 and D.2 respectively. Amplitude and phase results for the wave with $2a_d/\lambda = 0.05$ and $\alpha_d \nu/u^* = 0.00165$ (equivalent to $Re_b = 38,8000$) are shown in Figures D.3 and D.4.

Only semi-quantitative comparisons with the data are appropriate since the linear calculations are for a boundary layer rather than a channel flow and are strictly valid only for waves of infinitesimal amplitude. The purpose of the above calculations was to show the relative amplitude and phase differences between the three turbulence models at the flow conditions of the data.

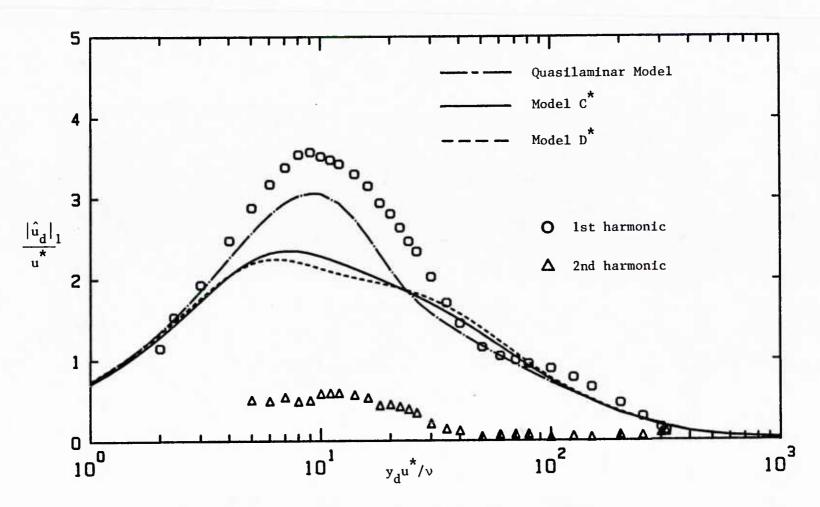


Figure D.1 Comparison of Linear Theory with Measurements, $|\hat{u}_d|_1$ (2a_d/ λ = 0.03125, $\alpha_d v/u^*$ = 0.008)

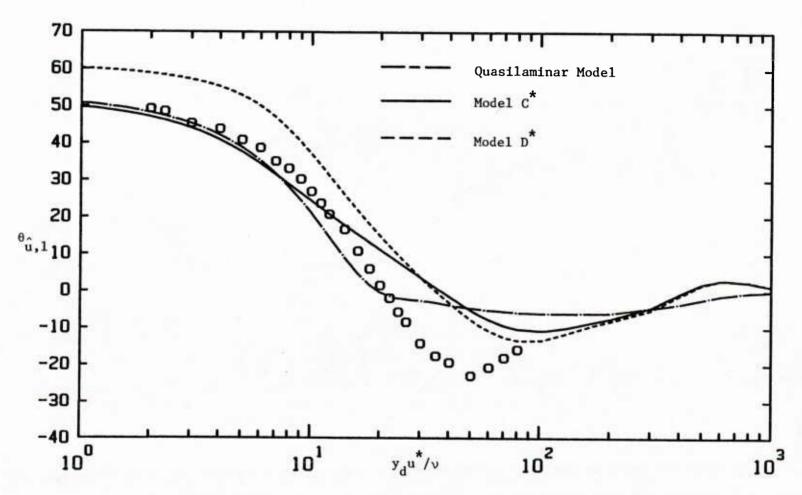


Figure D.2 Comparison of Linear Theory with Measurements, $\theta \hat{u}$, 1 $(2a_d/\lambda = 0.03125, \alpha_d \nu/u^* = 0.008)$

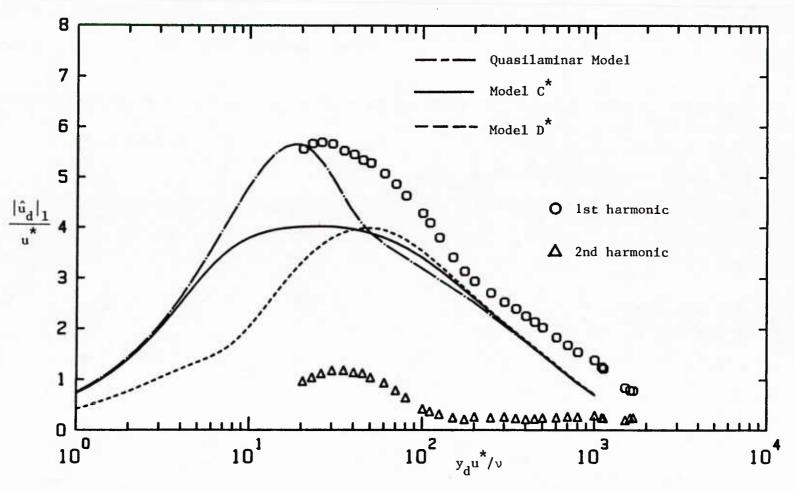


Figure D.3 Comparison of Linear Theory with Measurements, $|u_d|_1 (2a_d/\lambda = 0.05, \alpha_d v/u^* = 0.00165)$

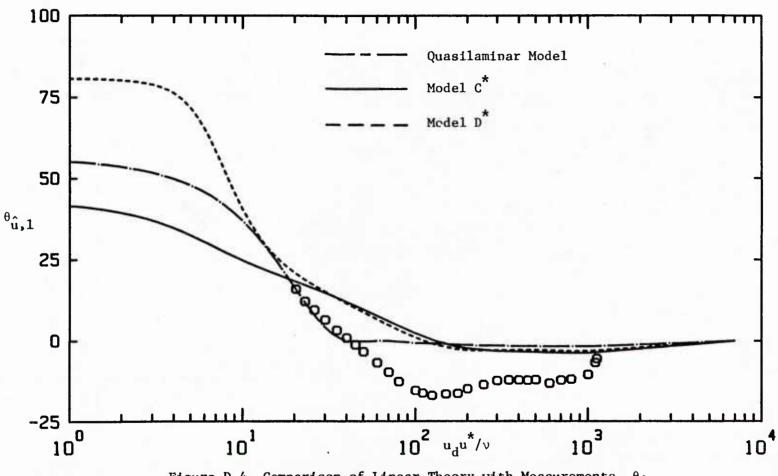


Figure D.4 Comparison of Linear Theory with Measurements, $\theta_{\hat{u}}$, 1 (2a_d/ λ = 0.05, $\alpha_{d} v/u^{*}$ = 0.00165)

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